B.E. COMPUTER SCIENCE AND ENGINEERING FOURTH YEAR FIRST SEMESTER - 2024

SUBJECT PATTERN RECOGNITION

Time: 3 hours

Full marks: 100

Group A

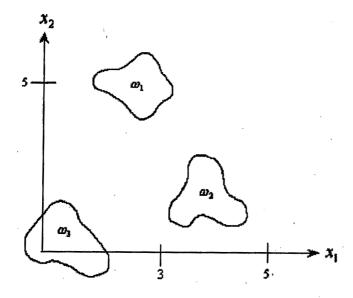
Answer Question No. 1 (COMPULSORY) and any one form the rest of the two questions of this Group

1. Answer true or false stating reasons

2x10 = 20

- (a) A Naïve Bayes Classifier can only work on categorical data.
- (b) The success of a pattern classification scheme using decision function depends on finding the geometrical properties of the pattern classes under consideration.
- (c) In a typical PR problem, the dimensionality of measurement space is always greater than that of feature space.
- (d) A NB classifier is much faster than KNN to provide prediction.
- (e) In Bayesian Network, the nodes represent events and the edges represent conditional dependencies.
- (f) For a supervised pattern classification problem having *M* classes, where the patterns are pair-wise separable, the classifier needs to compute *M* number of decision surfaces to perform classification.
- (g) A Bayesian network is not suitable to represent the probabilistic relationships between diseases and their symptoms.
- (h) A Naïve Bayes Classifier always assumes that each feature x_i is conditionally dependent of every other feature x_i for $i \neq i$.
- (i) A pattern is a shape of an object that we are going to recognize.
- (j) The method of pattern classification by decision functions can be expected to yield satisfactory results only when the patterns are linearly separable.
- 2. (a) Explain briefly the necessary steps involved in a typical Pattern Classifier with an example.
 - (b) Explain the difference between supervised and unsupervised PR with examples

3. (a) (a) For the following three pattern classes ω_1, ω_2 and ω_3 in \Re^2 compute the decision boundaries and decision rules that are needed to successfully classify all the patterns from the said three classes.



(b) Explain briefly a typical Naïve Bayes Classifier. How it can be useful in solving some problems of PR 6+4

Group B

Answer Question No. 4 (COMPULSORY) and any two form the rest of the three questions of this Group

4. Answer true or false stating reasons

2x10 = 20

- (a) K-means algorithm cannot cluster data sets well with large differences in densities.
- (b) Each node in a typical ANN can have any number of outgoing connections, where the signals in all of these may not be the same.
- (c) A Syntactic Pattern Classifier infers a grammar from a set of training patterns.
- (d) Partitional clustering methods help in exploring data at different levels of granularity.
- (e) The support vectors of a linear SVM can be any points in the training set.
- (f) Syntactic Pattern Recognition attempts to classify patterns based on a set of extracted features and an underlying statistical model for the generation of these patterns.

- (g) While using RBF kernel with SVM, choosing a small value of 'Gamma' may overfit the classifier.
- (h) Hopfield network is usually employed for data clustering.
- (i) A multi-layer-perceptron is a recursive network that is suitable for solving optimization problem.
- (j) The training phase is not required in a typical syntactic pattern classification system.
- 5. What is partitional clustering? State and explain one such method that is based on the principle of minimization of intra-class distances. Discuss the merits and demerits of the method. 2 + 12 + 6
- 6. (a) How are the features of a biological neurone being imitated in an artificial neurone?
 - (b) Describe how can a single layer perceptron classify two linearly separable classes? Can such an ANN learn an XOR function? Justify your answer.

10 + 4

7. (a) What is syntactic pattern recognition? Why is it important?

2 + 2

- (b) With necessary diagram explain briefly a typical Syntactic Pattern Recognition System.
- (c) Suppose you need to classify the following four alphabets.



Define the necessary set of primitive strings and an appropriate grammar to solve the problem using syntactic pattern recognition method.