

BACHELOR OF ELECTRICAL ENGINEERING (EVE) (3rd YR 1ST SEMESTER)**EXAMINATION, 2017**(1st / 2nd-Semester/Repeat/Supplementary/Annual/Bi-Annual)**SUBJECT: - ELECTRICAL INSTRUMENTATION**

Full Marks 100

Time: ~~Two hours~~/Three hours/ Four hours/ Six hours

(50 marks for each part)

Use a separate Answer-Script for each part

No. of Questions	PART I	Marks
1.	<p>Answer Question: ONE and any TWO from the rest: (All symbols have their usual significance.)</p> <p><i>Answer any four questions.</i></p> <p>a) Why PSD circuit connected to LVDT sensor can detect the direction of displacement ?</p> <p>b) Why variable dielectric type capacitive sensor is suitable for measurement of thickness?</p> <p>c) Why temperature compensation is needed for strain gauge bridge</p> <p>d) How a piezoelectric sensor can be used in accelerometer ?</p> <p>e) Distinguish between the operation of Doppler frequency shift type and Transit type ultrasonic flow sensor</p>	4X5
2.	<p>f) Derive the expression of frequency domain transfer function and voltage sensitivity per unit core displacement of a LVDT when its secondary is connected to meter load.</p> <p>g) The core of a LVDT is connected to a diaphragm type pressure sensor. The LVDT gives output of 10V rms when the pressure is 200N/m². The diaphragm is deflected through 0.5X10⁻³ mm by a pressure of 100 N/m². What is the sensitivity in V/N/m² of the whole arrangement?</p>	8+7
3.	<p>a) Define 'g' and 'd' constants of a piezoelectric sensor . Prove any relation existing between them.</p> <p>b) Derive the expression of error voltage as output from a AC bridge , whose adjacent arms include two capacitive elements (C1,C2) of a differential capacitive sensor and change by $\pm \Delta C$</p>	7+8

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4.	<p>a) Explain the phenomenon of piezoelectricity with necessary diagram.</p> <p>b) What are the different modes .of piezoelectric sensors?</p> <p>c) Explain with diagram, the working principle of servo accelerometer .</p> <p>Write short notes on any three of the following:</p>	5+5+5
5.	<p>a) Liquid level measurement using ultrasonic sensors following pulse echo method.</p> <p>b) Electromagnetic type velocity sensor.</p> <p>c) Hot wire anemometer .</p> <p>d) Load cell.</p>	3X5

B.E.E. (EVENING) 3RD YEAR 1ST SEMESTER SUPPLEMENTARY EXAMINATION, 2017**SUBJECT: - ELECTRICAL INSTRUMENTATION**

Time: Three hours

Full Marks 100
(50 marks for each part)

Use a separate Answer-Script for each part

No. of Questions	PART-II	Marks
Answer any three, 2 marks for well organized answers		
1.	Justify and/or correct the following statements:	(4X4=16)
	i) Switched capacitor circuits have certain advantages in IC technology.	
	ii) Butterworth poles are placed on an ellipse.	
	iii) <i>Lock Range</i> and <i>Capture Range</i> of a Phase Locked Loop (PLL) are same.	
	iv) State variable filters are called " <i>universal filters</i> ".	
2. a)	Design a low pass maximally flat active filter with the following specifications: a) 3-dB cut-off frequency (ω_c) = 1000 rad/s. b) maximum attenuation in the pass band is 0.5 dB for $\omega \leq 0.5\omega_c$ rad/s. c) minimum attenuation in the stop band is 20 dB for $\omega \geq 4\omega_c$ rad/s d) pass band gain = 4 Realize the above filter circuit.	(9+7=16)
	b) Derive the transfer function of a high pass filter for state variable filters. (Draw necessary circuit realization).	
3. a)	How PLL can be used as frequency translator?	(6+6+4= 16)
	b) Develop a linear model of PLL.	
	c) How proper compensation circuit is designed for Cathode Ray Oscilloscope (CRO) to avoid error due to input impedance?	
4. a)	Explain the operation of a successive approximation type A/D converter for 3-bits.	(6+6+4=16)
	b) A four bit unipolar Successive Approximation type ADC has an offset error of - 1/2 LSB. Reference voltage is +12 volts. Find the output for input voltage 8.6 V <u>with</u> and <u>without</u> offset error.	
	c) Compare the conversion times for 4 bit SAR type and counter type ADC in case of 8.6 V input with $V_{ref} = +12$ V and clock frequency 1kHz.	
5.	Write Short notes on any <i>two</i>	(2X8=16)
	a) Storage Oscilloscope	
	b) Gain and offset errors of DAC	
	c) Linearity error of ADC	