

# ELEMENTS OF COMPUTATIONAL FLUID DYNAMICS

## Chapter-3

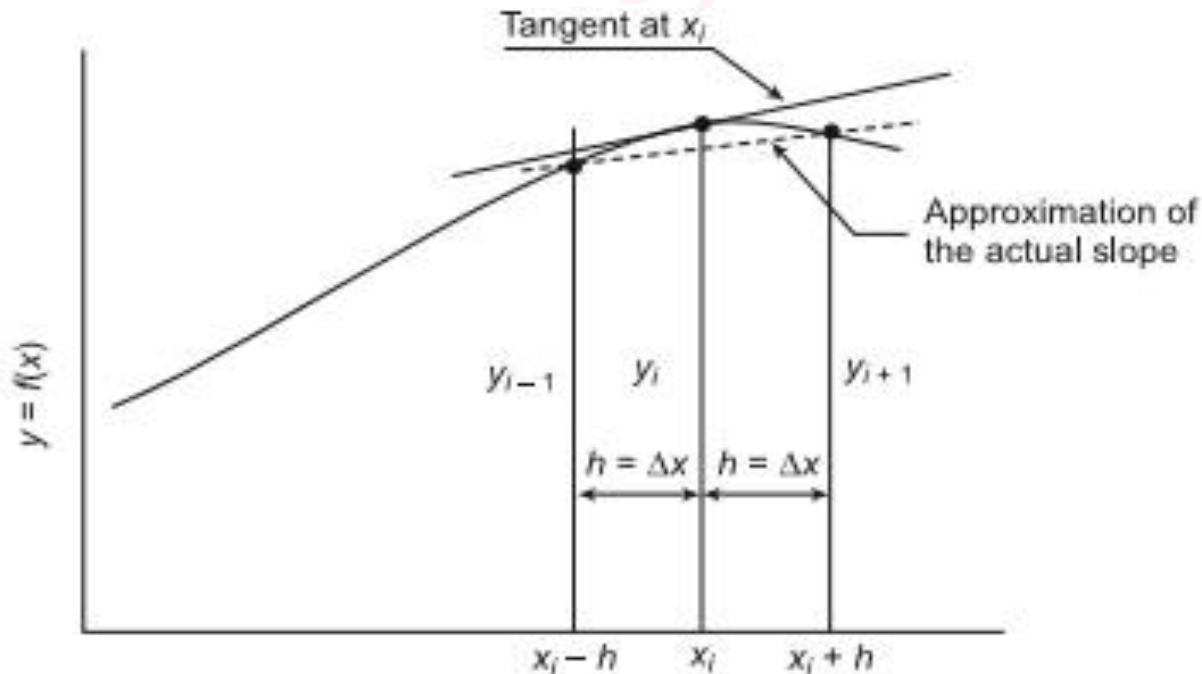
# Introduction to the Finite Difference Method (FDM)

The finite difference method enables one to integrate a differential equation numerically by evaluating the values of the function at a discrete (finite) number of points. The origin of this method is Taylor series expansion, which assumes that the function is smooth, that is, continuous and differentiable.

## Taylor series expansion

The Taylor series of a real or complex-valued function  $f(x)$  that is infinitely differentiable at a real or complex number  $a$  is the power series

$$f(x) = f(a) + (x-a)f'(a) + \frac{(x-a)^2}{2!}f''(a) + \frac{(x-a)^3}{3!}f'''(a) + \dots$$



# Central difference

The Taylor series expansion of a function  $f(x)$  at  $x_i+h$  expanded about  $x_i$  is

$$f(x_i+h) = f(x_i) + (x_i+h-x_i)f'(x_i) + \frac{(x_i+h-x_i)^2}{2!}f''(x_i) + \frac{(x_i+h-x_i)^3}{3!}f'''(x_i) + \dots$$

Let,  $y_i = f(x_i)$     $y_{i+1} = f(x_i+h)$     $y_{i-1} = f(x_i-h)$

$$y_{i+1} = y_i + h y'_i + \frac{h^2}{2!} y''_i + \frac{h^3}{3!} y'''_i + \dots \quad (1)$$

Then, the Taylor series expansion of a function  $f(x)$  at  $x_i-h$  expanded about  $x_i$  is

$$y_{i-1} = y_i - h y'_i + \frac{h^2}{2!} y''_i - \frac{h^3}{3!} y'''_i + \dots \quad (2)$$

Subtracting (1)-(2), we get,

$$y_{i+1} - y_{i-1} = 2h y'_i + \frac{2h^3}{3!} y'''_i + \dots$$

$$\therefore y'_i = \frac{y_{i+1} - y_{i-1}}{2h} - \frac{1}{6} (y'''_i h^2) + \text{higher order terms}$$

Therefore,

$$\therefore y'_i = \frac{y_{i+1} - y_{i-1}}{2h} + O(h^2)$$

Neglecting the  $O(h^2)$  terms, which is called the **truncation error (error due to truncated Taylor series)**, we obtain the central difference FDM expression

$$\therefore y'_i = \left( \frac{dy}{dx} \right)_{x=x_i} = \frac{y_{i+1} - y_{i-1}}{2h}$$

Now, adding Eqs. (1) and (2)

$$y_{i+1} + y_{i-1} = 2y_i + h^2 y''_i + \frac{h^4}{12} y''''_i + \dots$$

$$y''_i = \frac{y_{i+1} - 2y_i + y_{i-1}}{h^2} - \frac{1}{12} (y''''_i h^2) + \text{higher order terms}$$

$$\therefore y''_i = \frac{y_{i+1} - 2y_i + y_{i-1}}{h^2} + O(h^2)$$

Neglecting the  $O(h^2)$  terms

$$y''_i = \left( \frac{d^2 y}{dx^2} \right)_{x=x_i} = \frac{y_{i+1} - 2y_i + y_{i-1}}{h^2}$$

- It can also be expressed as

$$y_i'' = \frac{\frac{y_{i+1} - y_i}{h} - \frac{y_i - y_{i-1}}{h}}{h} \quad y_i'' = \frac{\frac{y_{i+1} - y_i}{h} - \frac{y_i - y_{i-1}}{h}}{h}$$

- where  $y'_{i+1/2}$  and  $y'_{i-1/2}$  represent the slope of the tangent to the curve at  $x_i + (h/2)$  and  $x_i - (h/2)$ , respectively.
- The afore-derived central difference expressions reveal that the first and second derivatives of the function involve values of function on both sides of the x-value at which the derivative of the function is to be evaluated.

# Forward difference

From Taylor series expansions, it is also easy to obtain expressions for the derivatives that are entirely in terms of values of function at  $x_i$  and points to the right of  $x_i$ . These are called forward difference expressions.

$$y_{i+1} = y_i + h y'_i + \frac{h^2}{2!} y''_i + \frac{h^3}{3!} y'''_i + \dots$$

$$\Rightarrow h y'_i = y_{i+1} - y_i - \frac{h^2}{2!} y''_i - \frac{h^3}{3!} y'''_i - \dots$$

$$\Rightarrow y'_i = \frac{y_{i+1} - y_i}{h} - \frac{h}{2!} y''_i - \frac{h^2}{3!} y'''_i - \dots$$

$$\therefore y'_i = \frac{y_{i+1} - y_i}{h} + O(h)$$

Neglecting the  $O(h)$  terms

$$\therefore y'_i = \left( \frac{dy}{dx} \right)_{x=x_i} = \frac{y_{i+1} - y_i}{h}$$

Similarly,

$$y_{i+2} = y_i + (2h) y_i' + \frac{(2h)^2}{2!} y_i'' + \frac{(2h)^3}{3!} y_i''' + \dots \quad (1)$$

Also,

$$y_{i+1} = y_i + (h) y_i' + \frac{(h)^2}{2!} y_i'' + \frac{(h)^3}{3!} y_i''' + \dots \quad (2)$$

Now, (1) - 2X(2) gives

$$\therefore y_i'' = \frac{y_{i+2} - 2y_{i+1} + y_i}{h^2} + O(h)$$

Neglecting the  $O(h)$  terms

$$y_i'' = \left( \frac{d^2 y}{dx^2} \right)_{x=x_i} = \frac{y_{i+2} - 2y_{i+1} + y_i}{h^2}$$

# Backward difference

With this approach, one can easily obtain derivative expressions that are entirely in terms of values of the function at  $x_i$  and points to the left of  $x_i$ . These are known as backward difference expressions, which are given below for  $y'_i$  and  $y''_i$ .

$$y_{i-1} = y_i - h y'_i + \frac{h^2}{2!} y''_i - \frac{h^3}{3!} y'''_i + \dots$$

$$\Rightarrow h y'_i = y_i - y_{i-1} + \frac{h^2}{2!} y''_i - \frac{h^3}{3!} y'''_i + \dots$$

$$\Rightarrow y'_i = \frac{y_i - y_{i-1}}{h} + \frac{h}{2!} y''_i - \frac{h^2}{3!} y'''_i + \dots$$

$$\therefore y'_i = \frac{y_i - y_{i-1}}{h} + O(h)$$

Neglecting the  $O(h)$  terms

$$\therefore y'_i = \left( \frac{dy}{dx} \right)_{x=x_i} = \frac{y_{i+1} - y_i}{h}$$

Similarly, one can obtain

$$y''_i = \left( \frac{d^2 y}{dx^2} \right)_{x=x_i} = \frac{y_i - 2y_{i-1} + y_{i-2}}{h^2} \quad (\text{Home work})$$



## Employing forward, backward, and central difference expressions

- I. Forward difference expressions are used when data to the left of a point at which a derivative is desired are not available.
- II. Backward difference expressions are used when data to the right of the desired point are not available.
- III. Central difference expressions are used when data on both sides of the desired point are available and are more accurate than either forward or backward difference expressions.