## M.E. ELECTRONICS AND TELE-COMMUNICATION ENGINEERING

# FIRST YEAR SECOND SEMESETER-2019

#### Ex/PG/ETCE/T/127C/201

# STOCHASTIC CONTROL (CON)

Time: 3 Hours

Full Marks: 100

## Answer Q.1 and Any Four from rest

Select the correct answer:		
i. Probability Distribution function Fx(X) is defined as		4x5
A. $Fx(X) = P(X \le x)$ B. $Fx(X) = P(X \ge x)$	C. $Fx(X) = P(X = x)$	TAU
ii. An experiment involves tossing of a coin; here set of all		
A. Nyquist Space B. Random Space	C. Sample Space	
iii. Two random variables Xi & Yi are uncorrelated if		
A. $E(XiYj) = Exi(Xi)Eyj(Yj)$ B. $E(XiYj) = Exi(Yj)$	j)Eyj(Xi) C. E (XiYj) ≈ Exi Eyj (XiYj)	
iv. Bayes Rule is	,-,,, (,,,) (,)	
A. $f(Y \mid X) = f(X,Y)/f(X)$ B. $f(Y \mid X) = f(Y,X)/f(X)$	C. $f(Y \mid X) = f(X,Y)/f(Y)$	
v. A stochastic process { x(t) ; t ∈ I } is Gauss_Markov if it		
A. only Gaussian B. only Markov	C. Both Gaussian-Markov	
2 - What is Contact and income		
2. a. What is a Stochastic process (SP)		4+8+8
State the properties of SP     Define Random Variable		
c. Define Random Variable		
3. Define the following		
a. Probability Density Function		4x5
b. Joint Probability Density Function		
c. Joint Probability Distribution Function	(21) 522	
or joint rectainty Distribution Parietion	$(1/\pi)$ for $x^2 + y^2 \le$	
<li>d. Assume x and y are scalars whose joint density function</li>	n is cylindrical : f(x,y) = {	
	0 elsewhere	
	o eservicie	
4. a. What is Gauss-Markov Stochastic Process		8+12
<li>b. A scalar process {x(t); t≥ 0} defined by differential</li>	eg. $\{dx(t)/dt\} = -x(1-2t)$	
verify if the process is Gauss-Markov	11 (2 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1	
	Semi-Random Binary Transmission	4+4+12
<li>b. Autocorrelation of a random signal y(t) is R(t)= exp</li>	(-t); Derive an expression for its spectrum S (e	υ)
6. a. State the Prediction Problem		8+12
<ul> <li>Explain the Weiner-Hopf integral equation if its impu</li> </ul>	dse response is $h(\tau)$	
7. a. What is Kalman Gain-Matrix		
b. State and explain the Kalman Filter Algorithm		8+12
b. State and explain the Kalman Filter Algorithm		
8. Write Short Note (Any Two)		2x10
a. Estimation Error		2X10
b. Interpolation Problem		
c. Expectation value E[g(x)]		
d. Characteristic function φ <sub>s</sub> (s)		