

(4)

Ex./M.Sc./M/1.4/32/2019

- (b) In a dynamical system with two degrees of freedom, the K. E. and P. E. are given by where

$$T = \frac{\dot{q}_1^2}{2(a+bq_2)} + \frac{1}{2}q_2^2 \dot{q}_2^2, V = c + dq_2$$

where a, b, c and d are constants. Show that the value of q_2 in terms of time is given by the equation of the form

$$(q_2 - k)(q_2 + 2k)^2 = h(t - t_0)$$

with h, k and t_0 as constants. 5+5

7. (a) Establish Hamilton's principle from D'Alembert's principle.
(b) Two heavy uniform rods AB and AC each of mass M and length 2a are hinged at A and placed symmetrically over a smooth cylinder of radius 'c' whose axis is horizontal. If they are slightly and symmetrically displaced from the position of equilibrium, show that the time of small oscillation is

$$2\pi \sqrt{\frac{a \sin \alpha}{3g} \left(\frac{1+3 \sin^2 \alpha}{1+2 \sin^2 \alpha} \right)}$$

where $a \cos^3 \alpha = c \sin \alpha$. 5+5

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MASTER OF SCIENCE EXAMINATION, 2019

(1st Year, 1st Semester)

MATHEMATICS

General Mechanics

Unit - 1.4

Time : Two hours

Full Marks : 50

The figures in the margin indicate full marks
(Symbols have their usual meaning)

Answer any *five* questions.

1. (a) State the Liouville's form for a dynamical system.
(b) The K. E. and P. E. of a particle moving in a plane are given by

$$2T = \dot{x}^2 + \dot{y}^2, V(r) = -\frac{\mu}{r} - \frac{\mu^1}{r^1}$$

where r, r^1 are the distances of the particle from the points (c,0) and (-c,0) respectively. Show that the problem can be formulated in Liouville's form. 3+7

(Turn over)

(2)

2. Show that the K. E. of a moving system can be expressed as

$$T = \frac{1}{2} \sum_{i,j} a_{ij} \dot{q}_i \dot{q}_j + \sum_i b_i \dot{q}_i + C$$

If for a scleronomic system $T'(q,p)$ is what T becomes when expressed in terms of variables q and p , then prove that

(i) $\dot{q}_i = \frac{\partial T'}{\partial p_i}$ (ii) $\frac{\partial T}{\partial q_i} + \frac{\partial T'}{\partial q_i} = 0$

(iii) T' is a homogeneous quadratic in p 's.

(iv) $T + T' = \sum p_i \dot{q}_i$.

(v) $2T' + \frac{D}{\Delta} = 0$ where $\Delta = \det(a_{ij})$ and

$$D = \begin{vmatrix} a_{11} & \dots & a_{1n} & p_1 \\ a_{21} & \dots & a_{2n} & p_2 \\ \dots & \dots & \dots & \dots \\ a_{n1} & \dots & a_{nn} & p_n \\ p_1 & \dots & p_n & 0 \end{vmatrix} \qquad 3+1+1+1+1+3$$

3. (a) Define action of a mechanical system. State and prove principle of least action.

(3)

(b) What do you mean by Legendre's dual transformation?

(c) Derive Hamilton–Jacobi partial differential equation. (1+3)+2+4

4. (a) Define canonical transformation. Show that Poisson bracket remains invariant under canonical transformation.

(b) Show that the transformation

$$Q = \sqrt{q} \cos p, P = \sqrt{q} \sin p$$

represents a canonical transformation Hence evaluate the new Hamiltonian of the system for which

$$T = \frac{1}{2} m \dot{q}^2, V = \frac{1}{2} k q^2 \qquad (1+4)+(3+2)$$

5. (a) Show that $J_1 = \int_{S_2} \sum d q_i dp_i$, is invariant under canonical transformation where S_2 is a 2D surface in phase space.

(b) Establish Euler's dynamical equations from the principle of angular momentum. 5+5

6. (a) Establish Earth's rotation using Foucault's pendulum.

(Turn over)