

Dimensional Analysis.

The subject deals with the process where all the important parameters involved in a physical phenomena are systematically organized into dimensionless no.

$$(Eg: Re = \frac{\rho V d}{\mu})$$

Adv.:- ① No. of unknown quantities are reduced.

② The problem is generalised and need for specifying a particular system of units is eliminated. The eq^{ns} are true for any system

③ of units.

Importance:- These eq^{ns} are independent of geometry and thus it is useful for determining the structure performance of a prototype (A full scale model) from data obtained by tests on a model (a reduced-scale structure).

System of Dimensional:-

START

Engg problems are complex in nature. They are determined from experiment. Due to economic or other problem, the experiments can't be performed under identical condition.

Lab tests are carried out in altered condition of operating parameters from the actual one.

- (i) The test results are applied to actual problem (How??)
- (ii) Different variables are ~~etc~~ reduced to less no. of variables.

The soln. lies in physical similarity. By this the above two problems are solved.

So various test can be carried out by a scale model. [Example aeroplane, ship, performance of fluid machines like turbines, pump & propellers etc]

Test with one fluid & result applied with another fluid.

Type of physical similarity.

Prototype - Full sized structure of actual engs design. This operate under the

Objective & importance of model studies. involve model design & fabrication... and performance test on models and analysis.

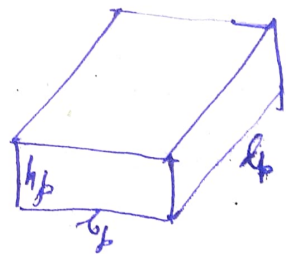
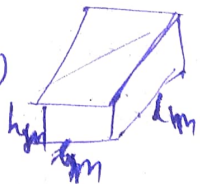
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Similitude → represents the theory of and art of predicting prototype conditions from model observation.

The result obtained from experiments on the models can be applied to the prototype only if a complete both flows follow same physics. And two systems are geometrically, kinematically & dynamically similar.

① Geometric similarity

$$\frac{l_m}{l_p} = \frac{b_m}{b_p} = \frac{h_m}{h_p} = l_r \quad (\text{seateratio})$$



Area ratio $A_r = \frac{A_m}{A_p} = \frac{l_m \cdot b_m}{l_p \cdot b_p} = l_r^2$

Volume ratio $V_r = l_r^3$

* Some times distorted model is used to keep the physics same. Example model of a river. Scale factor is different for length, width and height

Kinematic similarity :-

Vel ratio $V_r = \frac{V_m}{V_p} = \frac{L_m/T_m}{L_p/T_p} = \frac{L_r}{T_r}$ $T_r = \text{Time ratio.}$

Accⁿ $\frac{a_m}{a_p} = a_r = \frac{L_r}{T_r^2}$ $\frac{Q_m}{Q_p} = \frac{C_m^3/T_m}{L_p^3/T_p} = \frac{L_r^3}{T_r} = Q_r$

Dynamic similarity → Similarity of forces.

Ratio of particular forces are similar for both model and prototype.

The forces are viscous force F_v , Pressure force F_p , Gravity force F_g , Capillary force (due to surface tension) F_c , Compressibility force (force due to elasticity) F_e

Resultant force $F_R = F_v + F_p + F_g + F_c + F_e$
 $F_I \rightarrow$ inertia force equal & opposite to resultant force
 $F_R + F_I = 0$ or $\left(\frac{F_R}{F_I}\right) = 0$

$F_I \propto \text{mass} \times \text{acc}^n \propto \rho L^3 \times \frac{V}{T}$
 $\Rightarrow F_I \propto \rho L^3 \cdot \frac{V}{T} \propto \rho L^2 V^2 \Rightarrow F_I \propto \rho L^2 V^2$

$V = \frac{L}{T}$
 $T = \frac{L}{V}$

Viscous force F_v \propto shear stress \times area
 \propto vel grad $\rightarrow d^2$

$F_v \propto \mu \cdot \frac{V}{L} \cdot L^2$
 $\propto \mu V L$

Pressure force $F_p \propto (\Delta P) \cdot L^2$

Gravity force $F_g \propto mg$
 $\propto \rho L^3 g$

Capillary or surface tension force $F_c \propto \sigma L$

Elastic force $F_e \propto E \cdot L^2$

All the # ratios are with respect to inertia force which is common:

(1) $\frac{F_I}{F_v} = \frac{\rho V^2 L^2}{\mu V L} = \frac{\rho V L}{\mu} = Re$ Reynolds no.

(2) $\frac{F_p}{F_I} = \frac{\Delta P L^2}{\rho V^2 L^2} = \frac{\Delta P}{\rho V^2} = Eu$ Euler no.
 These are dynamic similarity governed by viscous pressure and inertia forces.

(3) $\frac{F_g}{F_I} = \frac{\rho L^3 g}{\rho V^2 L^2} = \frac{Lg}{V^2}$ } for flow governed by gravity pressure and inertia forces.

$\frac{V}{\sqrt{Lg}}$ is known as Froude no. $Fr = \sqrt{\frac{F_I}{F_g}}$

(4) $\frac{\text{Surface Tension force}}{\text{Inertia force}} = \frac{F_\sigma}{F_I} = \frac{\sigma}{\rho V^2 L} = We$ (Weber No)

Applicable when surface tension is dominant force.
 (i) capillary flow where capillary wave appear.
 (ii) Flow of small jets
 (iii) Flow of thin sheet of liquid over solid surface.

(5) $\text{Mach No} = \frac{\text{Inertia force}}{\text{Elastic Force}} = \frac{\rho V^2 L}{E_s L^2} = \frac{\rho V^2}{E_s} = Cauchy number$

Velocity of sound $(a) = \sqrt{E_s/\rho}$
 Austrian Physicist Ernst Mach

$\therefore \frac{\rho V^2}{E_s} = \frac{V}{E_s/\rho} = \frac{V}{a}$ $\frac{V}{a} = \text{Mach No} = \frac{V}{\sqrt{E_s/\rho}} = Ma$

Dynamic similarity of flows with elastic forces.

$E = \text{modulus of elasticity}$ $E_s = \text{isentropic bulk modulus of elasticity}$

Flow become compressible if $Ma > 0.3$

Situation:- Flow of air past high-speed aircraft, missiles, propellers and rotary compressors. In these cases Mach no. is a condition for

Dynamic similarity $\frac{V_p}{a_p} = \frac{V_m}{a_m}$

Prob: - A ship has a length of 150 m and wetted area of 3000 m². A model of this ship 5 m in length when towed in fresh water at 2 m/s produce resistance of 40 N. Calculate: (i) the corresponding speed of the ship (ii) The shaft power required to propel the ship at this speed through sea water (1030) take propeller $\eta = 75\%$.

(31)

The resistance R to the motion of ship is given by

$R = \rho v^2 l^2 f\left(\frac{\rho v l}{\mu}\right)$. For dynamic similarity the non-dimensional terms $R/\rho v^2 l^2$ and $\frac{\rho v l}{\mu}$ should be equal for model & prototype.

(i) $\frac{v_m \cdot l_m}{\nu_m} = \frac{v_p \cdot l_p}{\nu_p} \therefore v_p = v_m \cdot \frac{l_m}{l_p} = 2 \times \frac{5}{150} = \frac{1}{15} \text{ m/s}$

(ii) $\left(\frac{R}{\rho v^2 l^2}\right)_m = \left(\frac{R}{\rho v^2 l^2}\right)_p$

\therefore Ratio of the drag forces / resistance

$\frac{R_p}{R_m} = \frac{\rho_p}{\rho_m} \times \left(\frac{l_p}{l_m}\right)^2 \times \left(\frac{v_p}{v_m}\right)^2 = \frac{1030}{1000} \times \left(\frac{150}{50}\right)^2 \times \left(\frac{1}{15/2}\right)^2 = 1.03$

\therefore Drag force on the prototype $R_p = 1.03 \times R_m = 1.03 \times 40 = 41.2 \text{ N}$

Prob: A model of torpedo is tested in a towing tank at 26 m/s vel whilst the prototype is to run at 6.5 m/sec. (a) what model scale has been used? for water $\nu = 1.13 \times 10^{-6} \text{ m}^2/\text{sec}$.

(b) What would be model speed if tested in wind tunnel under a pressure of 2000 kPa and a constant temp of 27°C. Absolute ^{viscosity} vel. of air under these condition is 1.85×10^{-4} poise and Gas constant $R = 287 \text{ J/kgK}$.

Soln: Viscous effect predominant here,

$\therefore Re$ is significant ratio.

$\frac{v_m l_m}{\nu_m} = \frac{v_p l_p}{\nu_p}$

$\therefore \frac{l_m}{l_p} = \frac{v_m}{v_p} \times \frac{\nu_p}{\nu_m} = \frac{6.5}{26} = \frac{1}{4}$

\therefore model scale ratio = 1:4

(c) For air 2000 kPa and 27°C. $\rho = \frac{P}{RT} = \frac{2000 \times 10^3}{287(273+27)} = 23.23 \text{ kg/m}^3$

$\mu = 1.85 \times 10^{-4} \text{ poise} = 1.85 \times 10^{-5} \text{ N s/m}^2$

$\nu = \frac{\mu}{\rho} = \frac{1.85 \times 10^{-5}}{23.23} = 0.796 \times 10^{-6} \text{ m}^2/\text{s}$

$v_m = v_p \times \frac{l_p}{l_m} \times \frac{\nu_m}{\nu_p} = 6.5 \times 4 \times \frac{0.796 \times 10^{-6}}{1.13 \times 10^{-6}} = 18.32 \text{ m/s}$

Resistance R to the motion of a completely submerged body is given by $R = \rho V^2 L^2 f\left(\frac{VL}{\nu}\right)$ where ρ and ν are the kinematic viscosity of the fluid, L = length of body & V = flow velocity. If the resistance of $\frac{1}{8}$ th scale air ship model when tested in water at 12 mps in 200N, what will be the resistance of the air ship at the corresponding speed? Kinematic viscosity of air is 13 times that of water is 810 times that of air.

Ans:- From similarity consideration, the non-dimensional terms $R/\rho V^2 L^2$ and $\frac{VL}{\nu}$ should be same for prototype and its model.

$$\left(\frac{VL}{\nu}\right)_m = \left(\frac{VL}{\nu}\right)_p \Rightarrow V_p = V_m \times \frac{L_m}{L_p} \times \frac{\nu_p}{\nu_m} = 12 \times \frac{1}{8} \times 13 = 19.5 \text{ m/sec.}$$

$$\left(\frac{R}{\rho V^2 L^2}\right)_m = \left(\frac{R}{\rho V^2 L^2}\right)_p \quad R_p = R_m \cdot \frac{\rho_p}{\rho_m} \cdot \left(\frac{V_p}{V_m}\right)^2 \cdot \left(\frac{L_p}{L_m}\right)^2$$

$$= 200 \times \frac{1}{810} \times \left(\frac{19.5}{12}\right)^2 \times 8^2 = 41.73 \text{ N.}$$

The application of dynamic similarity and dimensional analysis.

~~Explain~~ Explain importance of ~~mass~~ ratio of forces and non-dimensional number like Re, Eu, Fr, We and Ma. etc.] These are Ob'

To change Re we can change any of the variables.

or $Re = \frac{\rho V D}{\mu}$

The above relations has been obtained by straight forward method. But sometimes it is very very difficult. Hence an alternative method of determining these dimensional dimensionless parameters are dimensional analysis

Explain the dimension of physical quantities.

Physical Quantity	Dimension	Dynamic Quantities	Dimension
Mass (m)	M	Density	ML^{-3}
Length (L)	L	Sf wt	$ML^{-2}T^{-2}$
Time (T)	T	Surface Tension σ	MT^{-2}
Force (F)	MLT^{-2}	Pressure p	$ML^{-1}T^{-2}$
Temp	θ	Mod. of Elasticity (E)	$ML^{-1}T^{-2}$
Area (A)	L^2	μ	$ML^{-1}T^{-1}$
Volume (V)	L^3	Resistive force	MLT^{-2}
Linear Vel (V)	LT^{-1}	Thrust	MLT^{-1}
Angular " (w)	T^{-1}	Torque/work	ML^2T^{-2}
Accn (a)	LT^{-2}	Energy	ML^2T^{-2}
Discharge (Q)	L^3T^{-1}	Power	ML^2T^{-3}
Gravity (g)	LT^{-2}		
Kinematic viscosity (v)	L^2T^{-1}		

The fundamental theory of dimensional analysis is based on the following axiom.

'Equations describing a physical phenomenon must be dimensionally homogeneous and the units therein must be consistent.'

i.e. dimension on the two sides of the eqn is identical.

$$T = 2\pi \sqrt{L/g} \quad [T] = [T] \left[\frac{L}{LT^{-2}} \right]^{1/2} = T$$

Dimensional Analysis - Buckingham's Pi-Theorem.

If there are n variables in dimensionally homogeneous equation and if these variables contain m primary dimensions, then the variables can be grouped into $(n-m)$ non-dimensional parameters.

The non-dimensional groups are called pi terms.

$$\text{Mathematically } f(x_1, x_2, x_3, \dots, x_n) = 0$$

where x 's are physical quantities (such as velocity, density, viscosity, pressure etc) pertinent to a physical phenomenon, then the same ~~phenomenon~~ ^{phenomenon} can be described by $(n-m)$ dimensional pi terms.

$$\phi(\pi_1, \pi_2, \dots, \pi_{n-m}) = 0$$

Here m represents the fundamental dimensions such as mass, length and time. [e.g. Force, length & time]

Experience shows that suitable non-dimensional groups results when a geometric property (e.g. length), a fluid property (e.g. density) and a flow characteristic (e.g. velocity) are chosen to represent such variables.

Ex:- Show by use of Buckingham's Pi-theorem that vel through an orifice is given by

$$v = \sqrt{2gH} f\left(\frac{D}{H}, \frac{\mu}{\rho v H}, \frac{\sigma}{\rho v^2 H}\right)$$

H = head, D = dia of orifice, μ = coeff of viscosity, ρ = density, σ = surface tension & g = accel due to gravity.

Soln:- It can be presumed the the functional relationship is

$$f(v, D, H, \rho, \mu, \sigma) = 0$$

There are 7 physical quantities and 3 fundamental units, hence $(7-3) = 4$ pi terms. Choosing density ρ , velocity v and head H as repeating variables with unknown exponents, the non-dimensional π terms can be as follows.

(i) $\pi_1 = \rho^{a_1} v^{b_1} H^{c_1} D$

$$M^0 L^0 T^0 = [M L^{-3}]^{a_1} [L T^{-1}]^{b_1} [L]^{c_1} [L]$$

Equating exponents we get $a_1 = 0$ $b_1 = 0$

$$-3a_1 + b_1 + c_1 + 1 = 0 \quad c_1 = -1$$

$$\therefore \pi_1 = H^{-1} \cdot D = \frac{D}{H}$$

(ii) $\pi_2 = \rho^{a_2} v^{b_2} H^{c_2} g$

$$M^0 L^0 T^0 = [M L^{-3}]^{a_2} [L T^{-1}]^{b_2} [L]^{c_2} [L T^{-2}]$$

$$a_2 = 0 \quad -3a_2 + b_2 + c_2 + 1 = 0 \quad -b_2 - 2 = 0$$

$$\downarrow \quad \Rightarrow b_2 = -2$$

$$c_2 = 1$$

$$\therefore \pi_2 = v^{-2} \cdot H \cdot g = \frac{gH}{v^2}$$

(iii) $\pi_3 = \rho^{a_3} v^{b_3} H^{c_3} \mu$

$$M^0 L^0 T^0 = [M L^{-3}]^{a_3} [L T^{-1}]^{b_3} [L]^{c_3} [M L^{-1} T^{-1}]$$

$$a_3 + 1 = 0 \quad -3a_3 + b_3 + c_3 - 1 = 0 \quad -b_3 - 1 = 0$$

$$a_3 = -1 \quad b_3 = -1 \quad c_3 = -1$$

$$\pi_3 = \rho^{-1} v^{-1} H^{-1} \mu = \frac{\mu}{\rho v H}$$

(iv) $\pi_4 = \rho^{a_4} v^{b_4} H^{c_4} \sigma$

$$[M^0 L^0 T^0] = [M L^{-3}]^{a_4} [L T^{-1}]^{b_4} [L]^{c_4} [M T^{-2}]$$

$$a_4 + 1 = 0 \quad -3a_4 + b_4 + c_4 - 2 = 0 \quad -b_4 - 2 = 0$$

$$a_4 = -1 \quad b_4 = -2, \quad c_4 = -1$$

$$\pi_4 = \rho^{-1} v^{-2} H^{-1} \sigma = \frac{\sigma}{\rho v^2 H}$$

∴ Functional relationship can then be written as

$$\phi \left[\frac{D}{H}, \frac{gH}{v^2}, \frac{\mu}{\rho v H}, \frac{\sigma}{\rho v^2 H} \right] = 0$$

$$\text{or } \frac{v^2}{gH} = \phi \left[\frac{D}{H}, \frac{\mu}{\rho v H}, \frac{\sigma}{\rho v^2 H} \right]$$

$$v = \sqrt{2gH} \phi \left[\frac{D}{H}, \frac{\mu}{\rho v H}, \frac{\sigma}{\rho v^2 H} \right]$$

Problem: The resisting force F of a supersonic plane during flight can be considered as dependent upon the length of aircraft l , velocity v , air viscosity μ , air density ρ and bulk modulus of elasticity k . Express the functional relationship between these variables and resisting force.

$$f(F, l, v, \mu, \rho, k) = 0 \quad \text{Ans:} \quad F = l v^2 \rho \phi \left(\frac{\mu}{\rho l v}, \frac{k}{\rho v^2} \right)$$

primaries $\rightarrow l, v, l$

Prob: The resistance R experienced by a partially submerged body depends upon the velocity v , length of the body l , viscosity of the fluid μ , density of fluid ρ and g . Obtain the dimensionless expression for R .

$$f(R, v, l, \mu, \rho, g) = 0 \quad \text{Ans:} \quad R = l^2 v^2 \rho \phi \left[\frac{\rho v l v}{\mu}, \sqrt{\frac{g}{v}} \right]$$

Prob: Derive on the basis of dimensional analysis suitable parameters to present the thrust developed by a propeller. Assume that the thrust T depend on the angular vel ω , speed of advance v , diameter D , dynamic viscosity μ , mass density ρ and elasticity of fluid medium which can be represented by the speed of sound c in the medium.

$$f(T, \omega, v, D, \mu, \rho, c) = 0 \quad \text{fundamental} \rightarrow \frac{V D \rho}{\mu}$$

$$T = v^2 D^2 \rho \phi \left[\frac{\mu}{V D \rho}, \frac{D \omega}{v}, \frac{c}{v} \right]$$

Prob: Show that Power P developed by a water turbine can be expressed as

$$P = \rho N^3 D^5 f \left[\frac{D}{B}, \frac{\rho D^2 N}{\mu}, \frac{ND}{\sqrt{gH}} \right]$$

D = Dia of runner
B = width of "

N = rpm H = operating head
 μ = dynamic viscosity
 ρ = density.

Soln: $f(P, \rho, N, D, B, \mu, H, g) = 0$

Fundamental ρ, D, N .
5 π terms.

Th

The pressure drop ΔP in a pipe of diameter D & length l depends on the density ρ , viscosity μ , mean vel. 'v' and average height of protuberance t.

Show that pressure drop can be expressed as $\Delta P = \rho v^2 f \left[\frac{l}{D}, \frac{\mu}{\rho v D}, \frac{t}{D} \right]$

The efficiency η of a fan depends on the density ρ , dynamic viscosity μ of the fluid, angular vel. ' ω ', dia D of the rotor and discharge Q. Express η in terms of dimensionless parameters.

* The pi terms can only determine the pertinent dimensionless groups describing the problem but not the exact functional relationship between them.

* Any π term can be replaced by its power. or can be multiplied by a numerical constant. (then can be other π)

Modeling & Similarity.

Ex:

Ex: A 5 cm diameter sphere is tested in water at 20°C and vel. of 3.5 m/s and has a measured drag of 6 N. Make calculations for vel and drag force of a 2 m dia weather balloon moving in air at 20°C and 1 atm under similar conditions:

Given: Viscosities air 1.86×10^{-5} Pa-s water 1.01×10^{-3} Pa-s

Densities = air 1.20 kg/m³ water 1000 kg/m³

Q) A one-sixth scale model automobile is tested in a wind tunnel in the same air properties as the prototype. The prototype automobile runs on the road at a vel. of ~~50 m/s~~ 50 km/hr. For dynamically similar conditions, the drag measured on the model is 300 N. Make calculations for the drag of the prototype and the power reqd. to overcome the drag.

Q) Re is predominant for fully immersed bodies

$$\therefore \left(\frac{V L \rho}{\mu} \right)_m = \left(\frac{V L \rho}{\mu} \right)_p$$

$$\Rightarrow V_p = V_m \cdot \frac{\rho_m}{\rho_p} \cdot \frac{L_m}{L_p} \cdot \frac{\mu_p}{\mu_m} = 3.5 \times \frac{1000}{1.2} \times \frac{0.05}{2} \times \frac{1.86 \times 10^{-5}}{1.01 \times 10^{-3}}$$
$$= 1.346 \text{ m/sec.}$$

Further, for dynamic similarity the parameter $R/\rho V^2 L^2$ should be same for model & prototype.

$$\therefore \left[\frac{R}{\rho V^2 L^2} \right]_p = \left[\frac{R}{\rho V^2 L^2} \right]_m$$

$$R_p = R_m \cdot \left(\frac{\rho_p}{\rho_m} \right) \cdot \left(\frac{V_p}{V_m} \right)^2 \cdot \left(\frac{L_p}{L_m} \right)^2 = 6 \times \frac{1.20}{1000} \times \left(\frac{1.346}{3.5} \right)^2 \times \left(\frac{2}{0.05} \right)^2$$
$$= 1.704 \text{ N.}$$

Q) Speed of prototype automobile = 50 km/hr.
 $= 50/3.6 = 13.89$ m/s.

The resistance R to the motion of a completely submerged body is given by $R = \rho V^2 L^2 \phi \left(\frac{\rho V L}{\mu} \right)$

For similarity conditions the non-dimensional

Terms $R/\rho v^2 L^2$ and $\rho v L/\mu$ should be same for the prototype and the model.

(39)

$$\therefore V_m = V_p \times \frac{L_p}{L_m} \times \frac{\rho_p}{\rho_m} \times \frac{\mu_m}{\mu_p} \quad [\mu + \rho \text{ is same}]$$

$$= 13.89 \times 6 = 83.34 \text{ m/s.}$$

$$\begin{aligned} \text{(ii)} \quad R_p &= R_m \cdot \left(\frac{\rho_p}{\rho_m}\right) \times \left(\frac{V_p}{V_m}\right)^2 \times \left(\frac{L_p}{L_m}\right)^2 \\ &= 300 \times (1) \times (13.89/83.34)^2 \times 6^2 = 300 \text{ N.} \end{aligned}$$