

Fluid Dynamics.

It is the study of fluid motion that involves forces of action and reaction. [i.e forces causing accⁿ or decⁿ]

Dynamics of fluid motion is governed by the Euler equation (momentum principle) and ~~Bernoulli's~~ Bernoulli's eqⁿ (energy principle). These momentum and energy principals are derived from Newton's 2nd law of motion. [F=ma].

Concepts

- * System - fixed man, system boundary flexible.
- * Control volume - fixed volume in space bounded by the control surface. Some part of C.V is physical boundary and others are called cross section (c/s).

Energy and its forms.

Energy represents the capacity to produce a change in existing system i.e. capacity to do work.

Energy of a system :- ① Stored ^{energy} like K.E, PE and internal energy and
 ② Energy in transit:- Heat & Work.

* P.E. on datum energy $\rightarrow = mgZ$.

* K.E. $\rightarrow dF = m \cdot \frac{dv}{dt}$
 $\delta W = dF \cdot ds = m \cdot \frac{dv}{dt} \cdot ds = m \cdot v \cdot dv$.

$$W = m \int v \cdot dv = \frac{1}{2} m v^2$$

Internal energy - Energy stored within the system due to spacing in fluid molecules.

If comprises of K.E. due to molecular agitation and P.E. due to attractive and repulsive forces between the molecules or atoms constituting the fluid mass.

Heat & Work

Flow work - is a measure of the work required to push a fluid mass across the control surface at the entrance and exit cross-section.

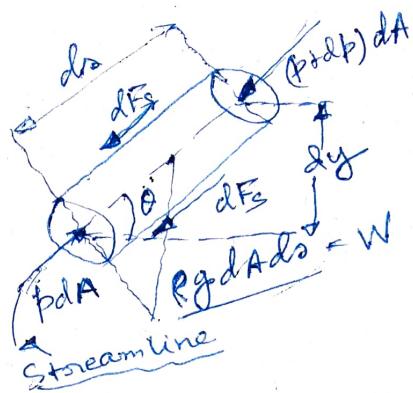
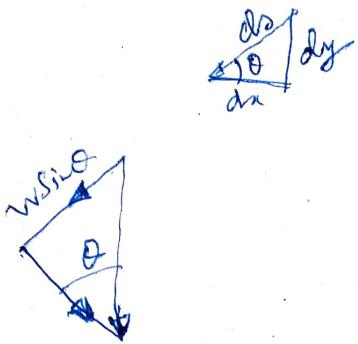
$$\text{Flow work} = \text{force} \times \text{displacement}$$

$$= p_1 A_1 V_1 dt$$

$$= p_1 V_1 dt \quad V_1 = \text{Vol.} \quad \overbrace{V_1 = \frac{\partial}{\partial t}}^{\rightarrow V_1 = \frac{dV}{dt}}$$

$$\therefore \frac{\text{Flow work}}{\text{unit time} \times \text{unit mass}} = p_1 \rho_1 \times \frac{p_1}{\rho_1}$$

(83) Euler Equation along a streamline



Euler's equation applies Newton's 2nd law of motion.
Element of fluid moving within a stream tube.
Elemental area dA .

Normal force p is at upstream & $p+dp$ in the downstream.
Net pressure force acting on the element,
 $p dA - (p+dp) dA = -dp \cdot dA$.

Tangential force \rightarrow due to viscous shear.

$$dF_S = \gamma \cdot dP \cdot ds$$

γ = shear stress.

dP = perimeter.

$dP \cdot ds$ = total area of
the streamtube.

The sum of all shear force is a measure of energy loss due to friction.

Body force: $= Rg \cdot dA \cdot dy$.

The resulting force is $=$ mass \times accn.

$$-dp dA - Rg \cdot dA \cdot dy - \gamma \cdot dP \cdot ds = R \cdot dA \cdot ds \cdot \frac{du}{ds}$$

Now $ds = \frac{\partial u}{\partial t} + u \cdot \frac{\partial u}{\partial x}$ [Since ~~2D~~ one dimensional]

For steady flow $\frac{\partial u}{\partial t} = 0$, $\therefore ds = u \cdot \frac{du}{ds}$ [Since 1-D]

$$\therefore -dp dA - Rg \cdot dA \cdot dy - \gamma \cdot dP \cdot ds = R \cdot dA \cdot u \cdot \frac{du}{ds}$$

Dividing throughout by the fluid mass $R dA ds$

$$\text{give } u \cdot \frac{du}{ds} + \frac{p}{R} \cdot \frac{dp}{ds} + g \cdot \frac{dy}{ds} = - \frac{\gamma}{R} \frac{dP}{dA}$$

[This is Euler equation of motion]

i) $u \frac{du}{ds}$ is a measure of convective accn. as it moves from one region to another region of different velocity. It is a measure of K.E.

ii) $\frac{1}{\rho} \cdot \frac{dp}{ds}$ - force/unit mass caused by pressure distribution.

iii) $g \cdot \frac{dy}{ds}$ gravitational force per unit mass.

iv) $-\frac{\gamma}{\rho} \cdot \frac{dp}{ds} \rightarrow$ force/unit mass caused by friction.

for ideal fluid $\gamma = 0$

\therefore The eqⁿ reduces to $u \cdot du + \frac{dp}{\rho} + g dy = 0$

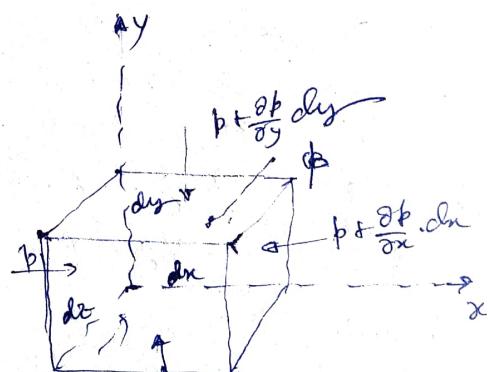
The above equations have been set up considering flow within a stream tube.

Euler's Equation in Cartesian Co-ordinates.

① Net pressure force in

x -direction

$$= f \cdot dy \cdot dz - \left(p + \frac{\partial p}{\partial x} \cdot dx \right) dy \cdot dz \\ = - \frac{\partial p}{\partial x} \cdot dx \cdot dy \cdot dz.$$



② Body force - Let R

be the body force per

unit mass of fluid having component X, Y, Z in x, y, z directions respectively.

Body force along x -direction $\times P \cdot dy \cdot dz$

* Inertia force

Along x -co-ordinate the inertia force is

mass \times acceleration $= \rho \cdot dx \cdot dy \cdot dz \cdot \frac{d^2 u}{dt^2} \left(\frac{DU}{DT} \right)$

$\therefore X P \cdot dy \cdot dz - \frac{\partial p}{\partial x} \cdot dx \cdot dy \cdot dz = \rho \cdot dx \cdot dy \cdot dz \cdot \frac{d^2 u}{dt^2} \left(\frac{DU}{DT} \right)$

$$\therefore X - \frac{1}{\rho} \cdot \frac{\partial p}{\partial x} = \frac{du}{dt} \left[\text{each term is force per unit mass i.e. accn.} \right]$$

$$\therefore X - \frac{1}{\rho} \cdot \frac{\partial p}{\partial x} = \frac{\partial u}{\partial t} + u \cdot \frac{\partial u}{\partial x} + v \cdot \frac{\partial u}{\partial y} + w \cdot \frac{\partial u}{\partial z}$$

Similarly

$$Y - \frac{1}{\rho} \cdot \frac{\partial p}{\partial y} = \frac{\partial v}{\partial t} + u \cdot \frac{\partial v}{\partial x} + v \cdot \frac{\partial v}{\partial y} + w \cdot \frac{\partial v}{\partial z}$$

$$Z - \frac{1}{\rho} \cdot \frac{\partial p}{\partial z} = \frac{\partial w}{\partial t} + u \cdot \frac{\partial w}{\partial x} + v \cdot \frac{\partial w}{\partial y} + w \cdot \frac{\partial w}{\partial z}$$

$$\boxed{\frac{\partial V}{\partial t} + \vec{V} \cdot \vec{\nabla} (\vec{V} \cdot \vec{V}) = -\frac{1}{\rho} \nabla \cdot \vec{p} + (X+Y+Z) \vec{k}} \rightarrow \text{Euler eqn.}$$

{ Each term is accn
i.e. force/unit mass }

Considering the flow steady & multiplying with dx , dy & dz respectively we get

$$X dx - \frac{1}{\rho} \frac{\partial p}{\partial x} dx = u \cdot \frac{\partial u}{\partial x} dx + v \cdot \frac{\partial u}{\partial y} dx + w \cdot \frac{\partial u}{\partial z} dx$$

$$Y dy - \frac{1}{\rho} \frac{\partial p}{\partial y} dy = u \cdot \frac{\partial v}{\partial x} dy + v \cdot \frac{\partial v}{\partial y} dy + w \cdot \frac{\partial v}{\partial z} dy$$

$$Z dz - \frac{1}{\rho} \frac{\partial p}{\partial z} dz = u \cdot \frac{\partial w}{\partial x} dz + v \cdot \frac{\partial w}{\partial y} dz + w \cdot \frac{\partial w}{\partial z} dz$$

Energy
per
unit
mass

For a streamline $\frac{dx}{u} = \frac{dy}{v} = \frac{dz}{w}$

$$\therefore u dy = v dx ; v dz = w dy ; u dz = w dx$$

$$\Rightarrow X dx - \frac{1}{\rho} \frac{\partial p}{\partial x} dx = \frac{1}{2} u \cdot \frac{\partial u}{\partial x} dx + u \cdot \frac{\partial u}{\partial y} dy + v u \cdot \frac{\partial u}{\partial z} dz$$

$$u \cdot \frac{\partial u}{\partial x} = \frac{1}{2} \frac{\partial u^2}{\partial x}$$

$$\therefore X dx - \frac{1}{\rho} \frac{\partial p}{\partial x} dx = \frac{1}{2} \left[\frac{\partial}{\partial x} (u^2) dx + \frac{\partial}{\partial y} (u^2) dy + \frac{\partial}{\partial z} (u^2) dz \right] = \frac{1}{2} d(u^2)$$

$$Y dy - \frac{1}{\rho} \frac{\partial p}{\partial y} dy = \frac{1}{2} d(v^2)$$

$$Z dz - \frac{1}{\rho} \frac{\partial p}{\partial z} dz = \frac{1}{2} d(w^2)$$

$$\begin{aligned} \text{Addig } X dx + Y dy + Z dz - \frac{1}{\rho} \left(\frac{\partial p}{\partial x} dx + \frac{\partial p}{\partial y} dy + \frac{\partial p}{\partial z} dz \right) \\ = \frac{1}{2} d(u^2) + \frac{1}{2} d(v^2) + \frac{1}{2} d(w^2) \end{aligned}$$

~~∴ $(X+Y+Z) = \frac{1}{\rho} \cdot dp$~~

$$X dx + Y dy + Z dz - \frac{1}{\rho} \cdot dp = \frac{1}{2} d(V^2)$$

* If $X = 0 = Z$, $Y = -g$ for static fluid $V=0$

$$-g dy - \frac{1}{\rho} dp = 0 \Rightarrow dp = -\rho g dy = -\rho g dy$$

$$V^2 dp = -\rho g dy \cdot \rho dy = -\rho g (y_2 - y_1) = \rho g (y_1 - y_2)$$

(89)

Bernoulli's Theorem: Integration of Euler's equation for 1 D flow.

It relates velocity, pressure and elevation changes of a fluid in motion.

$$\frac{1}{2} \frac{dV^2}{\rho} + \frac{dp}{\rho} + g dy = 0$$

$$\int \frac{1}{2} dV^2 + \frac{dp}{\rho} + g dy = \text{constant}$$

$$\therefore \frac{V^2}{2} + \frac{p}{\rho} + gy = \text{constant} \Rightarrow \text{Bernoulli's eqn}$$

[Swiss mathematician
Daniel Bernoulli
(1700 - 1782)]

The constant of integration varies from streamline to streamline but ~~not~~ remain constant along a streamline for a steady incompressible and frictionless flow.

~~Design~~ The unit of above eqn is $\frac{\text{N.m}}{\text{kg}}$ i.e. energy per unit mass.

On dividing by ~~g~~ g we get

$$\frac{p}{\rho} + \frac{V^2}{2g} + y = \text{H} \Rightarrow \text{energy per unit width} \left(\frac{\text{m.N}}{\text{m}} \right).$$

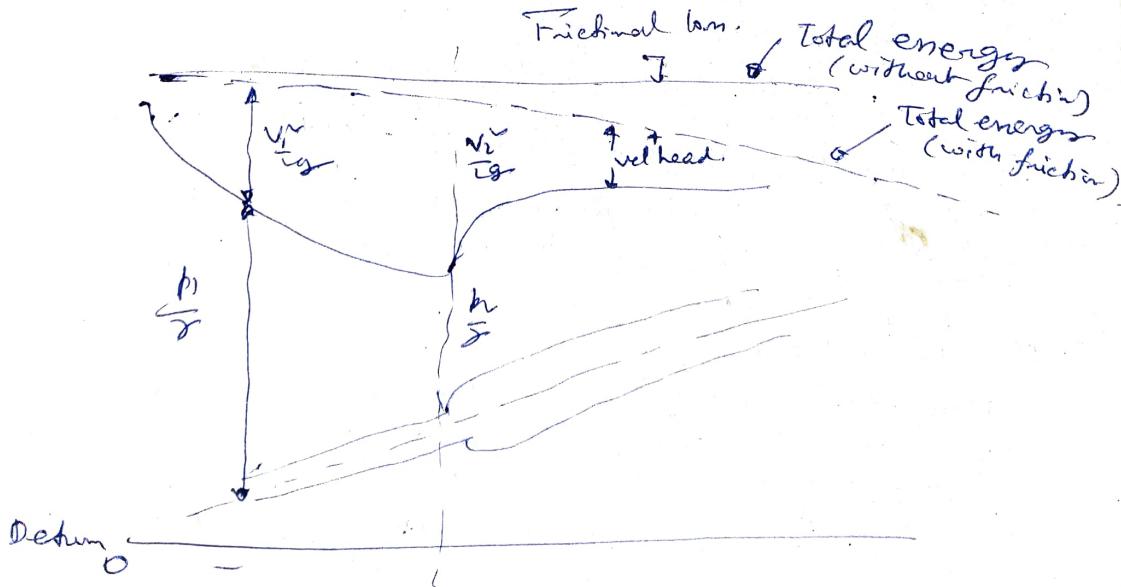
and has physical dimension of length · (m)

$\frac{V^2}{2g}$ = velocity head, $\frac{p}{\rho}$ = pressure head or static head.

y = elevated head, position head, potential head,

the sum of H = total or hydrodynamic head.

[It is sum of ~~ref~~, ~~ki~~ potential, kinetic and pressure energy.]



Bernoulli's eqn can also be written as

$$P + \frac{V^2}{2} + \rho + \gamma y = \text{Constant.}$$
 each for $\frac{\text{N.m}}{\text{m}^3}$

[This form is applied to gas flow]

Assumptions of Bernoulli's eqn.

- ① Flow is steady, incompressible, and I-D,
- ② Flow is continuous and velocity is,
- ③ Fluid is ideal,
- ④ Only gravity and pressure forces are present. [i.e. no energy from Heat or work]

[The eqn holds for frictionless (inviscid) and constant density fluid. The flow must be steady and the relation holds for single streamline]

For gases density is very small. Hence variation of gz is much less compared to $\frac{p}{\rho}$ and hence.

$$\text{the eqn becomes } \frac{p}{\rho} + \frac{u^2}{2} = \text{constant}$$

$$p + \frac{\rho u^2}{2} = \text{constant.}$$

The term $\frac{u^2}{2}$ represents kinetic energy of a fluid per unit mass. gz represents the static energy due to change in elevation.

$\frac{p}{\rho}$ corresponds to the work that would be done by the pressure force if fluid is moved from a pt. where the pressure is p to one where the pressure is zero.

KE Correction factors

The discharge through a small element of dA is $\rho u dA$. The KE passes through the element is $\frac{1}{2} (\rho u dA) u^2$ for the whole dA is $\frac{1}{2} \rho u^3 dA$ & total mass flow rate $\rho u dA$. If u is constant.

Now. KE per unit mass = $\frac{\frac{1}{2} \rho u^3 dA}{\rho u dA}$

(91)

If ρ is const. then if $\int \rho u^3 dx$
 Unless u is const. over entire pipe then this exp doesn't
 not corresponds to $\frac{1}{2} \rho u^2$

$$\therefore \alpha = \frac{1}{A} \int \frac{\rho u^3}{\rho} dA. *$$

SSSF

$$m_1 \left(p_1 + \rho_1 u_1 + \frac{\rho_1 v_1^2}{2} + g y_1 + q \right)$$

$$= m \left(p_2 + \rho_2 u_2 + \frac{\rho_2 v_2^2}{2} + g y_2 + q \right)$$

$$m_1 = m_2$$

$$u_1 = u_2 \rightarrow \text{no frictional loss} \quad w=0 \quad q=0$$

$$\rho_1 = \rho_2 \text{ (incompressible)}$$

$$\frac{p_1}{\rho_1} + \frac{\rho_1 v_1^2}{2} + g y_1 = \frac{p_2}{\rho_2} + \frac{\rho_2 v_2^2}{2} + g y_2 \Rightarrow \left(\frac{p}{\rho} + \frac{v^2}{2} + g y \right) = c$$

$$\therefore \left(\frac{p}{\rho} + \frac{v^2}{2g} + g y \right) = \text{constant}$$

Problem: A pipe of 12.5 cm in diameter is used to transport oil of relative density 0.75 under a pressure of 1 bar. If the total energy relative to a datum plane 2.5 m below the centre of the pipe is 20 Nm/N, work out the flow rate of oil.

$$\text{Ans: } 20 = \frac{v^2}{2g} + \frac{p}{\rho g} + gy = \frac{v^2}{2 \times 9.81} + \frac{1 \times 10^5}{0.75 \times 9.81} + 2.5$$

$$v = \sqrt{2 \times 9.81 \times 3.91} = 8.76$$

$$\text{discharge } Q = AV = \frac{\pi}{4} \times (0.125)^2 \times 8.76 = 0.1074 \text{ m}^3/\text{s.}$$

$$* \alpha = K_E \text{ correction factor} = \frac{1}{A} \int \frac{v^3}{\rho} dA.$$

$$\text{Actual } K_E F = \alpha \frac{v^2}{2}. \quad \therefore \alpha = \frac{K_E F}{\frac{v^2}{2}}$$

α can never be less than unity.

A pump delivers water through a ~~thin~~ 150 mm dia pipe. Inlet A, 225 m dia $\Rightarrow \bar{V} = 1.35 \text{ m/s}$. $P_{\text{abs}} = 150 \text{ Hg vacuum}$. The pump outlet B is 600 mm above A and 150 mm dia. At C, 5 m above B the gauge pressure = 35 kPa. If friction in pipe BC is 2.5 kW (dissipation) and power reqd to drive the pump is 12.7 kW, calculate overall η of the pump.

$$\text{at A } V_A = 1.35 \text{ m/s. } U_B = V_C = V_A \times \frac{\text{Area A}}{\text{Area C}} \\ = 1.35 \times \frac{(225)^2}{(150)^2} = 3.038 \text{ m/sec.}$$

$$-\frac{P_A}{\rho} + \frac{1}{2} V_A^2 + g Z_A + \frac{\text{Energy added to pump/time}}{\text{Unit mass/time}} \\ - \frac{\text{Energy lost/time}}{\text{Unit mass/time}} = \frac{P_e}{\rho} + \frac{1}{2} V_e^2 + g Z_e.$$

67-27.

Momentum of fluid in motion (Impulse-momentum)

$$F = \frac{d}{dt}(mv) = m \cdot \frac{dv}{dt} + v \cdot \frac{dm}{dt} \underset{\text{0}}{=} m \cdot \frac{dv}{dt}$$

"The time rate of change in momentum is proportional to the impressed force and takes place in the direction in which the force acts."

$F dt$ represents impulse of applied force.

Application:

- 1) Force on pipe bends and transitions.
- 2) Force exerted by a fluid jet striking against fixed or moving blades.
- 3) Force on propeller blades.
- 4) Jet Propulsion
- 5) To calculate head loss

mass within $a'a' & b'b' = cdcd'$

$$\bullet = \rho_1 A_1 dt_1 = \rho_2 A_2 dt_2$$

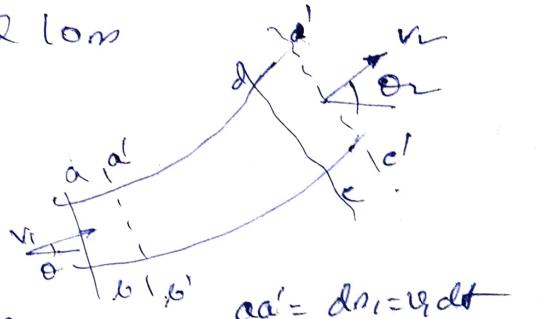
\therefore changing momentum

$$= (\rho_2 A_2 v_2 dt) v_2 - (\rho_1 A_1 v_1 dt) v_1$$

$$= \rho Q (v_2 - v_1) dt$$

$$F dt = \rho d (v_2 - v_1) dt$$

$$F = \rho \frac{dQ}{dt} (v_2 - v_1) \cdot \frac{dg}{g} = \rho Q = \underline{\text{mass flux.}}$$



$$\therefore F_x = \frac{\rho g}{g} (v_2 \cos \theta - v_1 \cos \theta)$$

$$F_y = \frac{\rho g}{g} (v_2 \sin \theta - v_1 \sin \theta)$$

Force exerted by the fluid on the pipe bend.

$$F_x = \frac{\rho g}{g} (v_1 \cos \theta - v_2 \cos \theta)$$

$$F_y = \frac{\rho g}{g} (v_1 \sin \theta - v_2 \sin \theta)$$

$$\text{Total } F_x = \frac{\rho g Q}{w} (v_1 \cos \theta - v_2 \cos \theta) + A_1 A_2 \cos \theta ; \\ - \rho A_2 \cos \theta$$

Force exerted by the pipe bends on the fluid.

Bernoulli's eqn with Head loss

Head loss occurs mainly due to friction while fluid flows through a pipe or duct. This can be represented in modified Bernoulli's eqn as.

$$\frac{P_1}{\rho g} + \frac{V_1^2}{2g} + z_1 = \frac{P_2}{\rho g} + \frac{V_2^2}{2g} + z_2 + h_f$$

where h_f represents the frictional work done per unit weight of a fluid element while flowing from ft 1 to ft 2. It is basically the loss of total mechanical energy.

For inviscid fluid h_f or $h_L = 0$

Total head loss in a pipe or duct system

$$h_L = \sum h_{\text{major losses}} + h_{\text{minor losses}}$$

$$= f \cdot \frac{L}{D_h} \cdot \frac{V^2}{2g} + \sum k \cdot \frac{V^2}{2g}$$

L = length of duct (m)

f = friction coefficient

V = flow velocity (m/s)

g = acceleration due to gravity (m/s²)

D_h = hydraulic diameter

$$= \frac{4A}{P}$$

A = area (m²)

of duct cross

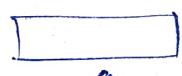
P = wetted perimeter (m)

$$\text{For circular pipe } D_h = \frac{4 \cdot \pi D^2}{\pi D^2} = 4D \quad \textcircled{O}$$

$$\text{For annulus } D_h = \frac{4(\pi D_o^2 - \pi D_i^2)}{\pi D_o + \pi D_i} = (D_o - D_i). \quad \textcircled{O}$$

For rectangular ~~Tube~~ Duct

$$D_h = \frac{4ab}{2(a+b)} = \frac{2ab}{(a+b)}$$



The hydraulic diameter is not same as equivalent diameter. It is the diameter of a pipe that give same pressure loss as a rectangular duct.

Major loss occur due to friction. This depend on flow velocity, pipe or duct length, pipe dia and a friction factor based on roughness of the pipe and type of flow (flow is laminar or turbulent).

$f = f \cdot \frac{L}{D_h} \frac{v^2}{2g} \rightarrow$ known as Darcy - Weisbach eqn. and valid for steady fully developed incompressible flow.

$$\frac{p_1}{\rho g} + \frac{\gamma v_1^2}{2g} + y_1 = p_2/\rho + \frac{h_2^2}{2g} + y_2 + h_{loss}.$$

$$\text{if } v_1 = v_2 \text{ & } y_1 = y_2$$

$$\text{then } h_{loss} = \frac{p_1}{\rho g} - \frac{p_2}{\rho g} = \frac{1}{2}(\rho v - \rho v) = \frac{h_{loss}}{f_{D_h}} - h_{frap}$$

friction coefficient = $64/Re$ for laminar flow.

$$\therefore Re < 2300.$$

for transition flows, $2300 < Re < 4000$ the flow varies between laminar & turbulent flow and friction factor cannot be determined.

For turbulent flow, f depends on Re and roughness of duct or pipe wall:

$$f = f(Re, \frac{\epsilon}{D_h}) \quad \epsilon = \text{roughness and } D_h = \text{hydraulic dia.}$$

$\frac{\epsilon}{D_h}$ = relative roughness.

Relative roughness is determined by the experiment and expressed in m.

The friction factor can be determined by Colebrook Equation

$$\frac{1}{f_{D_h}} = -2 \log_{10} \left[(2.51 / (Re f^{1/4})) + \frac{\epsilon}{D_h} / 3.72 \right]$$

A graphical representation of the above eqn is known as Moody diagram.