# Linearization of Sensors

# Topics to be covered

# **Linearization Techniques for RTDs**

# **Linearization Techniques for Thermistors**

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# Resistance Temperature Detectors (RTDs)

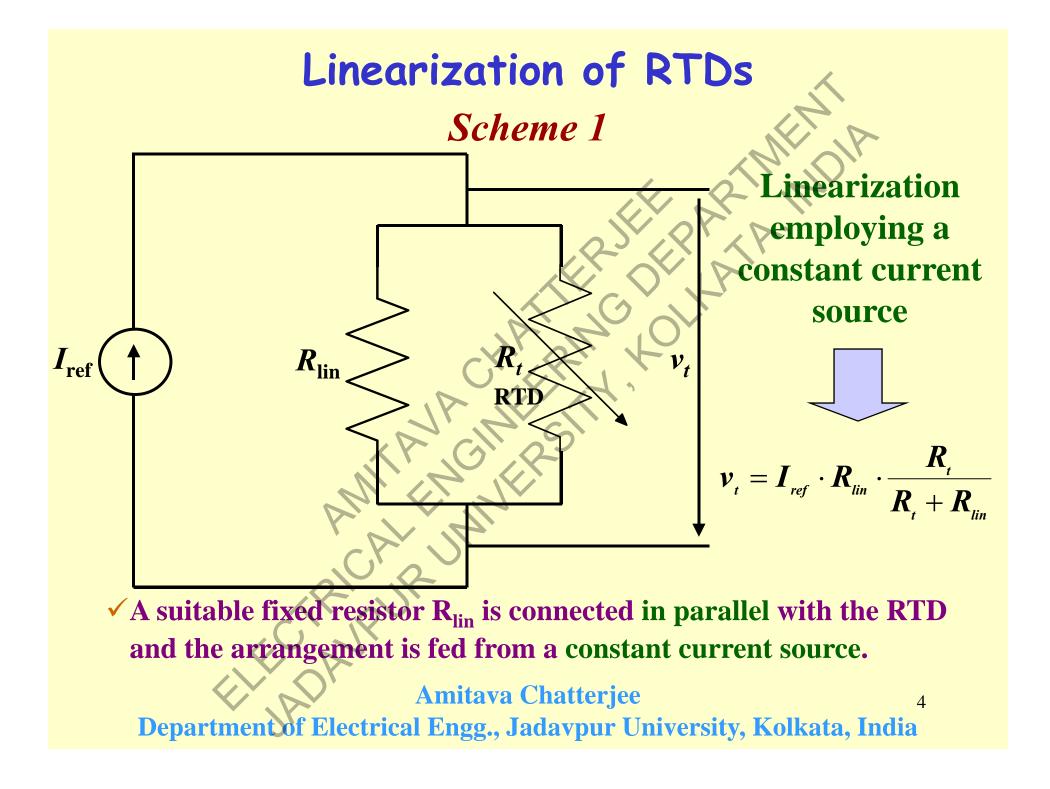
 Resistance Temperature Detectors (RTDs) are temperature transducers which produce an output resistance (R) in response to an input temperature (t).

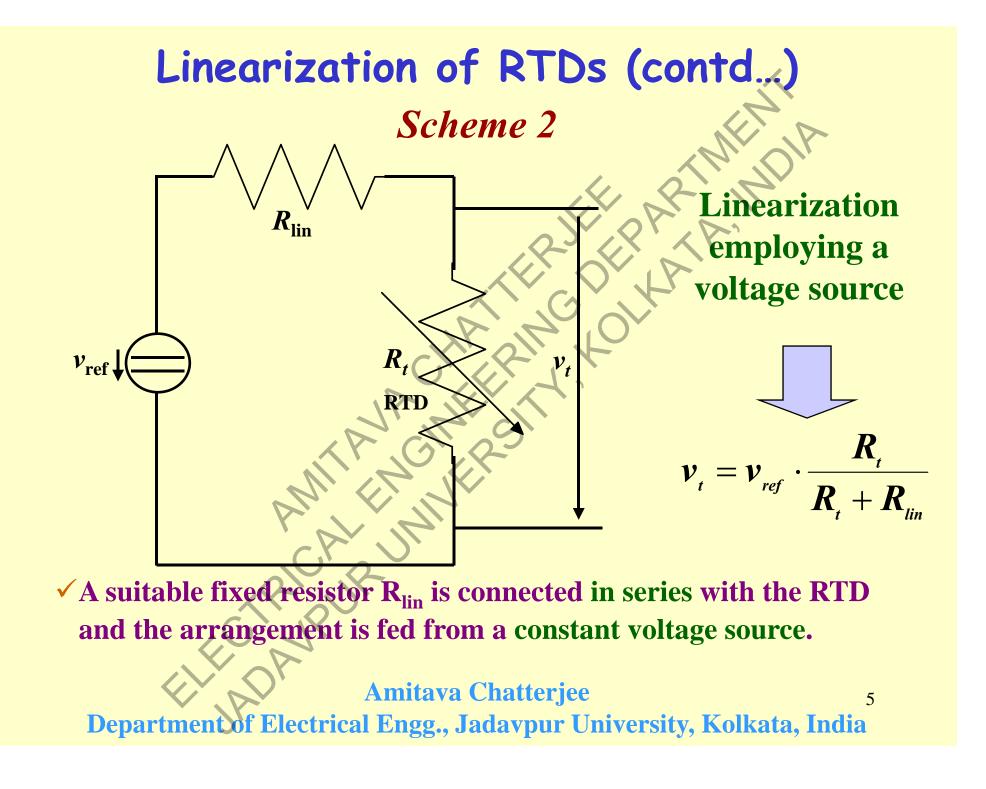
$$R = R_0 \left( 1 + \alpha_1 t + \alpha_2 t^2 + \dots + \alpha_n t^n \right)$$

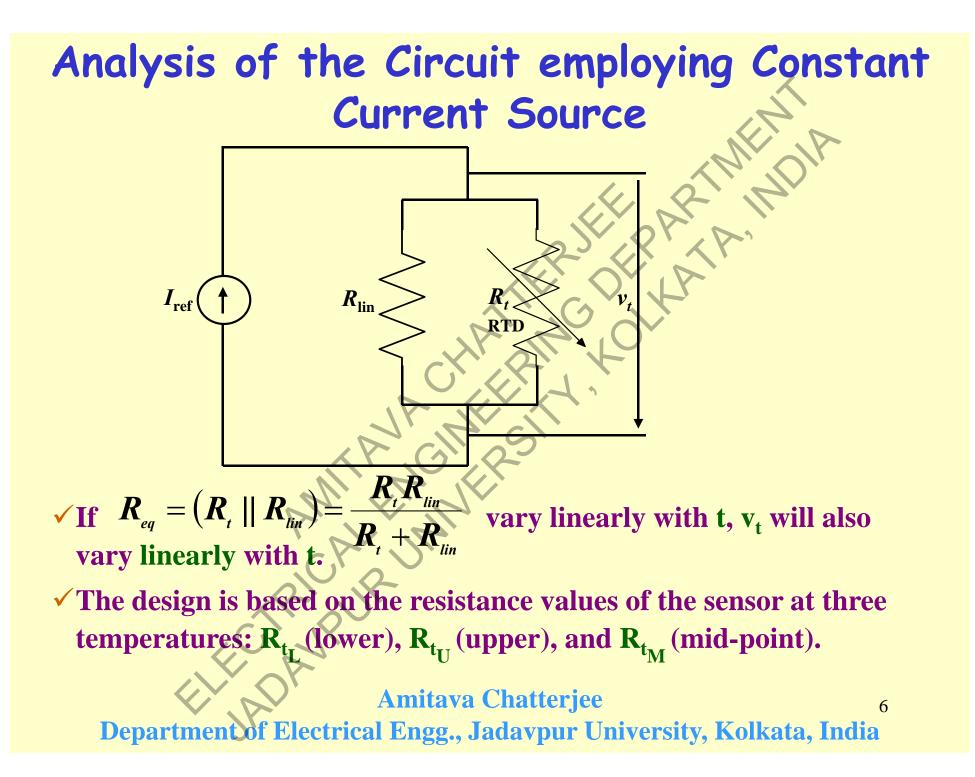
- Most commonly used materials for construction of RTDs: Platinum, Nickel and Copper.
- Usually 2 or 3 of the α constants are good enough for highly accurate representation.

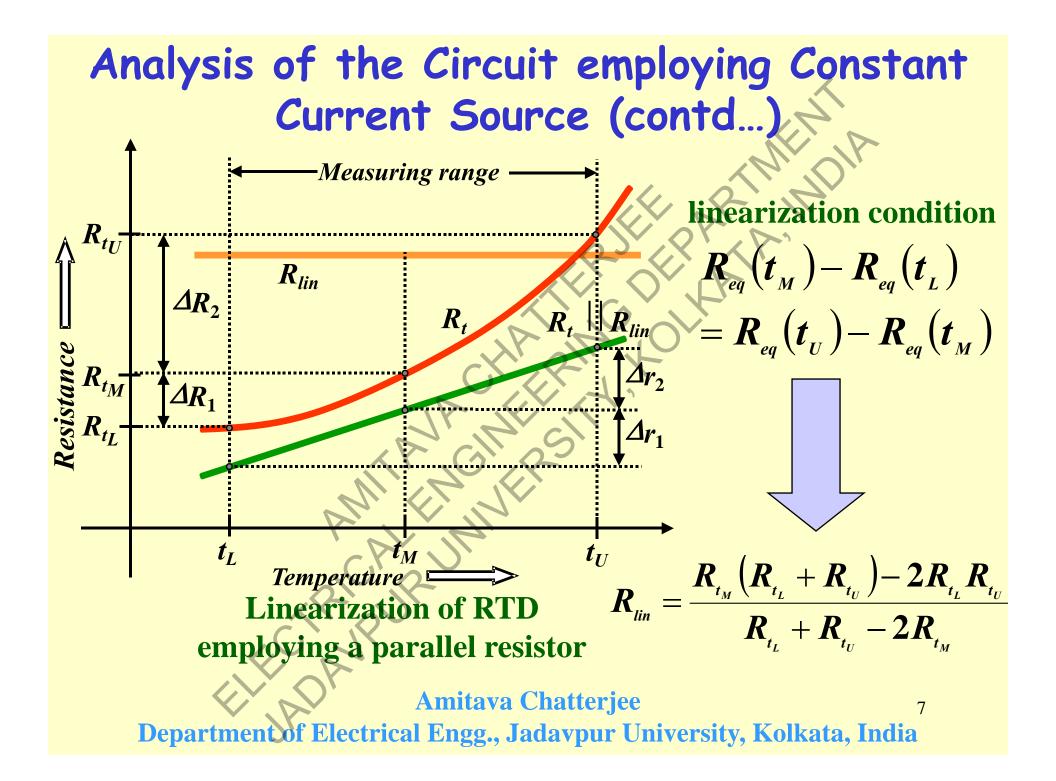
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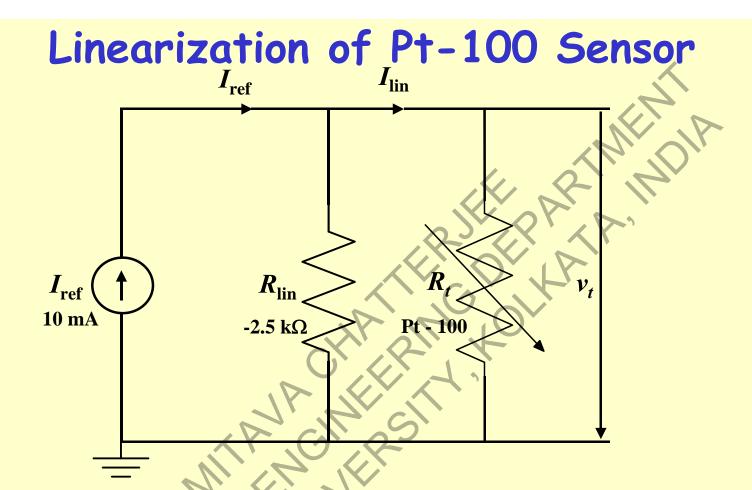
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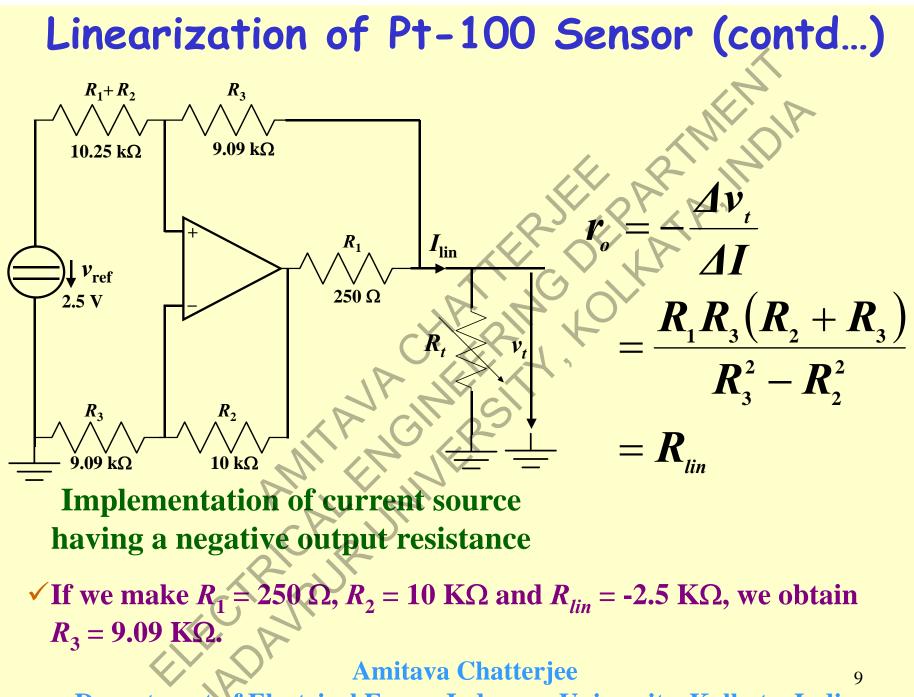




✓ For a Pt-100 sensor, operated in the temperature range between 0°C and 400°C, a linearizing resistor  $R_{lin} = -2.5$  KΩ is required.

✓ A current source of negative internal resistance must be used in this case.

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### Thermistors

Thermistors are semiconductor type temperature transducers with a negative temperature co-efficient of resistance.

 $R_0$ : resistance at the reference temperature

 $R_{T} = R_{0} \cdot exp \left| \beta \left( \frac{1}{T} - \frac{1}{T_{0}} \right) \right| \stackrel{T_{0}}{\beta: \text{ an experimentally determined constant,}} \\ \beta: \text{ an experimentally determined constant,} \\ \text{varies between 3500K and 4600K,} \end{cases}$ 

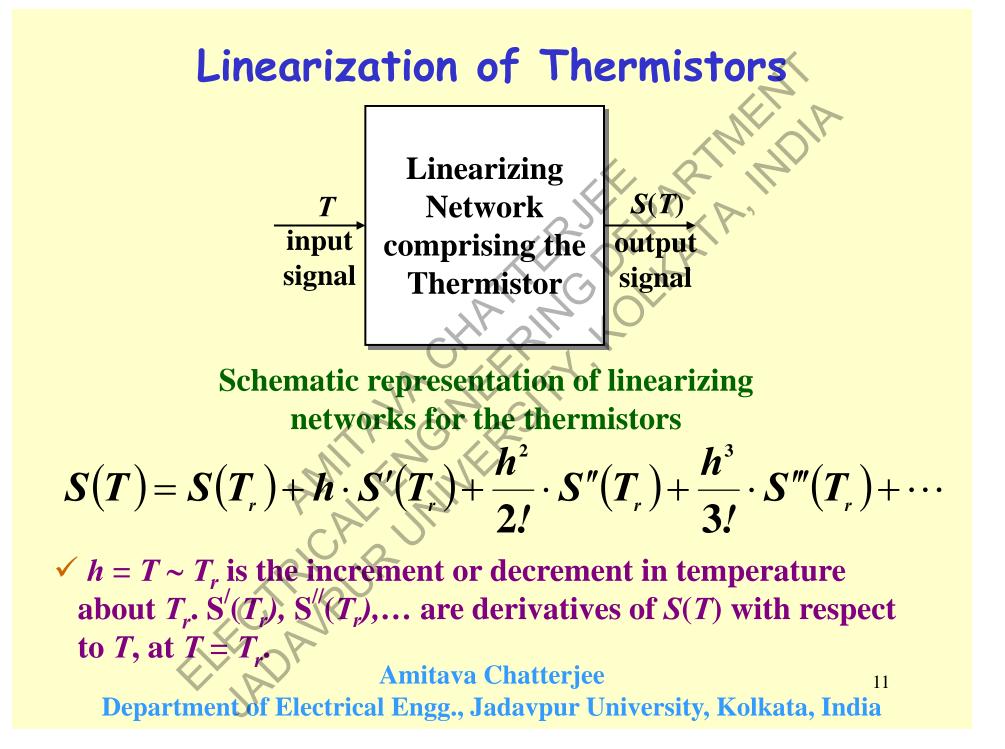
**T** and  $T_{0:}$  measured in Kelvin.

✓ Thermistors have large temperature co-efficients (-3 to -5%) per °C.

✓ More accurate temperature-resistance relation:

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 $\frac{1}{T_0} + \frac{1}{\beta} ln \frac{R_T}{R_0} + \frac{1}{C} \left( ln \frac{R_T}{R_0} \right)^2$ 

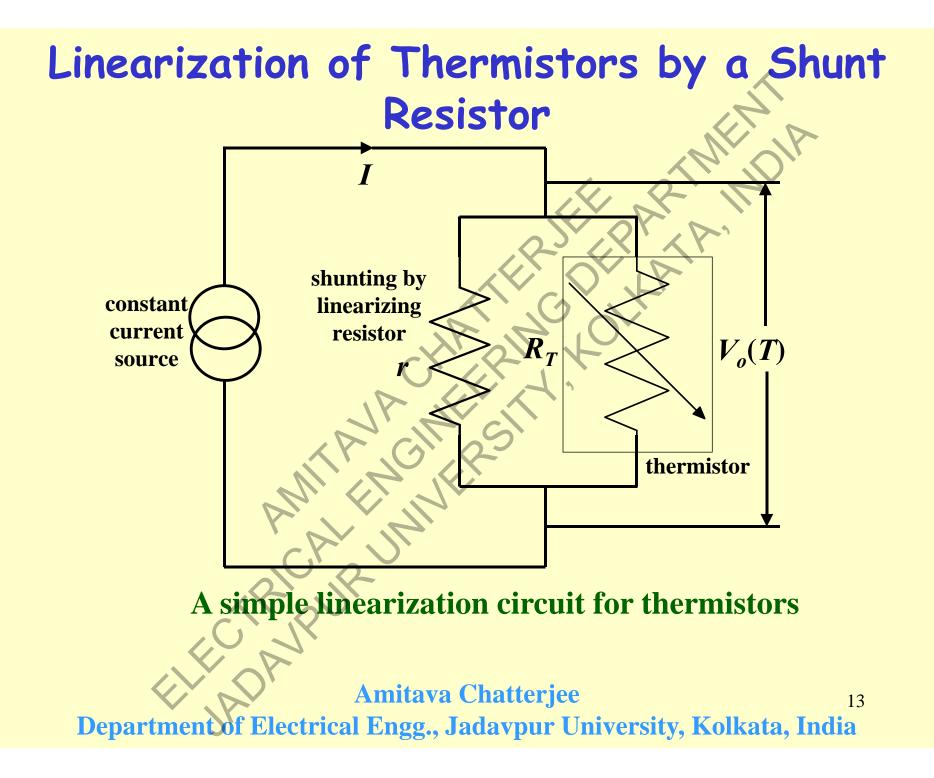


# Linearization of Thermistors (contd...)

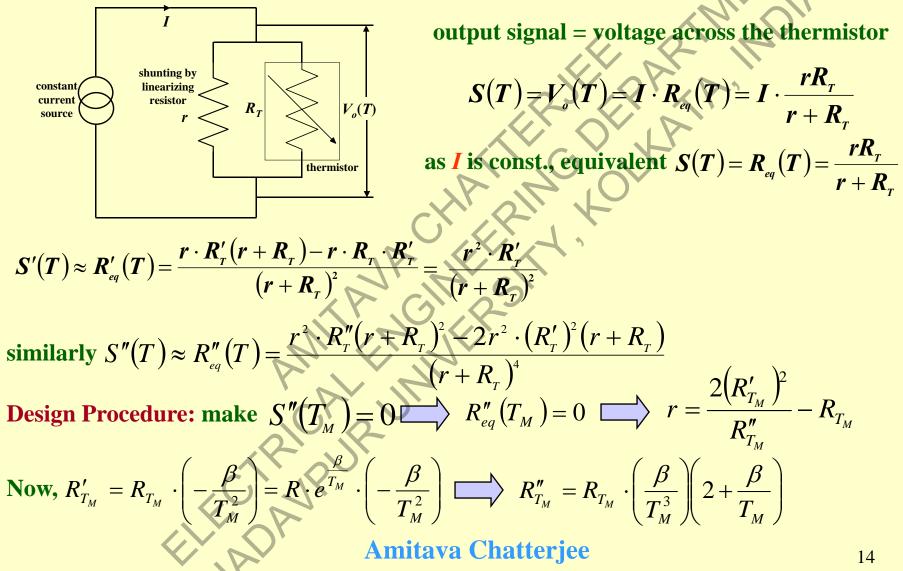
### **Considerations**

- ✓ The major contribution to non-linearity comes from the  $h^2$  term containing S<sup>*ll*</sup>( $T_r$ ). This term can be made zero by proper choice of circuit components.
- ✓ Under this condition, the S(T) vs. T characteristic can be assumed to be linear over a wide span of temperature, as long as the h<sup>3</sup> term remains negligibly small.
- ✓ The condition  $S''(T_p) \neq 0$  implies that the *S*(*T*) vs. *T* curve should have a point of inflection at *T* = *T<sub>r</sub>*.
- ✓ In practice, by proper selection of components, the point of inflection is located at the midpoint  $T_M$  of the range of temperature over which linearization is to be carried out.

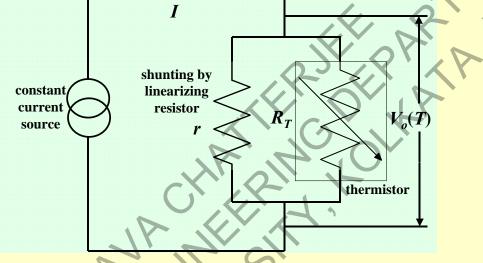
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# Linearization of Thermistors by a Shunt Resistor (contd...)



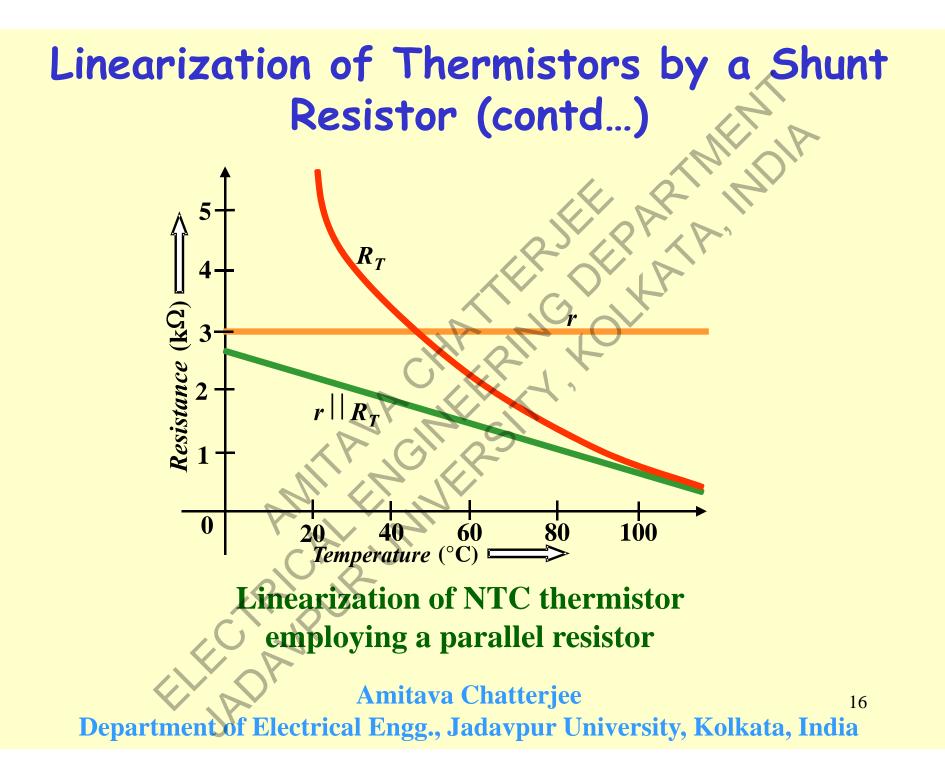
# Linearization of Thermistors by a Shunt Resistor (contd...)

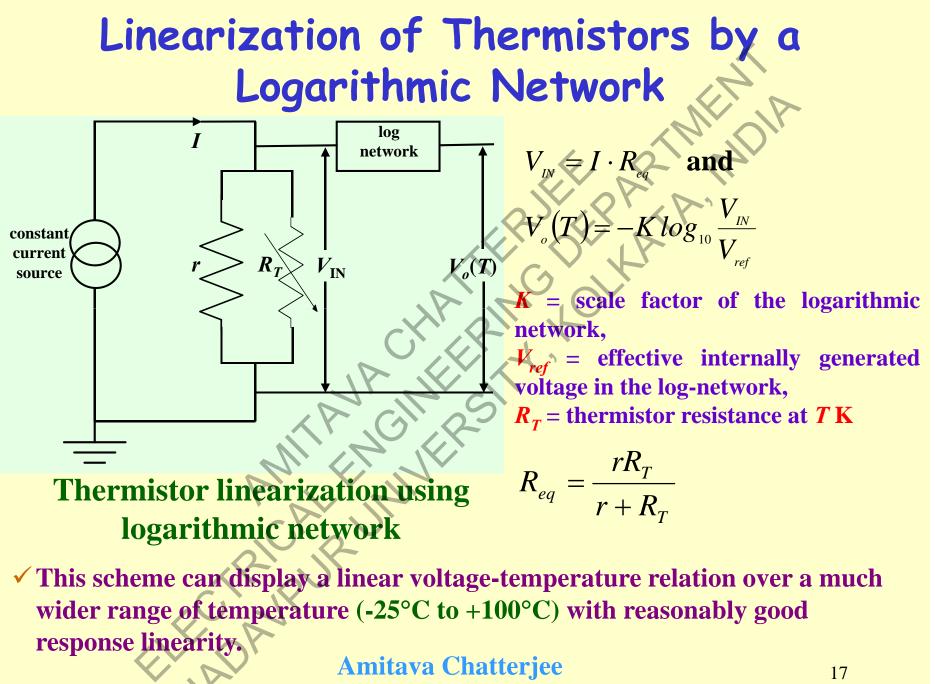


Final expression for the linearizing shunt resistance *r*:

 $r = R_{T_M} \left[ \frac{\beta - 2T_M}{\beta + 2T_M} \right]$ 

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## Linearization of Thermistors by a Logarithmic Network (contd...)

 $V_o(T)$   $V_o(T) = V_o(T_r + h) = V_o(T_r) + h \cdot V_o'(T_r) + \frac{h^2}{2!} \cdot V_o''(T_r) + \frac{h^3}{3!} \cdot V_o''(T_r) + \cdots$  **h** =  $T \sim T_r$  is the increment or decrement in temperature about the reference temperature  $T_r \cdot V_o'(T_r), V_o''(T_r), V_o''(T_r)$  etc. are the first, second, third, etc. derivatives of  $V_o(T)$  w.r.t. t temperature T, at  $T = T_r$ .

 $\overline{I} R_T = R_0 \cdot \exp \left| \beta \left( \frac{1}{T} - \frac{1}{T_0} \right) \right| \& V_o(T) = -K \log_{10} \left[ \left( \frac{I}{V_{ref}} \right) \cdot \frac{rR_T}{r + R_T} \right]$ 

**Design Procedure:** make the  $h^2$  term zero  $\longrightarrow V_o''(T_r) = 0$ 

log network

 $V_{\rm IN}$ 

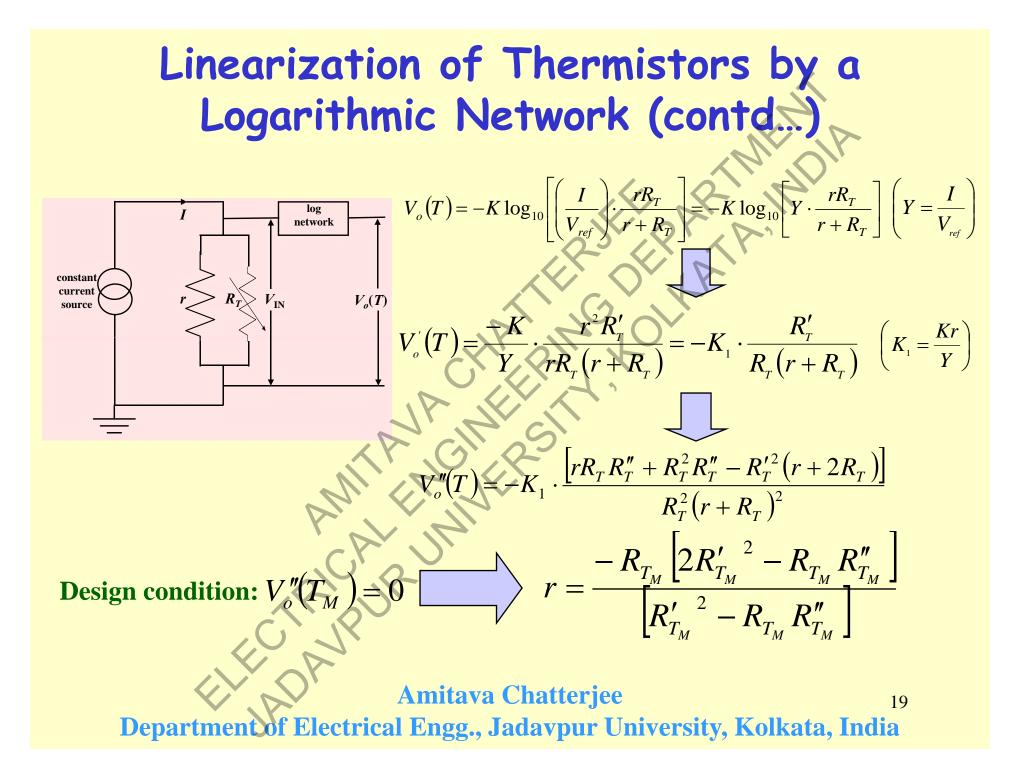
constant

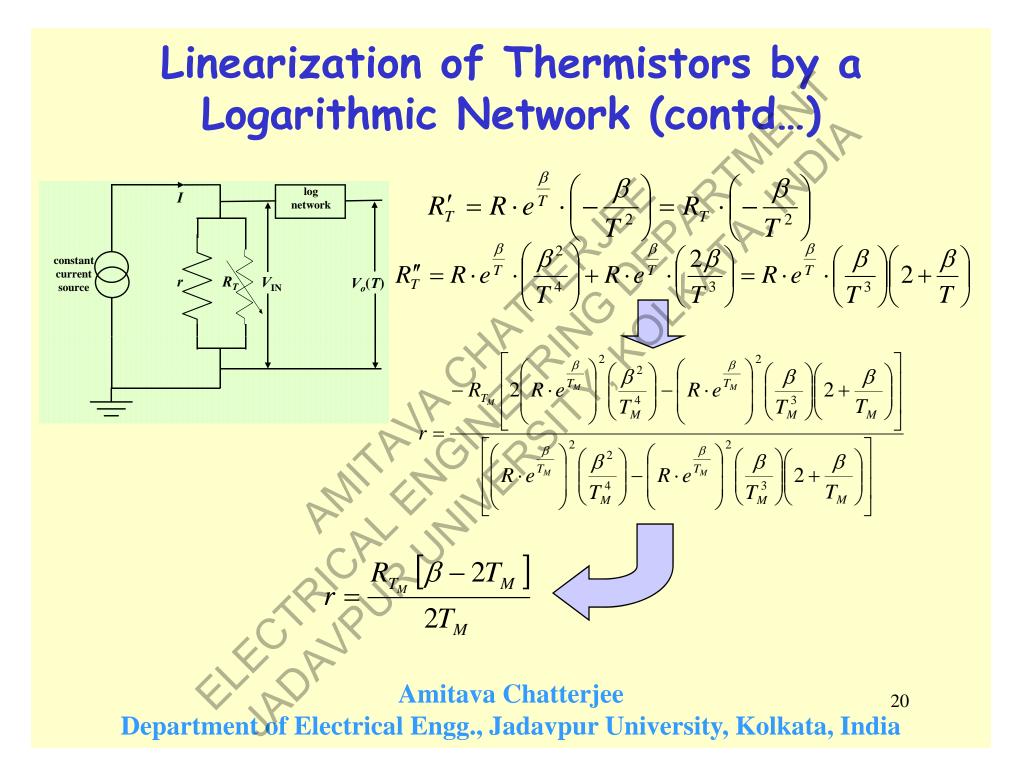
current

source

 $T_r$  is considered at the midpoint  $T_M$  of the range of temperature over which linearization is to be carried out

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Shockley's first order theory for a single p-n junction:

$$I = I_0 \left( \exp \frac{qV}{kT} - 1 \right)$$

$$I = \text{current through the junction (A)}$$

$$I_0 = \text{the theoretical reverse saturation}$$

 $I_0$  = the theoretical reverse saturation current (A) V = the voltage across the junction q = magnitude of the electronic charge (1.6 × 10<sup>-19</sup> C)

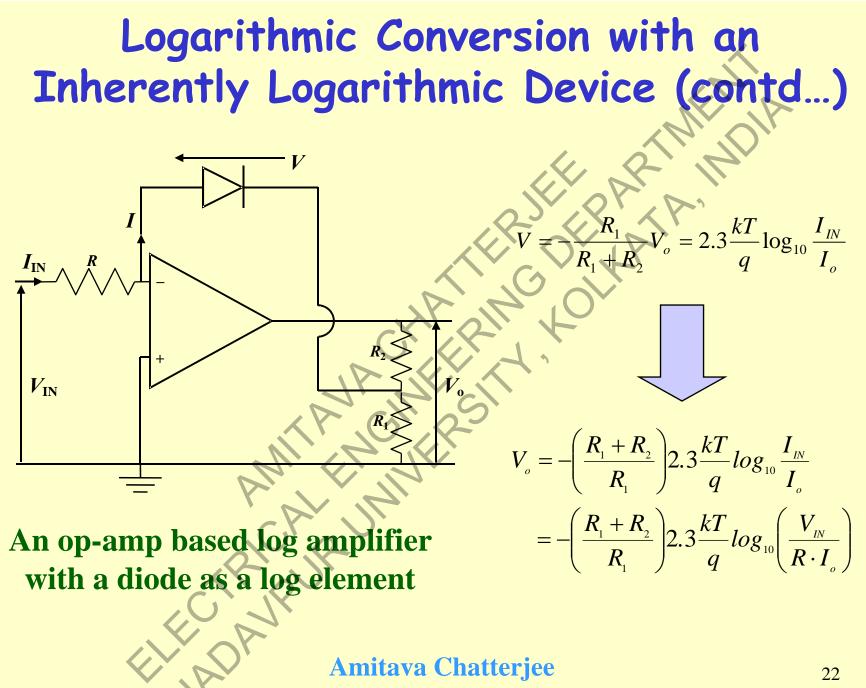
k = Boltzmann's constant (1.38 × 10<sup>-23</sup> J/K) and

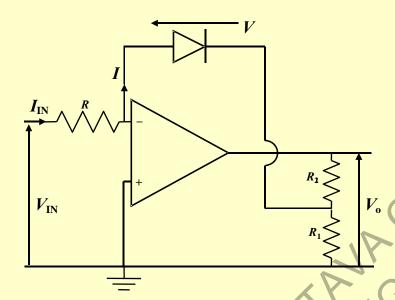
T = the temperature in K

 $\frac{kT}{q} \approx 26 \text{ mV} \text{ at } 27^{\circ}\text{C. Hence, for V} > 100 \text{ mV}, \quad I \approx I_0 \exp \frac{qV}{kT} \quad \square \qquad V = 2.3 \frac{kT}{q} \log_{10} \frac{I}{I_0}$ 

 $\log_{10}I$  varies linearly with *V*, with a slope of  $2.3\frac{kT}{q}$  < Volts/decade of current change.

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# Limitations

 The problem of temperature dependence of scaling factor, E<sub>o</sub>.

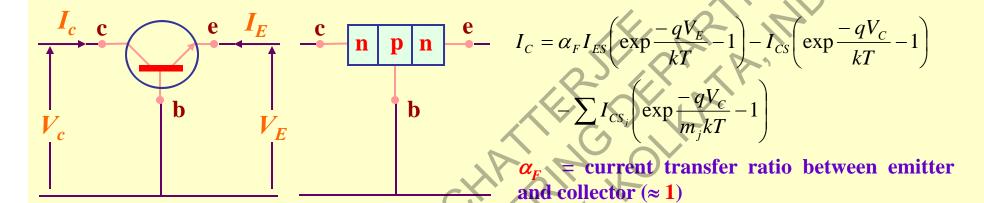
• Marked nonlinear temperature dependence exhibited by  $I_0$ .

**Diodes, used as ideal log elements, do not actually obey Shockley's relation accurately.** 

*Conclusion:* Transistors appear to be better candidates than diodes as logarithmic elements.

 $I_{j} = I_{0j} \left( \exp \frac{qV}{m_{j}kT} - i \right)$ 

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A simple n-p-n transistor model, along with its sign conventions  $I_{cs} = \text{collector reverse saturation current with}$  $I_{Es} = \text{emitter reverse saturation current with}$  $I_{Es} = \text{emitter reverse saturation current with}$ the collector shorted to the base

 $m_i$  = a constant, between 1 and 4

If 
$$V_C = 0$$
   
 $I_c = \alpha_F I_{ES} \left( \exp \frac{-qV_E}{kT} - 1 \right)$   
When  $I_C >> I_{ES}$    
 $-V_E = 2.3 \frac{kT}{q} \log_{10} \left( \frac{I_c}{I_o} \right)$  where  $I_o = \alpha_F I_{ES}$ 

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