M.TECH DISTRIBUTED AND MOBILE COMPUTING FIRST YEAR SECOND SEMESTER 2019

DISTRIBUTED OPERATING SYSTEMS

Time: Three hours Full Marks: 100

Answer any *five* from the following questions. Each question carries twenty marks.

Make your answer brief and to-the-point.

- a) What is distributed operating system (DOS)? Name various kinds of DOS that exist
 in literature and compare them with respect to degree of transparency, underlying
 hardware (homogeneous or heterogeneous), number of OS, basis for communication
 and scalability.
 - b) Write down the advantages and disadvantages of *distributed systems* (DS) over the centralized systems. What is the difference between a *multiprocessor* and a *multicomputer*?
 - c) A bus-based multiprocessor uses snoopy caches to achieve a coherent memory. Will semaphore work on this machine?

(2+6)+(6+3)+3

- a) Describe the Lamport's algorithm for achieving total ordering of various events in a
 distributed system (DS). Are the time values assigned to events necessarily close to actual
 physical time? Justify your answer.
 - b) What is mutual exclusion? Describe the Ricart and Agrawala's algorithm for achieving mutual exclusion in a DS.
 - c) A DS may have multiple, independent critical regions (CR). Imagine that process 0 wants to enter CR A and process I wants to enter CR B. Can Ricart and Agrawala's algorithm lead to deadlocks? Explain your answer.

(5+2) + (1+8) + 4

a) How a transaction is represented and executed in a distributed system?
 b) Define well-formed transaction and two-phase transaction. Consider the following transaction T1 and define it in well-formed two-phase form.

T1:begin_transaction read(x); read(y); write(x-5); write(y+5); end transaction.

c) Prove that if { T1, T2,, Tm} is a set of well-formed and two-phase transactions, then any legal schedule is equivalent to a serial schedule.

3 + (2+3) + 12

- a) Describe a distributed periodic deadlock detection algorithm. Prove that global deadlock will be detected by some site if that distributed periodic deadlock detection is followed.
 - b) What is *phantom deadlock*? Illustrate it with an example. How it can be prevented to occur?

(8+4) + (5+3)

5. a) "The choice of lockable object or granularity of the database, presents a trade off between increased concurrency and system overhead" – explain. Define three different intention locking modes that are introduced to increase concurrency in a distributed system and also show compatibility among these three locking modes.
b)Describe the two-phase commit protocol. What happens if COMMIT Coordinator crashes after successful write of a COMMIT record but before writing a COMPLETE record?

(3+3+2) + (10+2)

- 6. a) Specify one major limitation of bus-based multiprocessor? What alternative system design has been proposed in literature to overcome it?
 - b) Describe the cache consistency protocol adopted by **Dash**. A **Dash** system has **B** bytes of memory divided over **m** clusters. Each cluster has **n** processors in it. The cache block size is **c** bytes. Give a formula for the total amount of memory devoted to directories (excluding the two state bits per directory entry).
 - c) Write down the differences between UMA multiprocessor and NUMA multiprocessor. (1+4) + (8+4) + 3
- a) What are the advantages of adistributed shared memory (DSM) system over a distributed system? Write down the basic design principle of page-based DSM.
 - b) Although use of replicated pages among the processors can improve the performances of the page-based DSMs, but if a process attempts to write on a replicated page, a potential consistency problem arises - explain it. Describe a suitable protocol to overcome this consistency problem.
 - c) Write down the page replacement algorithm followed by DSM systems.

(2+4) + (3+6) + 5