

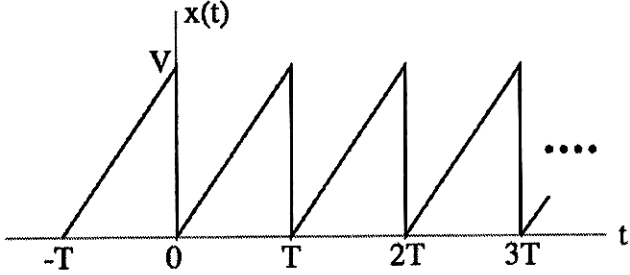
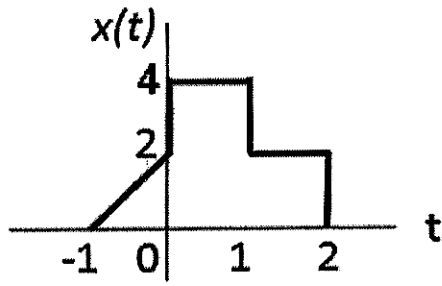
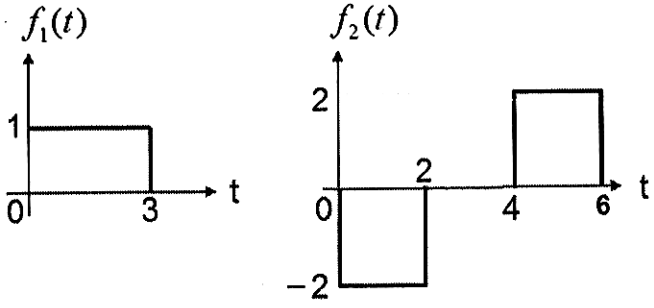
B.E. E (PART TIME) 2ND YEAR 2ND SEMESTER EXAM 2019

SUBJECT: - SIGNALS & SYSTEMS

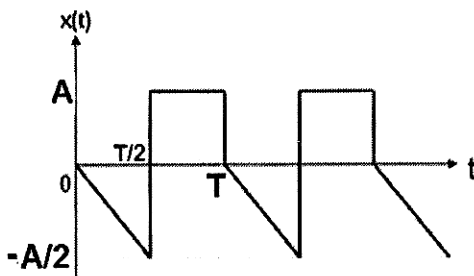
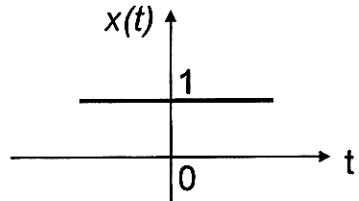
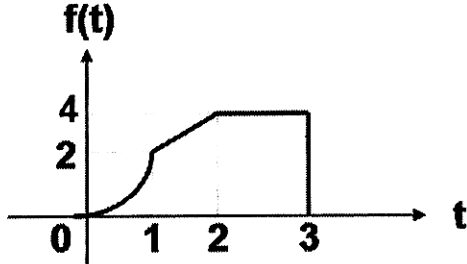
Time: Three hours

**Full Marks 100
(50 marks for each part)**

Use a separate Answer-Script for each part

No. of Questions	PART-I	Marks
Answer any 4 questions; 2 marks for well organized answers (12X4+2=50)		
1.	<p>Find Fourier coefficients, Amplitude and Phase Spectra for the following signal $x(t)$.</p> 	12
2. a)	<p>A signal $x(t)$ is shown below:</p>  <p>Find the even and odd components of $x(t)$.</p>	8
b)	<p>Prove that any signal can be resolved into even and odd components.</p>	4
3.	<p>Perform graphically the convolution between $f_1(t)$ and $f_2(t)$ as shown in the following figure.</p> 	12

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4.	Define crest factor of a time domain signal. Find the crest factor of the following signal. 	12
5. a)	State Dirichlet Conditions for a signal $x(t)$ to have a Fourier series expansion.	4
b)		8
	Find Fourier Transform of $x(t)$.	
6. a)	Check, whether the signal $x(t)$ is a power signal or an energy signal? Where, $x(t) = (\alpha^2 + t^4)^{-1/2}$ and α is a positive constant.	4
b)	A continuous time signal $x(t) = x_1(t) + x_2(t) + x_3(t)$, $x_1(t)$, $x_2(t)$ and $x_3(t)$ have time periods of 200 ms, 8s and 500 ms, respectively. Find the time period of $x(t)$.	4
c)	Prove that, output of a system is the convolution of input and the impulse response of the system itself.	4
7. a)	Express following function $f(t)$ in terms of singularity functions: 	6
b)	Derive an expression of complex form of Fourier series from trigonometric form of Fourier series.	6

BACHELOR OF ENGINEERING (ELECTRICAL ENGINEERING)

2ND YEAR 2ND SEMESTER EXAMINATION, 2019

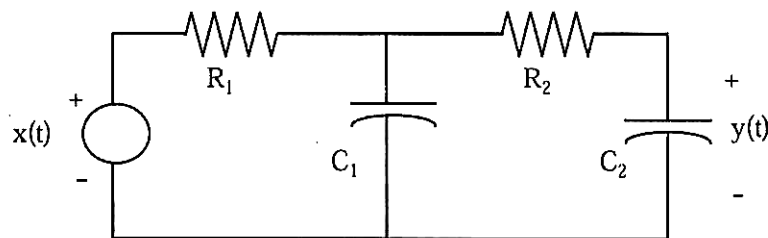
Subject: SIGNALS & SYSTEMS

Time: Three Hours

Full Marks: 100

Part II (50 marks)**Question 1** is compulsoryAnswer *Any Two* questions from the rest (2×20)

- | Question No. | Marks |
|---|-------|
| Q1 Answer <i>any Two</i> of the following: | |
| (a) Determine if the following system is (i) time-invariant, (ii) linear, (iii) causal, and/or (iv) memoryless. | 5 |
| $\dot{y}(t) + 4ty(t) = 2x(t)$ | |
| (b) Solve the following differential equation using the Laplace Transform method: | 5 |
| $\dot{y} - 2y = 2x$, with, $x(t) = u(t)$, $y(0) = -1$. | |
| (c) Determine whether the system characterized by the differential equation | 5 |
| $\ddot{y}(t) + 2\dot{y}(t) + 2y(t) = x(t)$ is stable or not? Assume zero initial conditions. | |
| (d) Determine the analog diagram to implement the following differential equation | 5 |
| $\dot{x}(t) + 0.1x(t) = 1$, $x(0) = 0$. | |
| Q2 (a) For a standard 2 nd order system find the expressions for the time-response for (i) un-damped, (ii) critically damped conditions. Show the respective pole locations. | 4+4 |
| (b) Find the transfer function, $Y(s)/X(s)$, for the circuit shown in Figure Q-2(b). Find the values of ξ and ω_n for $C_1=C_2=100\mu\text{F}$, $R_1=R_2=2000\Omega$. | |



8+4

Figure Q-2(b)

[Turn over

Ref. No.: EX/EE/5/T/221/2019

- Q3 (a) (i) Draw analog simulation diagram for the following system, and, (ii) obtain magnitude-scaled analog simulation of the system to utilize the full amplifier range of 0 to 10 volts without any overloading. 4+8

$$\ddot{x} + 2\dot{x} + 25x = 500, \quad x(0) = 20, \quad \dot{x}(0) = 0,$$

$$\text{with, } |x|_{max} = 20, \quad |\dot{x}|_{max} = 100.$$

- (b) Stating the simplifying assumptions obtain the block diagram representation of an armature controlled d. c. motor driving a load with viscous friction. Derive the corresponding transfer function assuming the angular velocity to be the output. 4+4
- Q4 (a) Define state and output equation for an LTI system. Draw the block diagram representation of the state and the output equations. 4+4
- (b) For an R-L-C series circuit driven by a constant voltage source obtain the state-space model. Assume the voltage across the capacitor to be the output. Draw the corresponding block diagram indicating the individual state variables. 8+4

- Q5 (a) Consider the mechanical system shown in Figure Q-5(a).

The external force $u(t)$ is the input to the system, and the displacement $y(t)$ of the mass is the output.

The displacement $y(t)$ is measured from the equilibrium position in the absence of the external force.

- (i) Obtain transfer function of the system.
(ii) Obtain the analogous electrical network based on *force-voltage* analogy.

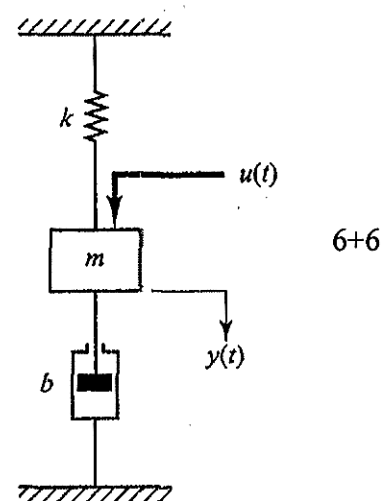


Figure Q-5(a)

- (b) Draw asymptotic Bode magnitude plot for the system with a transfer function:

$$G(s) = \frac{10(s + 2)}{s(s + 0.5)}$$