

Bachelor of Chemical Engineering Examination 2019 – 3rd Year, 2nd Semester

PROCESS DYNAMICS AND CONTROL

Time: Three hours; Full Marks = 100

Answer any FOUR questions. All questions carry equal marks

- In a liquid mixing tank ($A = 7 \text{ sq. m.}$) liquid level at steady state $[h_s]$ is 7 m, inflow and outflow rates are $q_i = q_o = 100 \text{ m}^3 \text{ h}^{-1}$. Predict the final level for a step change of $-10 \text{ m}^3 \text{ h}^{-1}$ in inflow rate for two cases:
 - a linear head-flow relationship, and
 - a nonlinear relation $q = C_v h^{0.5}$.
- Derive, and compare the transfer function models of isothermal CSTR with liquid phase reaction for the cases of 1st order and 2nd order kinetics respectively.
- The liquid level in a two-tanks-in-series system is to be controlled using a simple proportional controller. Both tanks have unity gain with time constants 1 min. and $\frac{1}{2}$ min. respectively. The liquid level measuring device that provides feedback to the controller is also unity gain with time-constant $\frac{1}{3}$ min. Draw a block diagram of the control system. Using the Routh test, find the range of values of controller gain K_c , for which the control system is stable.
 - A temperature sensor with heat transfer area $= 1 \times 10^{-5} \text{ m}^2$, mass $= 1 \times 10^{-4} \text{ kg}$ and sp. heat capacity $= 504 \text{ J/kg K}$; is used to measure the temperature of a gas stream flowing through a conduit. After having remained unchanged at 200°C for a long time, the gas stream temperature suddenly jumps to 210°C due to some disturbance in the source of flow. 4.8 minutes after this instant, the sensor shows a reading of 209.8°C . Estimate the film coefficient of heat transfer ($\text{W/m}^2\text{K}$). State necessary assumptions.
- A stirred-tank blending process with constant liquid holdup of 2 m^3 is used to blend two streams whose densities are both approximately 900 kg/m^3 . The density does not change during mixing.
 - Assume that the system has been operating for a long period of time with steady flow rates of $w_{1,ss} = 500 \text{ kg/min}$ and $w_{2,ss} = 200 \text{ kg/min}$. The mass fraction of component A in the first feed stream is $x_1 = 0.4$ and the mass fraction of component A in the second feed stream is $x_2 = 0.75$. What is the value of x_{ss} , the steady-state composition of the effluent stream?
 - Derive a linear model which describes the dynamic response of $x(t)$ to variation in the feed stream flow rates $w_1(t)$ and $w_2(t)$, and thereby obtain the appropriate transfer functions.
- The outflow from a storage tank ($A = 4 \text{ m}^2$, maximum liq. height = 5 m) is forcibly constrained at $0.02 \text{ m}^3/\text{s}$. At a certain “steady state”, tank fluid level was 2 m. The inflow rate is suddenly decreased by 10%.
 - How is the tank fluid level affected? Does it reach a final ‘steady’ value?
 - Redo the above problem when there is no constraint on the tank outflow.
- Compare Ziegler-Nichols controller settings (based on the Bode stability criterion and Frequency Response) and Cohen-Coon settings (based on the Process Reaction Curve approximated by a FOPDT model $G_{PRC} = K e^{-\lambda s} / (1 + \tau s)$) for a P-only controller used in a control system where $G_p = 1 / [1 + 5s][1 + 2s]$; $G_m = 1 / [1 + 10s]$ and a very fast FCE.

[N.B. For a P-only controller, Z-N settings give $K_C = 0.5 K_{C,max}$ whereas C-C settings give $K_C = (1/K)(\tau/\lambda)(1 + [\lambda/3\tau])$.]

State all necessary assumptions.