B. E. ELECTRICAL ENGINEERING 2ND YEAR 2ND SEMESTER EXAMINATION, 2024

(Old Syllabus)

SUBJECT: - SIGNALS AND SYSTEMS

Full Marks 100 (50 marks for each part)

Time: Three hours

| Use a separate Answer-Script for each part | | | | |
|--|---|-------|--|--|
| No. of Questions | PART I | Marks | | |
| | Answer any Five | | | |
| , . | | | | |
| 1. | D ' of the Compley form of Fourier series for a | | | |
| | Derive an expression of the Complex form of Fourier series for a periodic signal. | | | |
| | Hence, define magnitude spectrum and phase spectrum. | 10 | | |
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| 2 | | | | |
| 2. | Determine the Fourier Transform of | £. £: | | |
| | | 5+5 | | |
| | (a) $x(t) = e^{-5 t } \cos 100\pi t$ | | | |
| | (b) $y(t) = [u(t+3) - u(t-3)]$ | | | |
| _ | | | | |
| 3. | (a) Find graphically the even and odd component of the signal | | | |
| | shown in Fig-A. | _ | | |
| | | 7 | | |
| | x(t) | | | |
| | ↑ | • | | |
| | 8 | | | |
| | 6 | | | |
| | | | | |
| | $\begin{array}{c ccccccccccccccccccccccccccccccccccc$ | | | |
| | | | | |
| | Fig-A. | | | |
| | rig-A. | | | |
| | (b) Express $x(t)$, shown in Fig-A, in terms of singularity functions. | 3 | | |
| | | | | |
| 4. | | | | |
| | 1.14 | | | |
| | x(t) $h(t)$ | | | |
| | 3 | | | |
| | | t | | |
| • | $\begin{array}{c ccccccccccccccccccccccccccccccccccc$ | | | |
| 1 | | | | |
| | | | | |
| | Fig-B. | | | |
| | | | | |

| | Perform graphically the convolution between the signals $x(t)$ and $h(t)$, shown in Fig-B, in time domain. Sketch the resulting signal. | 10 |
|----|--|----|
| 5. | (a) Find the energy associated with the signal $x(t)$, shown in Fig-A. | 5 |
| | (b) State Parseval's theorem applied to periodic signal. Prove the same. | 5 |
| 6. | Write short notes on any one: | 10 |
| | (a) Properties of Impulse function.(b) Frequency response of a second order LTI system. | |
| 7. | (a) Two signals $x(t)$ and $f(t)$ are related as $f(t) = \frac{1}{3}[x(5t) - 4]$. Express energy of $x(t)$ in terms of the energy of $f(t)$. | 6 |
| | (b) Define duty cycle and crest factor of an ac coupled rectangular pulse. | 4 |

Ref. No.: Ex/EE/PC/B/T/224(O)/2024

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Time: Three Hours Full Marks: 100 **Subject: SIGNALS & SYSTEMS**

(Old Syllabus)

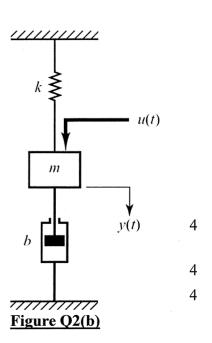
| Ques No | | Question 1 is compulsory Answer Any Two questions from the rest (2×20) | Marks |
|------------|-----|---|-------|
| Q1 | Ans | wer any Two of the following: | |
| | (a) | Determine if the following system $\dot{y}(t) + 4y(t) = 2x(t)$ is (i) time-invariant, (ii) linear, (iii) causal, and/or (iv) memoryless? | 5 |
| | (b) | Determine whether the system characterized by the differential equation $\ddot{y}(t) - \dot{y}(t) + 2y(t) = x(t)$ is stable or not? Assume zero initial conditions. | 5 |
| | (c) | The unit impulse response of an LTI system is the unit step function $u(t)$. Find the response of the system to an excitation $e^{-at}u(t)$. | 5 |
| | (d) | Determine the analog diagram to implement the following differential equation $\dot{x}(t) + 0.1x(t) = 1, \ x(0) = 0.$ | 5 |

- (a) For a standard 2nd order system derive the expression for unit step response for Q2 4+4 (i) un-damped, (ii) critically damped conditions. Show the respective pole locations in the s-plane.
 - (b) Consider a mechanical system shown in Figure Q2(b). Assume that the system is linear.

The external force u(t) is the input to the system, and the displacement y(t) of the mass is the output.

The displacement y(t) is measured from the equilibrium position in the absence of the external force.

- (a) Derive the transfer function of the system.
- (b) Obtain the analogous electrical network based on force-voltage analogy
- (c) Develop a State-Space Model of the System.



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4+8

4

- Q3 (a) (i) Draw analog simulation diagram for the following system, and,
 - (ii) obtain magnitude-scaled analog simulation of the system to utilize the full amplifier range of 0 to 10 volts without any overloading.

$$\ddot{x} + 2\dot{x} + 25x = 500$$
, $x(0) = 20, \dot{x}(0) = 0$, with, $|x|_{max} = 20$, $|\dot{x}|_{max} = 100$.

- (b) Stating the simplifying assumptions obtain the block diagram of an armature controlled d. c. motor driving a load with viscous friction.
- Q4 (a) State and prove the Final Value Theorem for Laplace Transformation. 4
 - (b) Solve the following differential equations using the Laplace Transform method $\ddot{y} + 9\dot{y} + 20y = x \qquad \qquad 8$ with, x(t) = 2u(t) (u(t): unit step), y(0) = 1, $\dot{y}(0) = -2$
 - (c) Given the following system:

$$G(s) = \frac{10}{s^2 + 10s + 100}$$

- (i) Plot the pole locations and find the corresponding values of ζ and ω_n .
- (ii) Draw the nature of the unit step response and indicate the following indices:

 Rise Time, Peak-Time, Peak Overshoot and Steady-State Value.
- Q5 (a) Define state and output equations for an LTI system. 4

 Draw the block diagram representation of the state and the output equations. 4
 - (b) Find the transfer function, Y(s)/X(s), for the circuit shown in Figure Q5(b). Calculate the values of ξ and ω_n for $C_1=C_2=100\mu F$, $R_1=R_2=2000\Omega$.

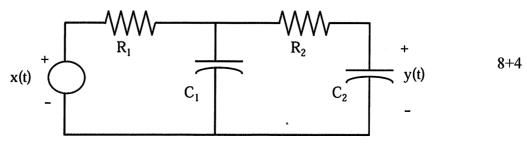


Figure Q5(b)