

NYQUIST STABILITY:

Basic philosophy:

$$\frac{C(s)}{R(s)} = \frac{G(s)}{1 + G(s)H(s)}$$

$$F(s) = 1 + G(s)H(s) = 0 \quad ; \quad GH(s) = \frac{N(s)}{D(s)}$$

$$= 1 + \frac{N(s)}{D(s)} = \frac{N'(s)}{D(s)}$$

∴ ① \mathcal{Q} poles of system = Zeros of $F(s)$ = ROOTS of charac. eqn.

② \mathcal{Q} T.F. $GH(s)$ poles = poles of $F(s)$

③ For asymptotic stability of \mathcal{Q} sys.,

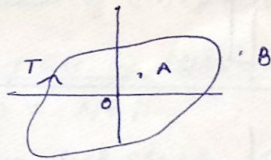
NO restriction on poles/zeros of \mathcal{Q} T.F. $GH(s)$

BUT Poles of \mathcal{Q} T.F. = Zeros of $F(s)$ in LHS.

Finding zeros of $F(s)$ is difficult but using $GH(s)$ roots, infer stability.

ANALYTIC FN $F(s)$ in s -plane if for n all its derivatives exist \Rightarrow no singular pts. \Rightarrow no POLES.

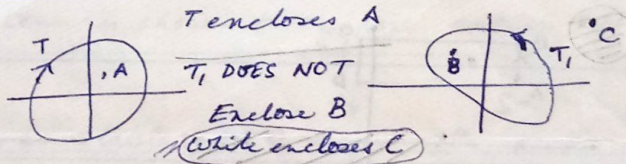
ENCIRCLED: A pt. is encircled by a closed path if it is found inside the path. Usually CW (convention for +ve traversal)



O, A encircled
B not.

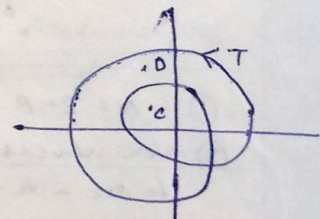
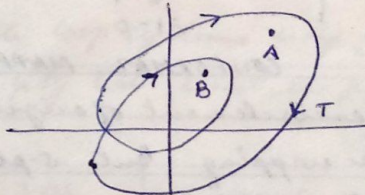
ENCLOSED

A point or region is said to be enclosed by a closed path if it is on the RT of a path when the path is traversed in CW direction.



No. of encirclements

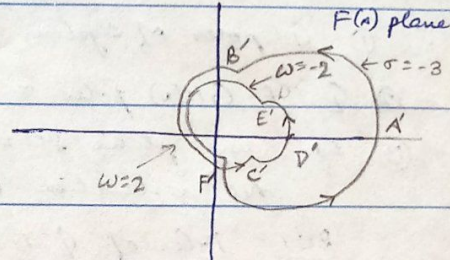
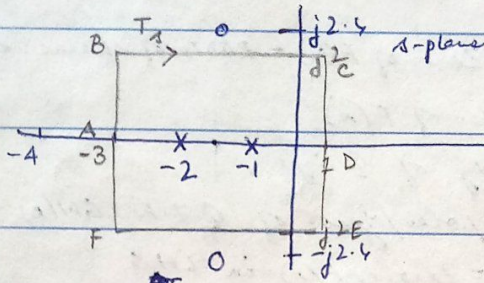
- For B $N = +2$
- A $N = +1$
- C $N = -2$
- D $N = -1$



Conformal mapping:

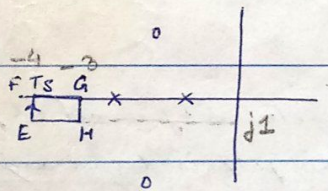
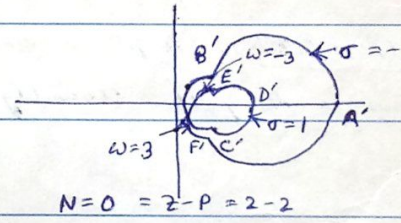
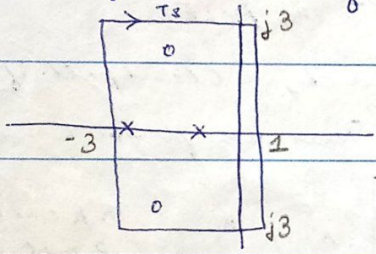
Say $G_H(s) = \frac{6}{(s+1)(s+2)}$

$\therefore F(s) = 1 + G_H(s) = \frac{(s+1.5+j2.4)(s+1.5-j2.4)}{(s+1)(s+2)} = 0$

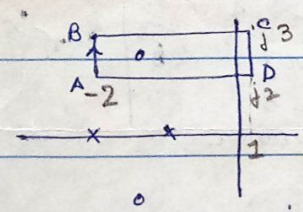
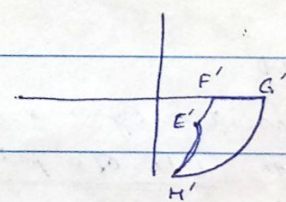


$s = \sigma + j\omega$	$A = -3 + j0$	$B = -3 + j2$	$C = 1 + j2$	$D = 1 + j0$	$E = 1 - j2$	$F = -3 - j2$
$F(s) = u + jv$	$A + j0$	$0.7 + j0.9$	$1.11 - j0.577$	$2 + j0$	$1.11 + j0.577$	$0.7 - j0.9$

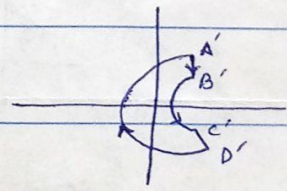
\therefore No. of encirclements of origin $N = -2 = Z - P$ as in $T_s \rightarrow$ hence can be used as CHECK for ANALYTICAL FN. in specified region



$N = 0$



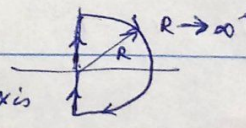
$N = +1$
 $= Z - P$
 $= 1 - 0$



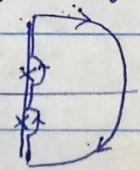
CONFORMAL MAPPING.

- ① $\therefore N = Z - P$ (encirclement of origin)
- ② Non reversible mapping But s-plane to $F(s)$ plane is one-to-one mapping

Usually T_s as jw axis & RHS-plane
But if pt. of singularity or pole on jw axis then small detour.

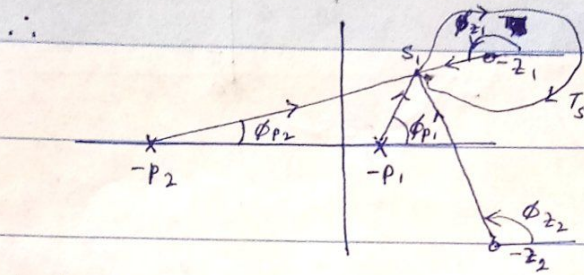


to keep region enclosed in s-plane s.t. $F(s)$ is analytic - value exists



CAUCHY'S THEOREM :

Say $F(s) = \frac{(s+z_1)(s+z_2)}{(s+p_1)(s+p_2)} = |F(s)| (\phi_{z_1} + \phi_{z_2} - \phi_{p_1} - \phi_{p_2})$



\therefore As s_1 traverses T_s , angles generated by $-p_1, -p_2, -z_2$ after one complete round are 0, while \angle generated by $-z_1$ is 2π radians (clockwise)

\therefore If Z zeros & P poles are encircled, then angle generated is $2\pi(Z) - 2\pi(P) = \phi_F = 2\pi N = \text{net angle generated by } T_s$ and hence net encirclement of origin of $F(s)$ plane in CW direction is $N = Z - P$.

Note $GH(s) + 1 = F(s) \Rightarrow GH(s)$ plane $(-1, 0)$ pt. $\equiv F(s)$ plane origin

\therefore Polar plot encirclement of $(-1, 0)$ pt. $\equiv F(s)$ plane encirclement of origin.

\therefore If there are P poles of GH in RHS and N encirclements of $(-1, 0)$
 $\Rightarrow Z$ of $F(s) = 1 + GH(s) = N + P$

Required to be zero for A. stable G_c system $\Rightarrow N = -P$ required.

NYQUIST STABILITY CRITERION :

- a) The Nyquist plot is obtained by mapping the fr. $GH(s)$ -polar plot.
- b) The Nyquist contour is chosen to enclose entire RH of s -plane

Then $Z = N + P$

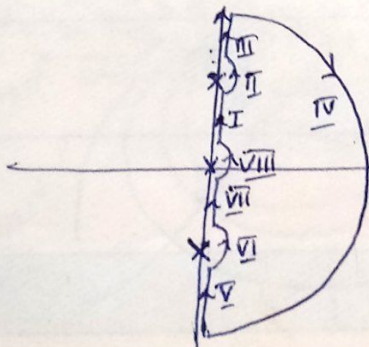
For G_c system to be stable, $Z = 0 \Rightarrow N = -P$.

Note: Since multiple loop systems may NOT include poles in RHS
 \therefore Routh's stability test must be performed.

II		III		IV	
s	F(s)	s	F(s)	s	F(s)
A = -3 + j0	4 + j0	A = -4 + j0	2 + j0	A = -2 + j2	-0.2 + j0.6
B = -3 + j3	0.68 + j0.41	B = -3 + j0	4 + j0	B = -2 + j3	0.4 + j0.2
C = 1 + j3	0.92 - j0.38	C = -3 + j1	1.6 - j1.8	C = 1 + j3	0.92 - j0.38
D = 1 + j0	2 + j0	D = -4 - j1	1.6 - j0.6	D = 1 + j2	1.11 - j0.58
E = 1 - j3	0.92 + j0.38				
F = -3 - j3	0.68 - j0.41				

Nyquist path for Q poles on $j\omega$ axis

$$GH(s) = \frac{K}{s(s^2 + \omega_1^2)(s+a)} \quad a > 0$$



- | | | |
|----------|----------------------------|-----------------------------------|
| I | $s = j\omega$ | $j0^+ \rightarrow j\omega_1^-$ |
| II | $s = \epsilon e^{j\theta}$ | $\theta \in [-\pi/2, \pi/2]$ |
| III | $s = \omega$ | $j\omega_1^+ \rightarrow j\infty$ |
| IV | $s = R e^{j\phi}$ | $\phi \in [\pi/2, -\pi/2]$ |
| V to VII | IPP of III to I | |
| VIII | $s = \epsilon e^{j\theta}$ | $\theta \in [-\pi/2, \pi/2]$ |