B.E. MECHANICAL ENGINEERING FIRST YEAR FIRST SEMESTER SUPPLEMENTARY EXAM – 2024

Subject: ENGINEERING MECHANICS: STATICS

Time: Three Hours

Full Marks: 100

The value of the acceleration due to gravity (g) can be taken as 10 m/s^2 , if it is not specified. Any missing information may be suitably assumed with appropriate justification.

Group A (Answer any two questions from this group)

Q1a. The flanged steel cantilever beam with riveted bracket is subjected to the couple and two forces shown in Fig. Q1a, and their effect on the design of the attachment at 'A' must be determined. Replace the two forces and couple by an equivalent couple M and resultant force R at 'A'.

Q1b. The turnbuckle in Fig. Q1b is tightened until the tension in cable AB is 1.2 kN. Calculate the magnitude of the moment about point 'O' of the force acting on point 'A'. [10]

Q1c. If $F_1 = 450$ N and the magnitude of the moment of both forces about line AB is 30 N-m, determine the magnitude of F_2 as shown in Fig. Q1c. Use the values a = 200 mm, b = 400 mm, and c = 500 mm.

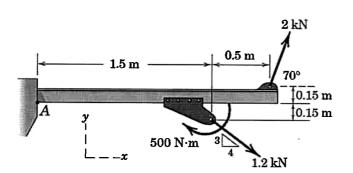
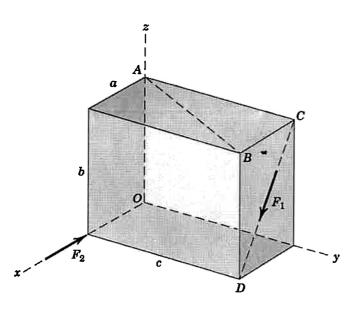


Fig. Q1a



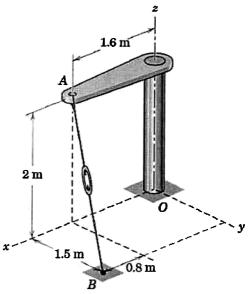
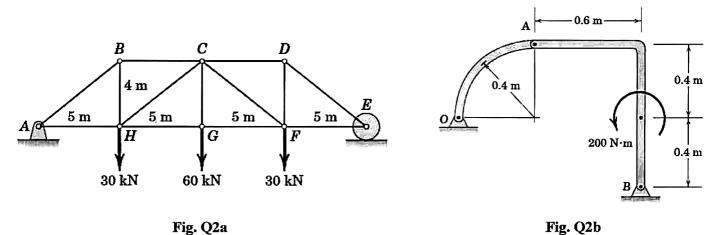


Fig. Q1b

Group B (Answer any four questions from this group)

Q2a. For the truss loaded as shown in Fig. Q2a, determine the forces in the members CH and GF. Draw the necessary free body diagram(s).

Q2b. Determine the magnitude of pin force at 'B' for the frame loaded as shown in Fig. Q2b. Draw the necessary free body diagram(s).



Q2c. The light right-angle boom (as shown in Fig. Q2c) which supports the 400 kg cylinder is supported by three cables and a ball-and-socket joint at 'O' attached to the vertical x-y surface. Determine the cable tensions. Draw the necessary free-body diagram(s).

Q2d. The light bracket ABC in Fig. Q2d is freely hinged at 'A' and is constrained by the fixed pin in the smooth slot at 'B'. Calculate the magnitude of the force supported by the pin at 'A' under the action of the 80 N·m applied couple. Draw the necessary free body diagram(s).

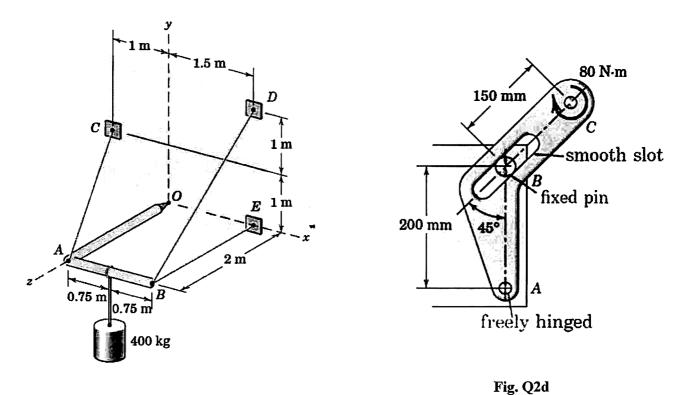


Fig. Q2c

Q2e. With necessary sketches and free body diagram(s), show that a flexible cable carrying uniformly distributed load of intensity w per unit horizontal distance in the vertical plane, forms a curve given by the equation $y = \frac{wx^2}{2T_0}$, where x and y are the coordinate of any point of the hanging cable and origin of the coordinate system is located at the lowest point of the cable. T_0 is the tension of the cable at its lowest point. The self-weight of the cable is negligible.

Group C (Answer any two questions from this group)

Q3a. The strut AB of negligible mass is hinged to the horizontal surface at 'A' and to the uniform 25 kg wheel at 'B' as shown in Fig. Q3a. Determine the minimum couple M applied to the wheel which will cause it to slip if the coefficient of static friction between the wheel and the surface is $\mu_s = 0.40$. Draw the necessary free body diagram(s). [10]

Q3b. The 3 m uniform beam is suspended by the flexible belt which passes over the large pulley as shown in Fig. Q3b. A locking pin 'A' prevents the rotation of the pulley. If the coefficient of friction between the belt and the pulley is 0.25, determine the minimum value of x for which the belt will not slip on the pulley. Draw the necessary free body diagram(s).

Q3c. With necessary sketches and free body diagram(s), show that in a square threaded screw jack, the expression of moment required to be applied about the axis of the screw, which is just enough to raise a load of W, will be $M = W r \tan(\alpha + \varphi)$, where r, α and φ are the mean radius of the screw, helix angle of the screw and the angle of static friction between the screw and nut surfaces, respectively.

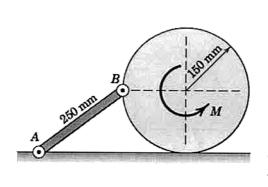


Fig. Q3a

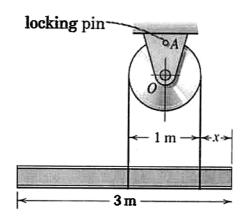


Fig. Q3b

Group D (Answer any two questions from this group)

Q4a. State and explain Pappus' Theorem with neat sketches.

[10]

Q4b. Determine the coordinates of the centroid of the shaded area as shown in the Fig. Q4b.

[10]

Q4c. Determine the moments of inertia of the Z section shown in Fig. Q4c about its centroidal x_0 and y_0 axes.

[10]

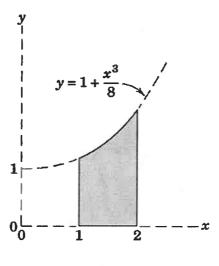


Fig. Q4b

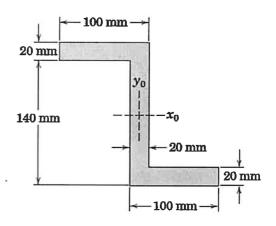


Fig. Q4c