EX/PRN/T/324/2017

BACHELOR OF PRINTING ENGINEERING, EXAMINATION, 2017

3rd Year, 2nd Semester

DIGIT	AL IM	AGING Time: Three hours	Full Marks: 100
Α	nswe	r any Five Questions	
 a) Convert the following image matrix into halftone using Steinberg method of error diffusion. 			ng Floyd and 8
		0.5	
	p)	Briefly describe the various kinds of inkjet systems.	6
	c)	Write the role of polarization filters in densitometry.	. 4
	d)	Write the role of screen ruling in moiré removal	2
2.	a)	Elaborate the proofs and approval cycle with necessar	ıry diagram. 🧸 🤄
	b)	Explain rosette patterns.	4
	c)	Write the advantages and disadvantages of moiré.	5
	d)	Describe the dot diffusion method.	5
3.	a)	Why proofs are made.	6
	b)	Write the benefits of stochastic screening.	6
	c)	Compare Bayer filter and Bayer matrix.	2
	d)	Write on the ideal requirements of a proofing system.	6
4.	a)	Describe PMT with necessary diagram.	8
	b)	Why sometimes softproof and hardproof does not ma	tch?
	c)	Compare PMT and CCD.	4

d) Write the various methods of CCD arrangement technique.

5.	a)	Generate 8 by 8 order dither matrix from the following matrix D ₂ D ₂ = 3 1 0 2	6		
	b)	• -	4		
		140 48 120 61 92 170 205 160 77 6 100 10 75 120 145 60 77 170 125 240			
	c)	Explain the role of interpolation in imaging.	4		
	d)	Write the role of halftone dot shape.	4		
	e)	Distinguish between Hell and Royal Zenith drum scanner.	2		
6.	a)	Write the required relation to compute the scan resolution of line	6		
		art, grayscale and color images.			
	b)	Describe one method of photomechanical and one method of	5		
		electrostatic proofing system.			
	c)	What are the various types of proofing systems?	5		
	d)	Describe Floyd Steinberg method of error diffusion.			
7.	a)	Describe various types of imagesetter.			
	b)	Write on imagesetter calibration.			
	c)	Explain monotype lasercomp with necessary diagram.			
8.	a)	Compare CAD and DAD based laser printers. 3			
	b)	Compare CCD and CMOS sensors.			
	c)	Write the factors that determine the file size of a digital image. 3			
	d)	Distinguish between three pass and single pass scanning. 4			
	e)	Compare clustered dot dither and dispersed dot dither. 4			
	f)	Explain some drawbacks of pixel grid patterning.	4		