

Bachelor of Engineering (Mechanical), 2019 (Old)
Fourth Year - First Semester
EXPERIMENTAL METHOD IN FLUID DYNAMICS

Time : 3 hours

Full Marks: 100

Answer any 4 [four] questions

- 1a. Explain the basic functional elements of a measurement system with two suitable examples. 20
 b. What do you mean by loading effect? 5
- 2a. What are the different methods of correcting spurious inputs of a measurement system? Explain two of those with suitable examples. 6+12
 b. Write short notes on: active and passive transducer. 7
- 3a. Explain static calibration and mention the basic steps of the same. 8
 b. Distinguish between analog and digital modes of operation. 5
 c. The power transmitted by a rotating shaft is given by,

$$W = 2\pi RFL/t$$
 where,
 $R = 1202 \pm 2$ [rev] is the revolution of shaft during time, t .
 $F = 45 \pm 3\%$ [N] is the force at end of torque arm.
 $L = 0.397 \pm 1\%$ [m] is the length of the torque arm.
 $t = 60 \pm 5$ [sec] is the time length of run.
 For 95% reliability find the uncertainty in measuring W . 12
- 4a. Distinguish between modifying input and interfering input of measurement system with suitable examples. 12
 b. Write short notes on: null and deflection methods of measurement 8
 c. What do you mean by Gimbal suspension? Where is it used? 5
5. Write short notes on:
 a. Static sensitivity and linearity
 b. Resolution and Threshold
 c. Hysteresis and dead space
 d. Accuracy and Precision
 e. Primary manipulation element 5 x 5