

M.E. ELECTRONICS AND TELE-COMMUNICATION ENGINEERING

FIRST YEAR SECOND SEMESETER-2018

STOCHASTIC CONTROL (CON)

Time : 3 Hours

Full Marks : 100

Answer Q.1 and Any Four from rest1. Indicate True(T)/ False(F) :

10x2

- Probability $P(x)$ of event- x is : $P(x) = [N/N(x)] \mid N \rightarrow 0$
- If X is a random vector and x is arbitrary vector, then Probability Distribution Function of X is $F_X(X) = P(X \geq x)$
- Experiment on measuring a frequency component in given spectra is carried out; all possible results of the measurement is defined as Random Vector Space
- Conditional Probability Distribution of X and Y is $F(x \mid Y=y) = P(X=x \mid Y=y)$.
- Joint Probability Density Function is $[\delta^{n+m} F] / \{ (\delta x_1 \dots \delta x_n) (\delta y_1 \dots \delta y_m) \}$
- Loss function of an incorrect estimate is $L = L\{|x^2| (k \mid j)\}$
- A stochastic process is Gauss-Markov, if it is only partially Markov and Full Gaussian
- If Ensemble of stochastic process has countable number of elements, then it is a Chain
- Covariance Matrix of uncorrelated random vectors is Diagonal
- Gaussian Random Vectors are uncorrelated and independent

2. (a) Define

- Joint Probability Distribution Function (JPD)
- Conditional Probability density Function (CPD)

5+5

(b) Given two scalars X and Y having cylindrical JPD as

10

$$1/\pi : x^2 + y^2 \leq 1$$

$$f(x, y) = \begin{cases} 1/\pi & : x^2 + y^2 \leq 1 \\ 0 & : \text{elsewhere} \end{cases}$$

Using Baye's Rule, derive CPD for $Y=0$; sketch the function

3. a) What is a Stochastic Process; state the properties 6+6+8
 b) Explain difference between continuous-time & discrete-time stochastic process
 c) What are properties of Covariance Kernel
4. a) What is a Gauss-Markov Stochastic Process 8+12
 b) A scalar process $\{x(t); t \geq 0\}$ defined by differential eq. $dx/dt = -x(1 - t)$; assuming $x(t)$ is Gauss-Random with mean = 0 & variance > 0 , verify the process as Gauss-Markov or Not.
5. a) Define (i) Random Binary Transmission (ii) Semi-random binary transmission 5+5
 b) Auto-correlation of a random signal $y(t)$ is $R(\tau) = \exp(-b\tau)$; Derive an expression for its spectrum $S(\omega)$ and show its typical frequency response. 10
6. a) What is (i) Continuous-time stochastic process (ii) Sampled data stochastic process 5+5
 b) A scalar process $\{x(t); t \geq 0\}$ with $x(t) = A \cos t$ is a continuous random variable that is uniformly distributed between ± 1 . Obtain the ensemble representation 10
7. a) What is Prediction Problem 8
 b) State Wiener-Hopf integral equation; explain in terms of Impulse response $h(\tau)$ 12
8. Write Short Note (any two) 10x2
- (a) Orthogonal process
 (b) Smoothing filter
 (c) Recursive filter
 (d) Interpolation
 (e) Kalman Gain Matrix