

# OFF-LINE FIR DIGITAL FILTERS

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# FIR digital filters for off-line analysis

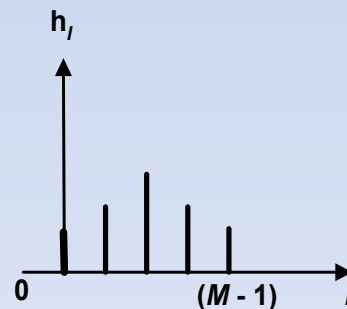
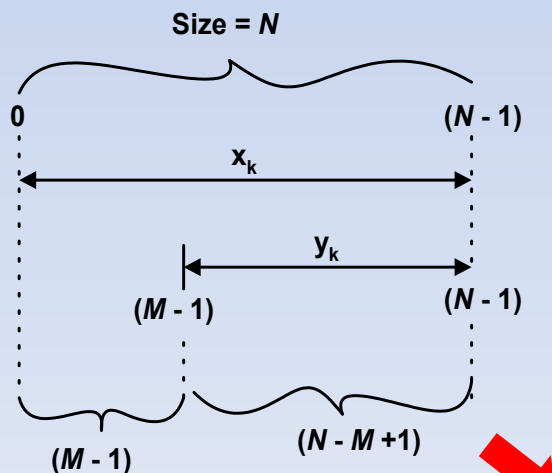
Let  $x_k$ ,  $k = 0, 1, 2, \dots, (N-1)$  be the off-line input data having a size of  $N$ .

Let an  $M$ -tap FIR filter be employed to process input data sequence  $x_k$ .

Assuming  $M$  to be odd and  $N > M$ , the output filter sequence may be represented as:

$$y_k = \sum_{l=0}^{M-1} h_l x_{k-l} \quad , \text{ for } k = (M-1), (M-1)+1, \dots, (N-1) \quad \dots(1)$$

where  $h_l$ ,  $l = 0, 1, 2, \dots, (M-1)$  is the causal finite impulse sequence of the filter.



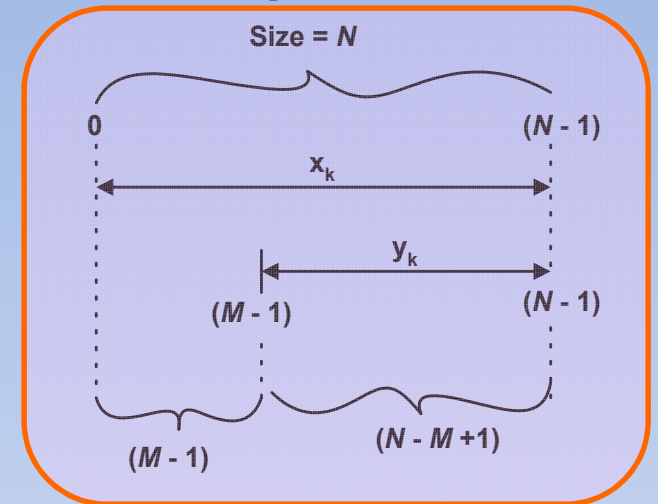
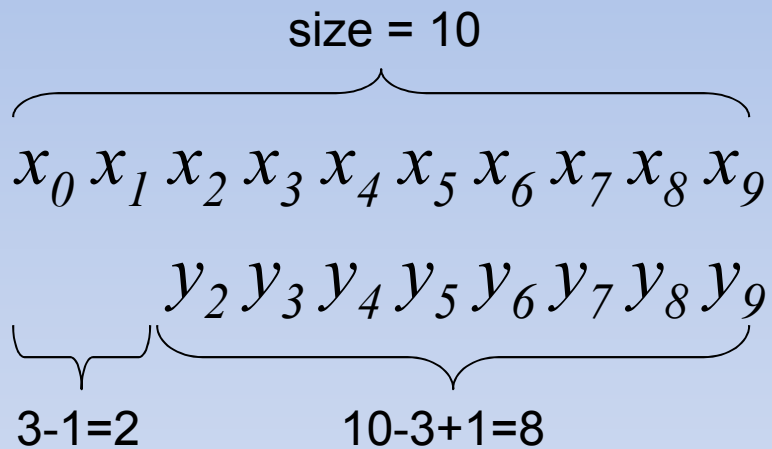
**The length of output sequence is smaller than the length of input sequence.**

Length of output sequence =  $N - M + 1$

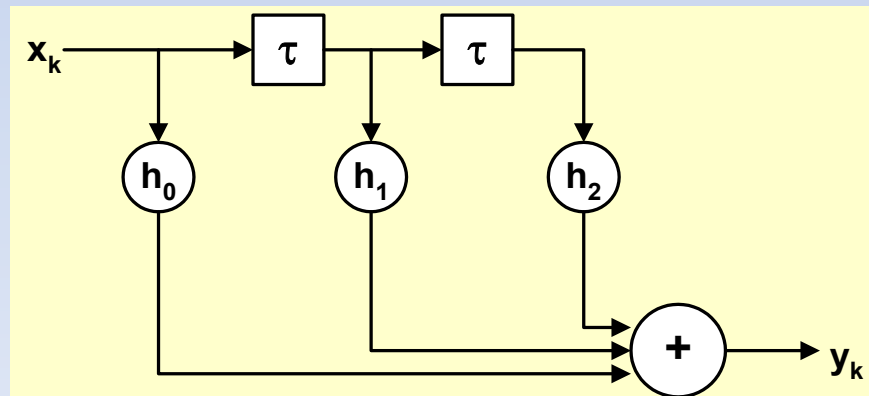
# FIR digital filters for off-line analysis

## Example:

Let  $N = 10$  and  $M = 3$ .



Realization

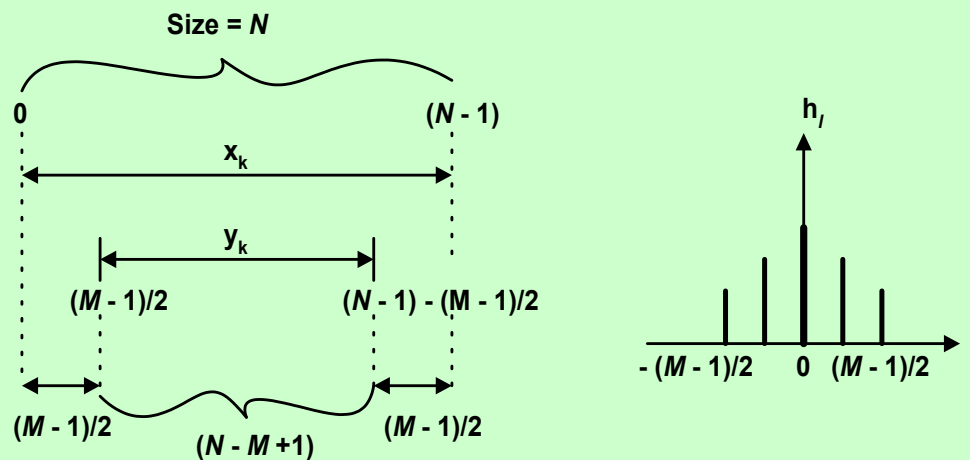


# FIR digital filters for off-line analysis

To have a symmetrical separation of  $y_k$  w.r.t.  $x_k$ , relation (1) may be expressed for a non-causal FIR filters (as causality is not essential for implementation of off-line filters) as,

$$y_k = \sum_{l=-\frac{(M-1)}{2}}^{\frac{(M-1)}{2}} h_l x_{k-l}, \text{ for } k = (M-1)/2, (M-1)/2+1, \dots, (N-1)-(M-1)/2 \quad \dots(2)$$

where  $h_l$ ,  $l = -(M-1)/2, \dots, 0, \dots, (M-1)/2$  is the non-causal finite impulse sequence of the filter.

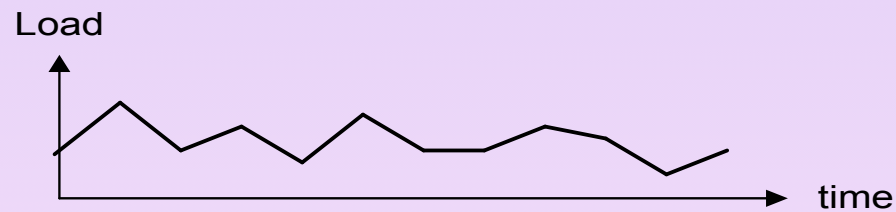


Here the spacing of  $y_k$  with respect to  $x_k$  is symmetrical.

# FIR digital filters for off-line analysis

## Examples of off-line data sequence

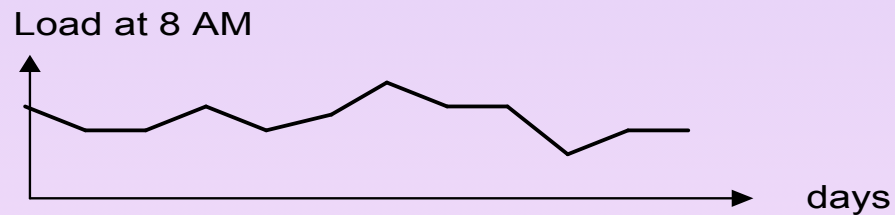
- Load variation of a particular place with respect to time of day.



# FIR digital filters for off-line analysis

## Examples of off-line data sequence

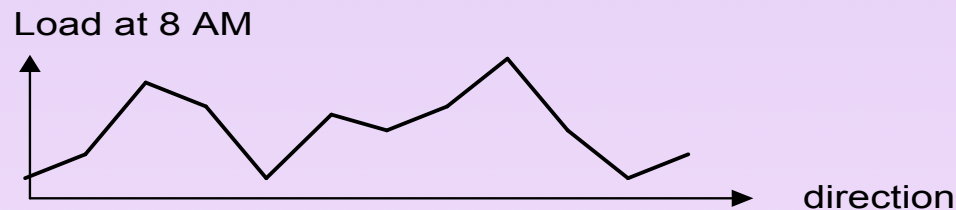
- Load variation of a particular place with respect to time of day.
- **Load variation of a particular place with respect to days at a particular time.**



# FIR digital filters for off-line analysis

## Examples of off-line data sequence

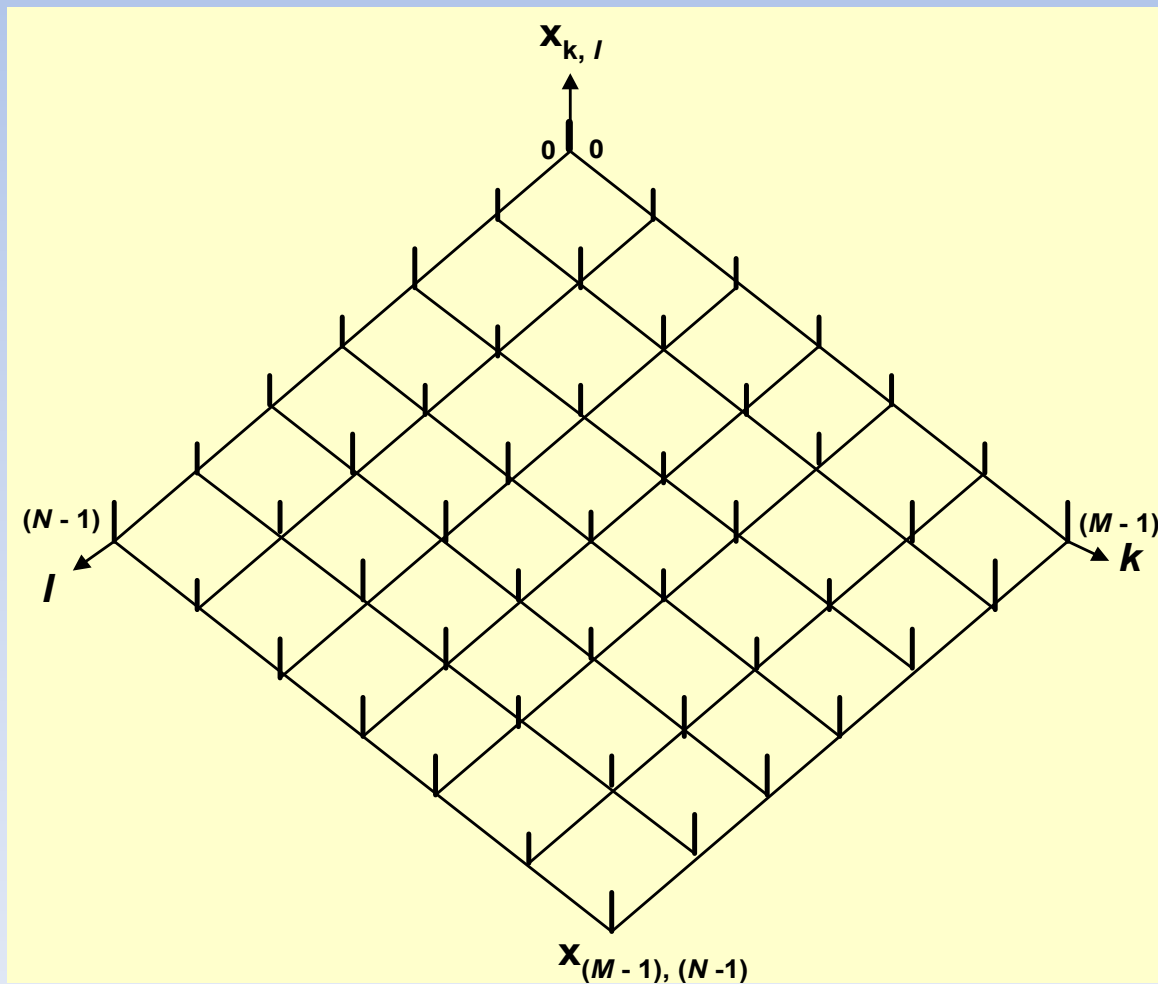
- Load variation of a particular place with respect to time of day.
- Load variation of a particular place with respect to days at a particular time.
- **Load variation along a particular direction in an area at a particular time.**



# FIR digital filters for off-line analysis of 2-D data

Let the 2-dimensional data sequence of size  $(M \times N)$  be

$$x_{k,l}, k = 0, 1, \dots, (M-1), l = 0, 1, \dots, (N-1)$$



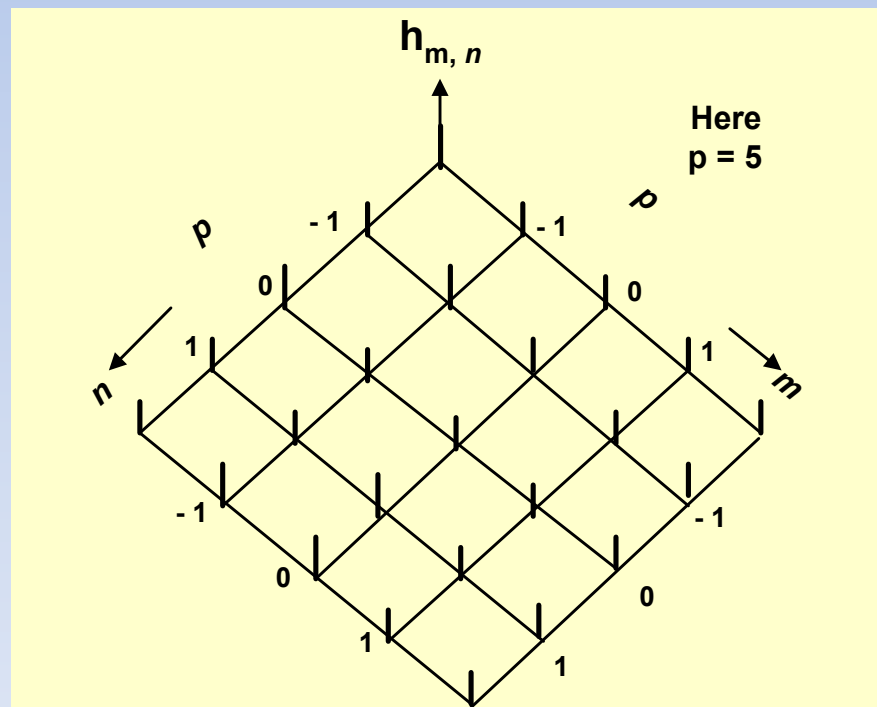


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Let a  $(p \times p)$  tap 2-dimensional FIR digital filter be employed to process  $x_{k,l}$ , assuming  $M, N > p$  and  $p$  is odd.



2-D finite impulse sequence of FIR digital filter

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Let a  $(p \times p)$  tap 2-dimensional FIR digital filter be employed to process  $x_{k,l}$ , assuming  $M, N > p$  and  $p$  is odd.

Then the filter output sequence may be expressed as (extending relation (2) for 2-dimensional)

$$y_{k,l} = \sum_{m=-(p-1)/2}^{(p-1)/2} \sum_{n=-(p-1)/2}^{(p-1)/2} h_{m,n} x_{k-m,l-n} \quad \dots(3)$$

for  $k = (p-1)/2, \dots, (M-1)-((p-1)/2)$  and  $l = (p-1)/2, \dots, (N-1)-((p-1)/2)$

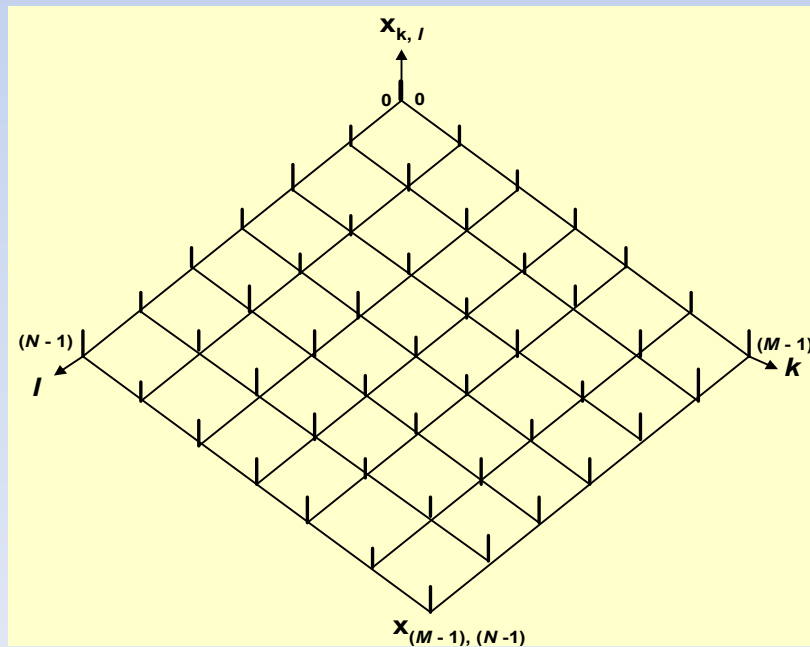
where  $h_{m,n}$ ,  $m = -(p-1)/2, \dots, 0, \dots, (p-1)/2$  and  $n = -(p-1)/2, \dots, 0, \dots, (p-1)/2$  is the non-causal 2-dimensional finite impulse sequence of the 2-dimensional digital FIR filter. Relation (3) represents a **2-dimensional convolution summation**.

# FIR digital filters for off-line analysis of 2-D data

$$y_{k,l} = \sum_{m=-(p-1)/2}^{(p-1)/2} \sum_{n=-(p-1)/2}^{(p-1)/2} h_{m,n} x_{k-m,l-n} \quad \dots(3)$$

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Relation (3) suggests that 2-dimensional filtering operation may be realized by performing 1-dimensional filtering operation  $M$  times along  $k$ -axis over  $N$ -data along  $l$ -axis.

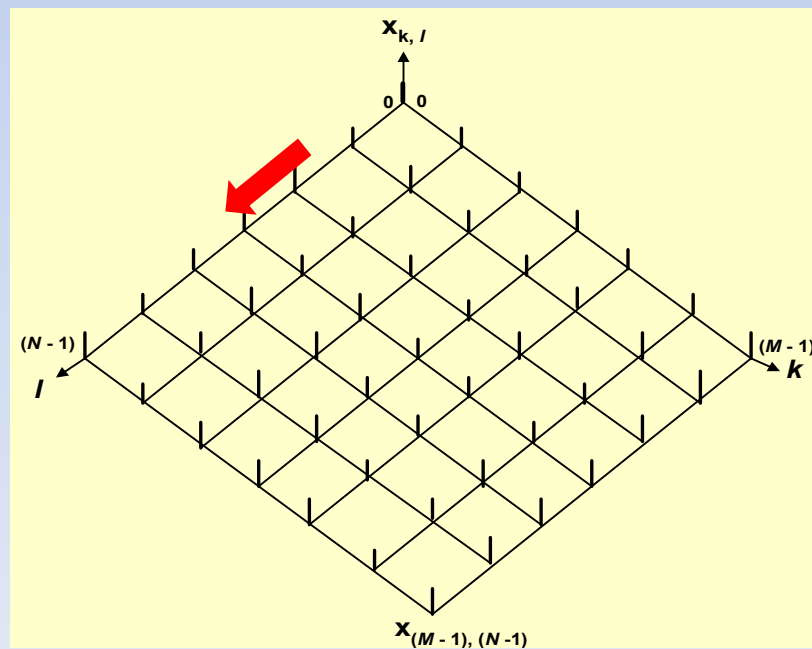


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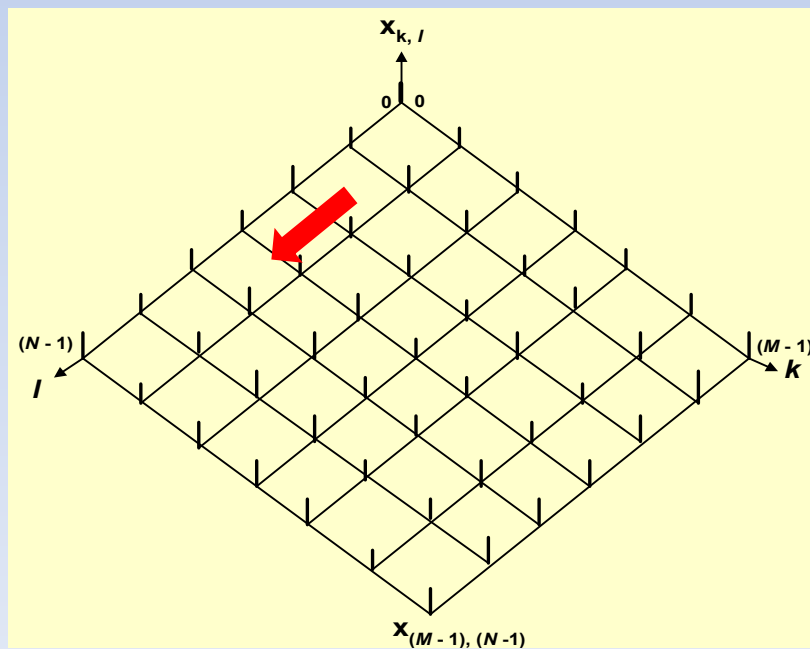


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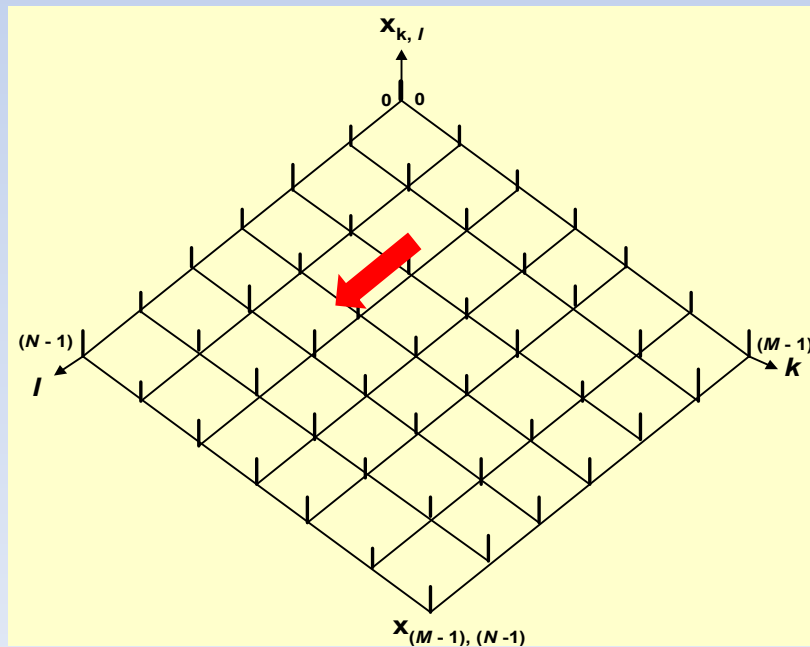


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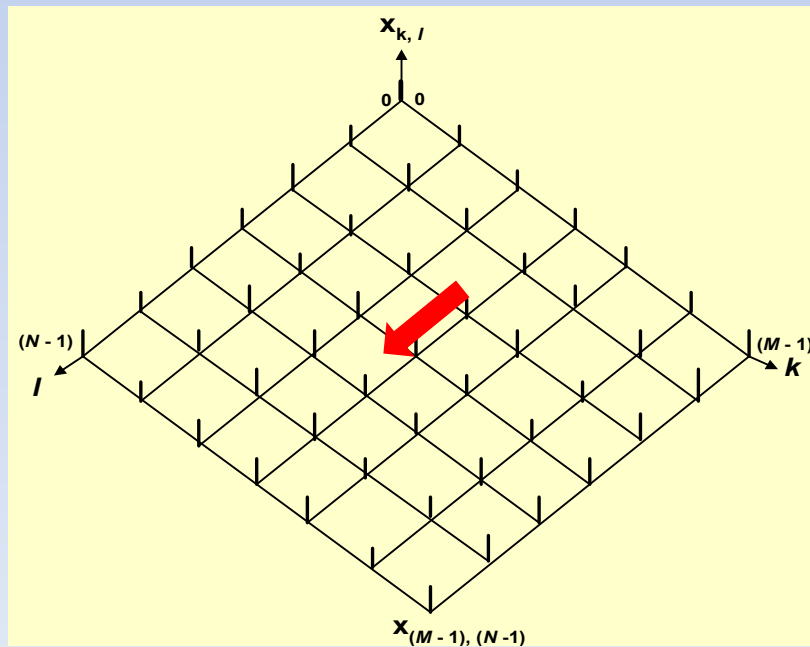


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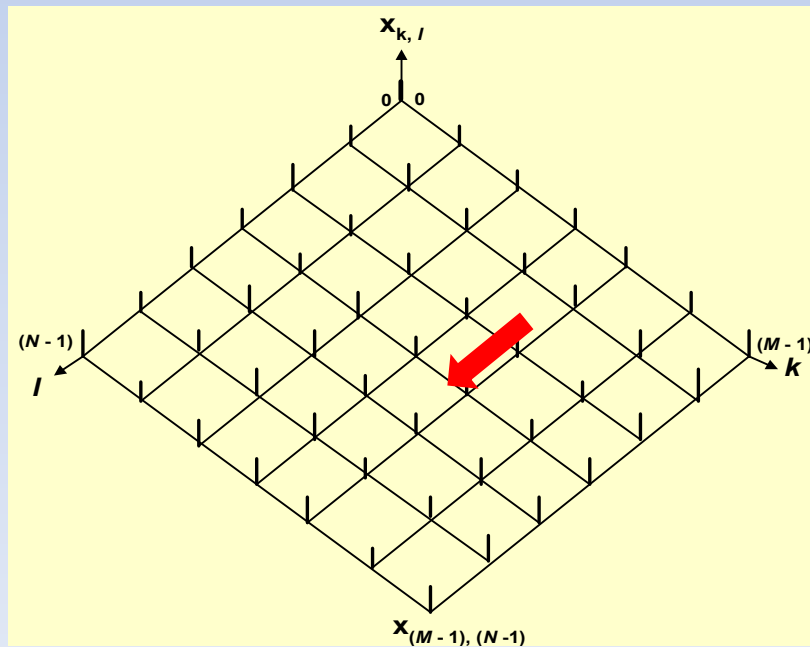


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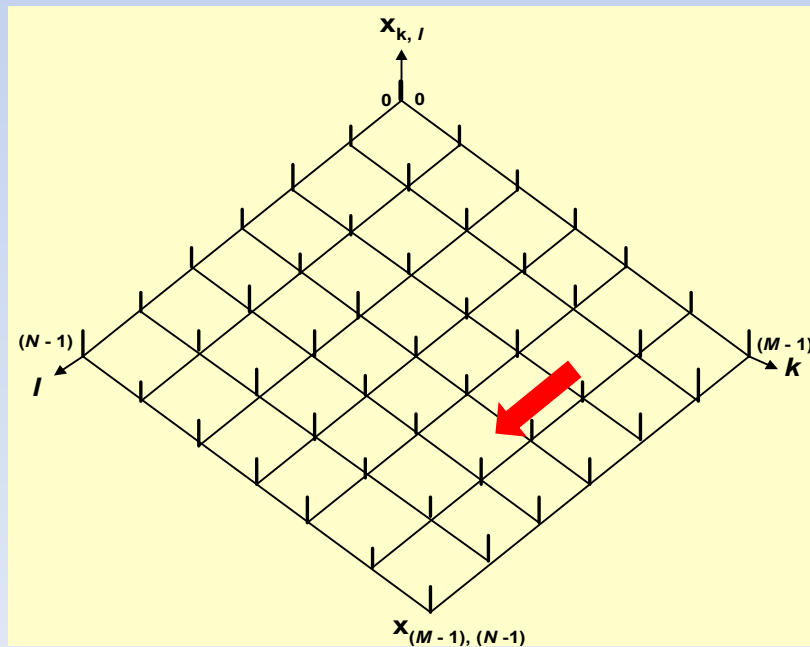


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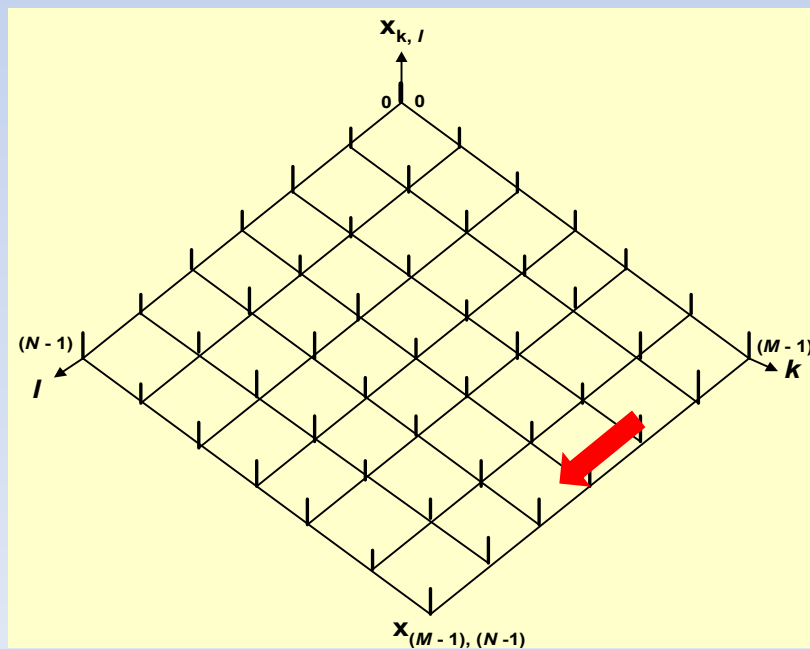


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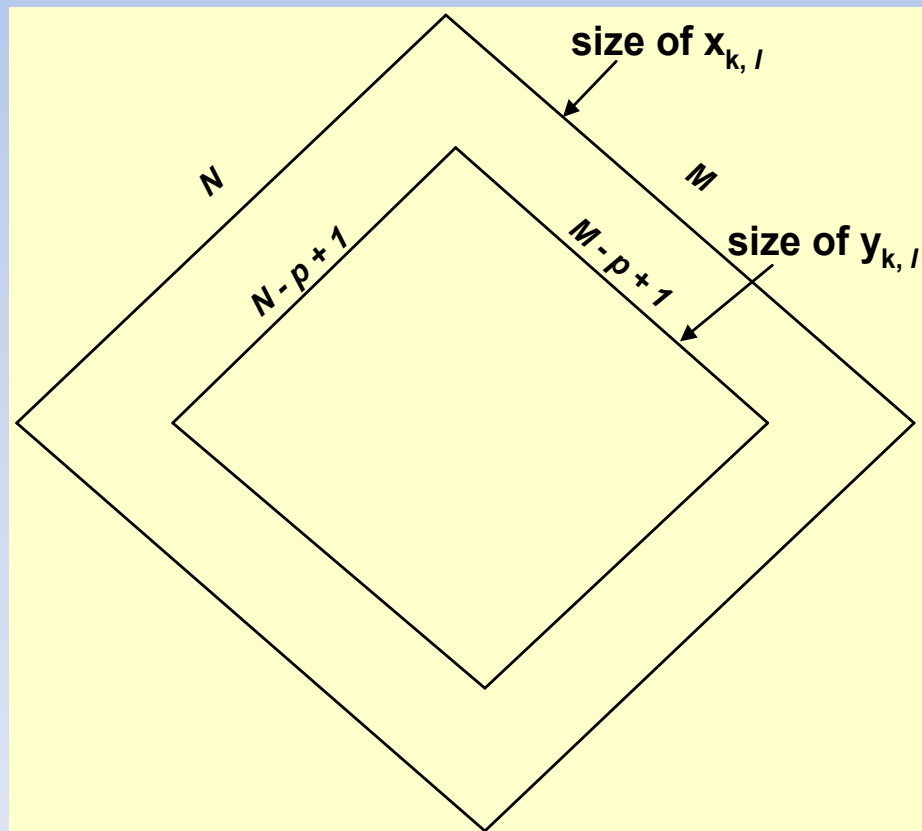
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# FIR digital filters for off-line analysis of 2-D data

Filter input-output space:



Thank You