

# Digital Signal Processing

M. K. Naskar

# Simple Digital Filters

- Lowpass
- Highpass
- Bandpass
- Bandstop
- Allpass

# Pole-zero placement method

# (FIR) Lowpass Filter

FIR filter

----> All zero filter

----> We have to think in terms of zeros.

----> Poles will be at trivial position only.

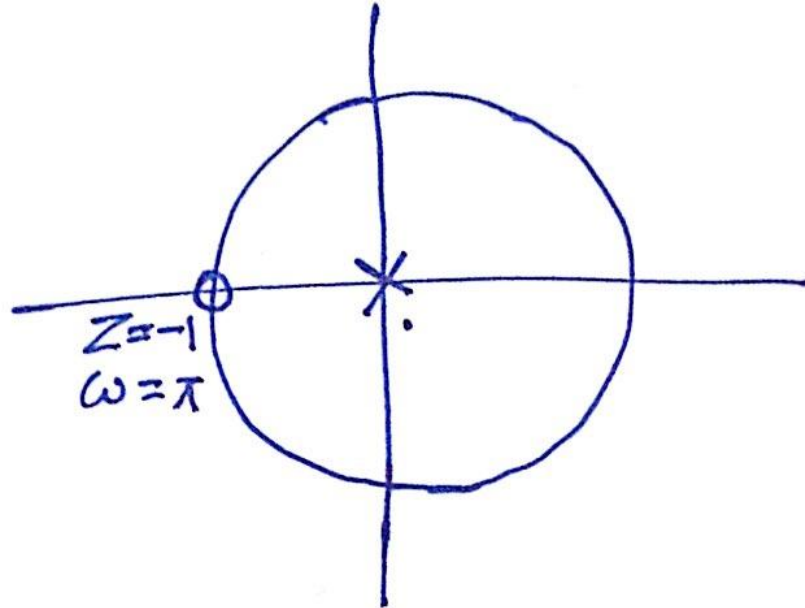
## Lowpass filter

----> Low frequencies will be passed

----> High frequencies will be attenuated

----> A zero should be placed at the highest frequency

# Lowpass FIR Filter :



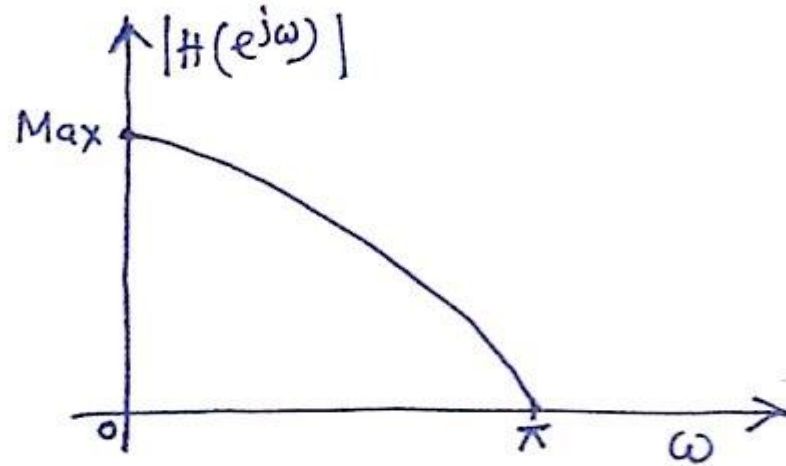
==

# (FIR) Lowpass Filter

System function:

$$H(z) = K \cdot (1 + z^{-1})$$

# Sketch of the magnitude response



## Normalization of K

$$H(z) \Big|_{z=1} = 1$$

$$\Rightarrow K \cdot (1 + 1^{-1}) = 1$$

$$\Rightarrow K \cdot 2 = 1$$

$$\Rightarrow K = \frac{1}{2}$$

# Simplest possible FIR Lowpass Filter

System function:

$$H(z) = \frac{1}{2} (1 + z^{-1}) \rightarrow 2\text{-point}$$

# Cutoff frequency

$$H(z) = \frac{1}{2} (1 + z^{-1}) \rightarrow \text{2-point moving average filter.}$$

$$\begin{aligned} \Rightarrow H(e^{j\omega}) &= \frac{1}{2} (1 + e^{-j\omega}) \\ &= \frac{1}{2} \cdot e^{-j\omega/2} (e^{j\omega/2} + e^{-j\omega/2}) \end{aligned}$$

$$= \frac{1}{2} \cdot e^{-j\omega/2} \cdot 2 \cos \omega/2$$

$$= \boxed{e^{-j\omega/2} \cos(\omega/2)}$$

$$|H(e^{j\omega})|^2 = \cos^2 \omega/2$$

$$\Rightarrow |H(e^{j\omega_c})|^2 = \cos^2(\omega_c/2) = \left(\frac{1}{\sqrt{2}}\right)^2 = \frac{1}{2}$$

$$\Rightarrow \left(\frac{1}{\sqrt{2}}\right)^2 = \cos^2 \omega_c/2$$

$$\Rightarrow \cos(\omega_c/2) = \cos \pi/4$$

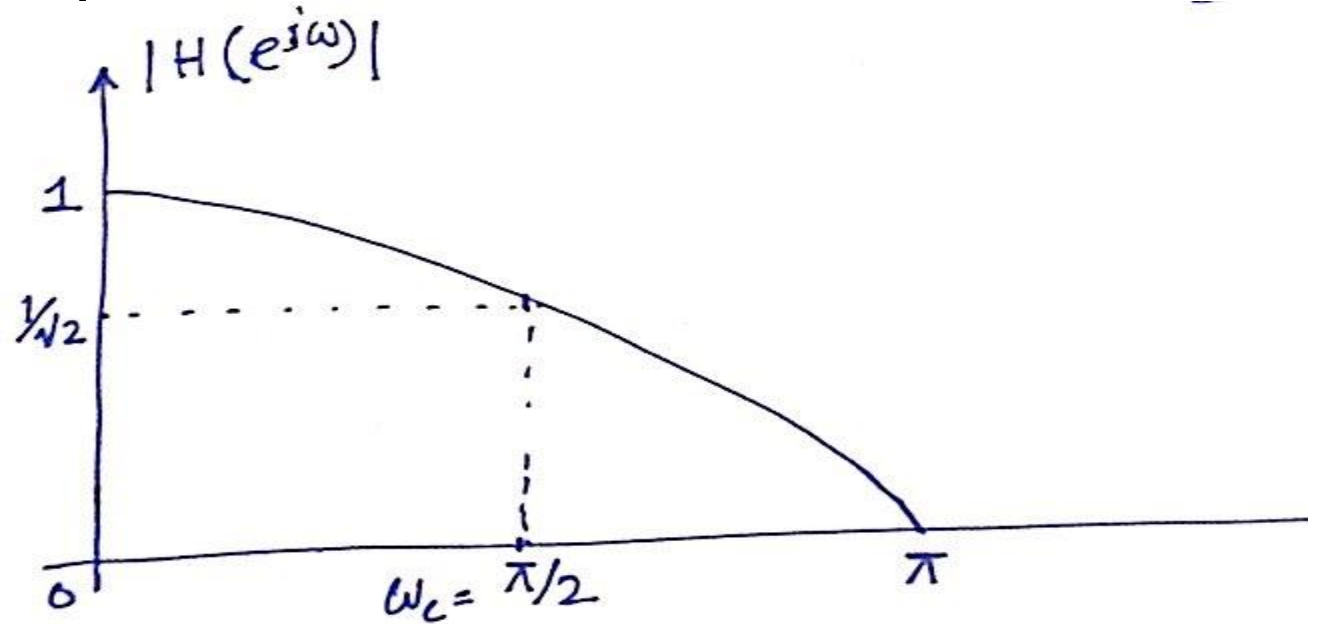
$$\Rightarrow \omega_c/2 = \pi/4$$

$$\Rightarrow \boxed{\omega_c = \pi/2}$$

$\omega_c$   
↑  
3 dB cut-off  
frequency.

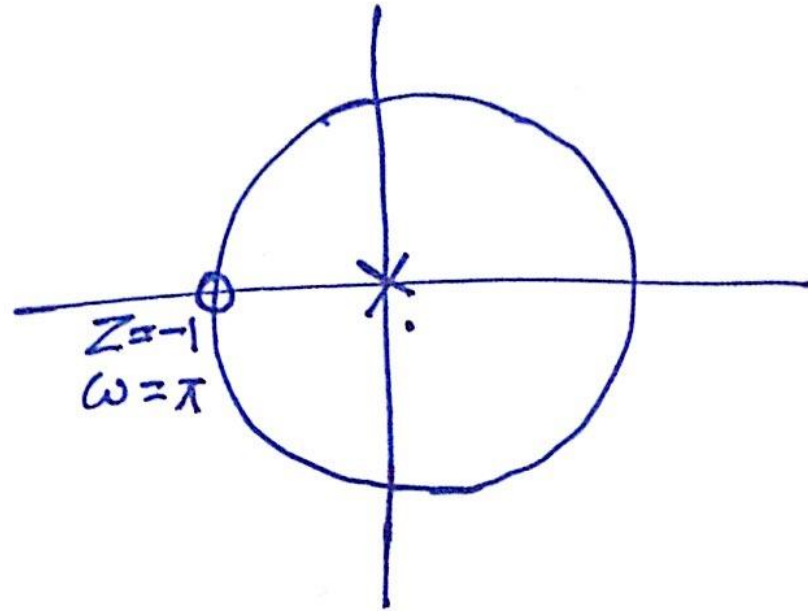
No control over the cut-off freq

# Magnitude response



Magnitude response of a two-p

# Lowpass FIR Filter :

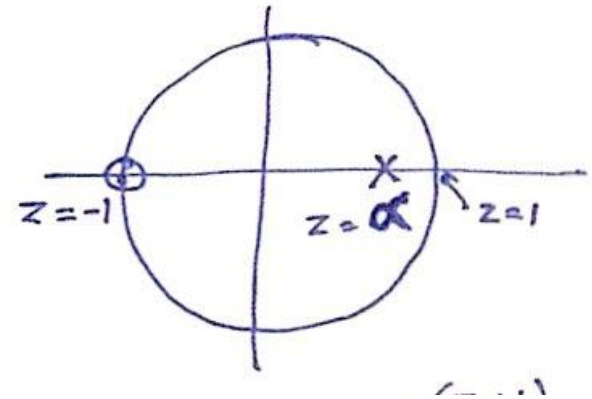


||

# (IIR) Lowpass Filter

system function:

$$H_z(z) = K \cdot \frac{1 + z^{-1}}{1 - \alpha z^{-1}}$$



# Normalization of K

---

$$H(z) = k \cdot \frac{(1+z^{-1})}{1-\alpha \cdot z^{-1}}$$

Normalization

dc gain to be 1

$$\Rightarrow H(z) \Big|_{z=1} = 1$$

$$\Rightarrow k \cdot \frac{1+1}{1-\alpha} = 1$$

$$\Rightarrow k = \left( \frac{1-\alpha}{2} \right)$$

$$\therefore H(z) = \left( \frac{1-\alpha}{2} \right) \cdot \frac{(1+z^{-1})}{(1-\alpha \cdot z^{-1})}$$

# Cutoff frequency

$$H(e^{j\omega}) = \left(\frac{1-\alpha}{2}\right) \cdot \frac{(1+e^{j\omega})}{(1-\alpha e^{j\omega})} \cdot \frac{(1+e^{-j\omega})}{(1-\alpha e^{-j\omega})}$$

$$H(e^{-j\omega}) = \left(\frac{1-\alpha}{2}\right) \cdot \frac{(1+e^{j\omega})}{(1-\alpha e^{j\omega})}$$

$$\begin{aligned} \therefore |H(e^{j\omega})|^2 &= H(e^{j\omega}) \cdot H(e^{-j\omega}) \\ &= \left(\frac{1-\alpha}{2}\right)^2 \cdot \frac{(1+e^{-j\omega})(1+e^{j\omega})}{(1-\alpha e^{-j\omega})(1-\alpha e^{j\omega})} \\ &= \left(\frac{1-\alpha}{2}\right)^2 \cdot \frac{(1+e^{j\omega}+e^{-j\omega}+1)}{(1-\alpha e^{j\omega}-\alpha e^{-j\omega}+\alpha^2)} \end{aligned}$$

$$\Rightarrow \left(\frac{1}{\sqrt{2}}\right)^2 = \left(\frac{1-\alpha}{2}\right)^2 \cdot \frac{(2+2\cos\omega_c)}{1-2\alpha\cos\omega_c+\alpha^2}$$

# Cutoff frequency

$$\Rightarrow \frac{2 + 2 \cos \omega_c}{1 - 2\alpha \cos \omega_c + \alpha^2} = \frac{2}{1 - 2\alpha + \alpha^2}$$

$$\Rightarrow \frac{1 + \cos \omega_c}{1 - 2\alpha \cos \omega_c + \alpha^2} = \frac{1}{1 - 2\alpha + \alpha^2}$$

$$\Rightarrow \cancel{1 - 2\alpha + \alpha^2} + \cos \omega_c - 2\alpha \cos \omega_c + \alpha^2 \cos \omega_c$$
$$= \cancel{1 - 2\alpha + \alpha^2} = 0$$

$$\Rightarrow (\cos \omega_c) \cdot \alpha^2 - 2\alpha + \cos \omega_c = 0 \Rightarrow \boxed{\cos \omega_c = \frac{2\alpha}{1 + \alpha^2}}$$

# Pole position

$$\Rightarrow (\cos \omega_c) \cdot \alpha^2 - 2 \cdot \alpha + \cos \omega_c = 0 \quad \Rightarrow \boxed{\cos \omega_c = \frac{2\alpha}{1+\alpha^2}}$$

$$\Rightarrow \alpha^2 - 2 \cdot \alpha \cdot \frac{1}{\cos \omega_c} + 1 = 0$$

$$\Rightarrow \alpha^2 - 2 \cdot \alpha \cdot \left(\frac{1}{\cos \omega_c}\right) + \left(\frac{1}{\cos \omega_c}\right)^2 - \left(\frac{1}{\cos \omega_c}\right)^2 + 1 = 0$$

$$\Rightarrow (\alpha - \sec \omega_c)^2 - \sec^2 \omega_c + 1 = 0$$

$$\Rightarrow (\alpha - \sec \omega_c)^2 - 1 - \tan^2 \omega_c + 1 = 0$$

$$\Rightarrow (\alpha - \sec \omega_c - \tan \omega_c)(\alpha - \sec \omega_c + \tan \omega_c) = 0$$

$$\Rightarrow \alpha - \sec \omega_c = \tan \omega_c \quad \Bigg| \quad \alpha \sec \omega_c = -\tan \omega_c = \frac{1}{\cos \omega_c} - \frac{\sin \omega_c}{\cos \omega_c} = \frac{1 - \sin \omega_c}{\cos \omega_c}$$

$$\Rightarrow \alpha = \sec \omega_c + \tan \omega_c = \frac{1}{\cos \omega_c} + \frac{\sin \omega_c}{\cos \omega_c} = \left( \frac{1 + \sin \omega_c}{\cos \omega_c} \right)$$

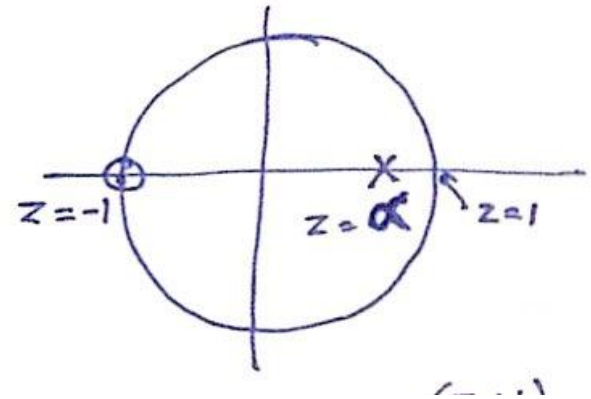
$$\boxed{\alpha = \frac{1 - \sin \omega_c}{\cos \omega_c}}$$

✓✓ Correct soln. as  $|\alpha| < 1$  for stability.

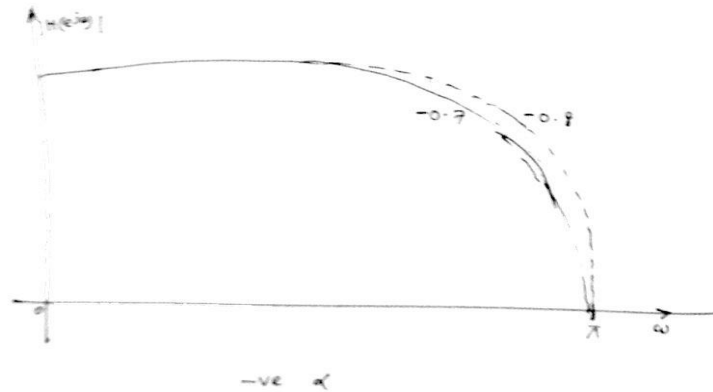
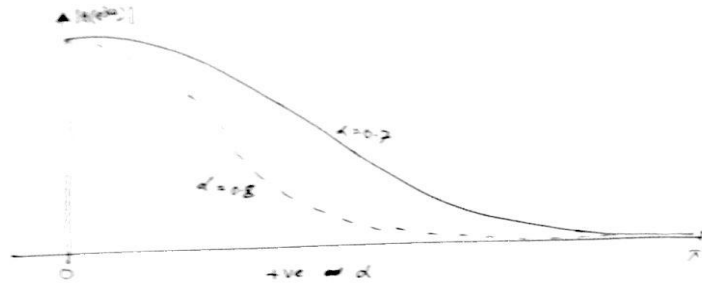
# (IIR) Lowpass Filter

system function:

$$H_z(z) = K \cdot \frac{1 + z^{-1}}{1 - \alpha z^{-1}}$$



# Magnitude response



# (FIR) Highpass Filter

FIR filter

----> All zero filter

----> We have to think in terms of zeros.

----> Poles will be at trivial position only.

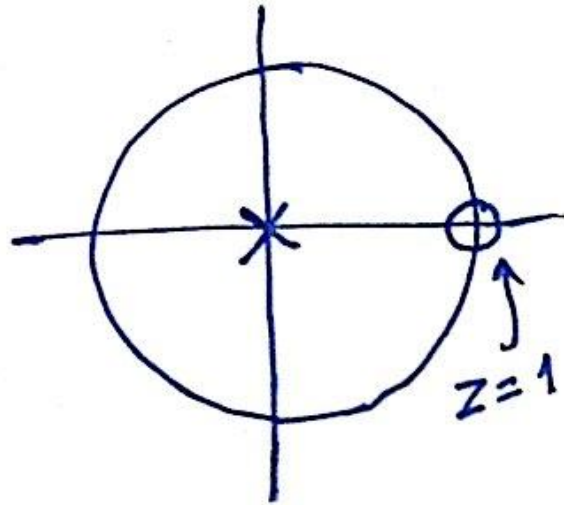
## Highpass filter

----> High frequencies will be passed

----> Low frequencies will be attenuated

----> A zero should be placed at the lowest frequency

# Highpass (FIR) Filter



•  $h$

•  $P_0$

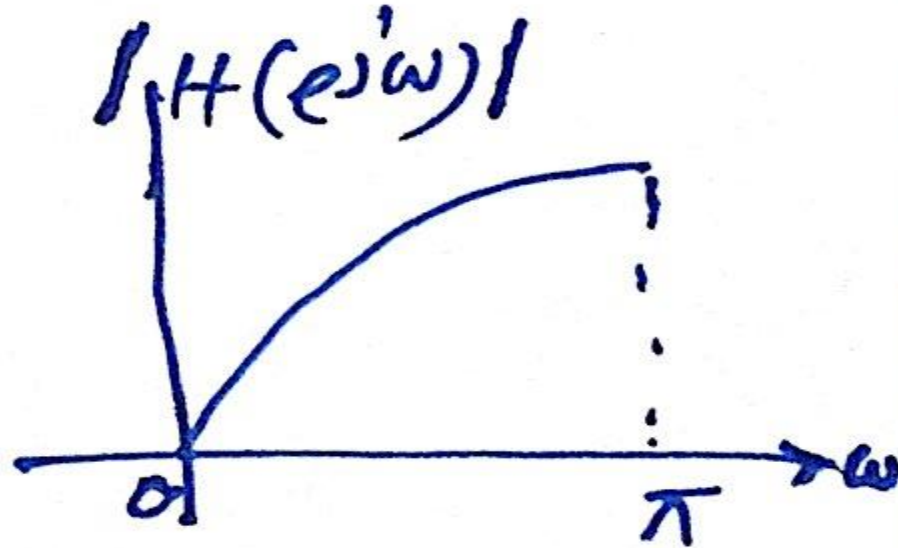
$m$

# (FIR) Highpass Filter

System function:

$$H(z) = K \cdot (1 - z^{-1})$$

# Sketch of the magnitude response



## Normalization of K

Max. value of  $H(z)$  occurs at  $\omega = \pi$  or  $z = -1$

$$H(z) \Big|_{z=-1} = k \cdot \left(1 - \frac{1}{(-1)}\right) = k \cdot 2$$

we normalize it at  $z = -1$ ,  
or,  $\omega = \pi$

$$1 = k \cdot 2$$
$$\Rightarrow k = \frac{1}{2}$$

$$\therefore H(z) = \frac{1}{2} (1 - z^{-1})$$

# Cutoff frequency

$$\begin{aligned}\therefore H(z) &= \frac{1}{2} (1 - z^{-1}) \\ H(e^{j\omega}) &= \frac{1}{2} (1 - e^{-j\omega}) \\ &= \frac{1}{2} e^{-j\omega/2} (e^{j\omega/2} - e^{-j\omega/2}) \\ &= \frac{1}{2} \cdot e^{-j\omega/2} \cdot 2j \cdot \sin(\omega/2) \\ &= j \cdot \sin(\omega/2) \cdot e^{-j\omega/2}\end{aligned}$$

$$|H(e^{j\omega_c})|^2 = \sin^2(\omega_c/2) = \left(\frac{1}{\sqrt{2}}\right)^2$$

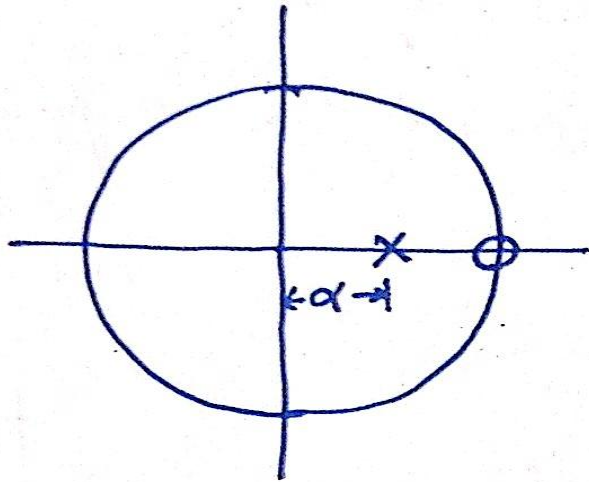
$$\Rightarrow \sin \omega_c/2 = \sin \pi/4$$

$$\Rightarrow \omega_c/2 = \pi/4$$

$$\Rightarrow \boxed{\omega_c = \pi/2}$$

No control over the cut-off frequency.

# (IIR) Highpass Filter



$$H(z) = K \frac{1 - z^{-1}}{1 - \alpha z^{-1}}$$

## Normalization of K

$$|H(z)|_{z=-1} = 1$$

$$\Rightarrow K = \left(\frac{1+\alpha}{2}\right)$$

$$\therefore H(z) = \left(\frac{1+\alpha}{2}\right) \cdot \frac{1-z^{-1}}{1-\alpha z^{-1}}$$

# Cutoff frequency

$$H(z) = \left(\frac{1+\alpha}{2}\right) \cdot \frac{(1-z^{-1})}{(1-\alpha z^{-1})}$$

$$\Rightarrow H(e^{j\omega}) = \left(\frac{1+\alpha}{2}\right) \cdot \left(\frac{1 - e^{-j\omega}}{1 - \alpha \cdot e^{-j\omega}}\right)$$

$$\Rightarrow H(e^{-j\omega}) = \left(\frac{1+\alpha}{2}\right) \cdot \left(\frac{1 - e^{j\omega}}{1 - \alpha \cdot e^{j\omega}}\right)$$

We have,  $|H(e^{j\omega})|^2 = H(e^{j\omega}) \cdot H(e^{-j\omega})$

$$= \left(\frac{1+\alpha}{2}\right)^2 \frac{(1 - e^{-j\omega})(1 + e^{j\omega})}{(1 - \alpha \cdot e^{j\omega})(1 - \alpha \cdot e^{-j\omega})}$$

At cut-off,

$$\left(\frac{1}{\sqrt{2}}\right)^2 = \left(\frac{1+\alpha}{2}\right)^2 \cdot \frac{(1 - 2 \cos \omega_c + 1)}{(1 - 2\alpha \cos \omega_c + \alpha^2)}$$

$$\Rightarrow \frac{1}{2} = \left(\frac{1+\alpha}{2}\right)^2 \cdot \frac{2(1 - \cos \omega_c)}{1 - 2\alpha \cos \omega_c + \alpha^2}$$

$$\Rightarrow 1 - 2\alpha \cdot \cos \omega_c + \alpha^2 = (1+\alpha)^2 - (1+\alpha)^2 \cdot \cos \omega_c$$

$$\Rightarrow (1+\alpha)^2 \cdot \cos \omega_c - 2\alpha \cdot \cos \omega_c = (1+\alpha)^2 - 1 - \alpha^2$$

$$\Rightarrow \cos \omega_c [1 + 2\alpha + \alpha^2 - 2\alpha] = (1 + \alpha^2 + 2\alpha - 1 - \alpha^2)$$

$$\Rightarrow \cos \omega_c \cdot (1 + \alpha^2) = 2\alpha.$$

$$\Rightarrow \boxed{\cos \omega_c = \frac{2\alpha}{1 + \alpha^2}}$$

# Pole position

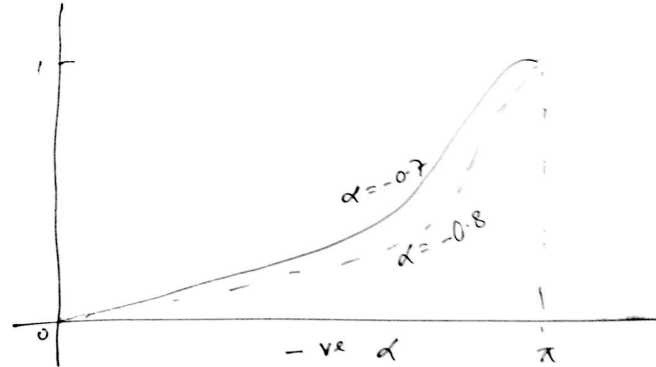
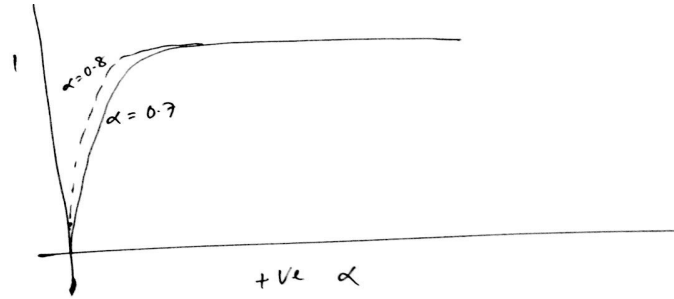
$$\begin{aligned}\cos \omega_c &= \frac{2d}{1+d^2} \\ \Rightarrow \cos \omega_c \cdot d^2 + \cos \omega_c &= 2d \\ \Rightarrow \cos \omega_c \cdot d^2 - 2d + \cos \omega_c &= 0 \\ \Rightarrow d^2 - \frac{2}{\cos \omega_c} \cdot d + 1 &= 0 \\ \Rightarrow d^2 - 2 \cdot d \cdot \frac{1}{\cos \omega_c} + \left(\frac{1}{\cos \omega_c}\right)^2 + 1 - \left(\frac{1}{\cos \omega_c}\right)^2 &= 0 \\ \Rightarrow \left(d - \frac{1}{\cos \omega_c}\right)^2 + (1 - \sec^2 \omega_c) &= 0 \\ \Rightarrow \left(d - \frac{1}{\cos \omega_c}\right)^2 - \tan^2 \omega_c &= 0 \\ \Rightarrow \left(d - \frac{1}{\cos \omega_c}\right)^2 - \left(\frac{\sin \omega_c}{\cos \omega_c}\right)^2 &= 0 \\ \Rightarrow \left(d - \frac{1}{\cos \omega_c} + \frac{\sin \omega_c}{\cos \omega_c}\right) \left(d - \frac{1}{\cos \omega_c} - \frac{\sin \omega_c}{\cos \omega_c}\right) &= 0\end{aligned}$$

$$\begin{aligned}\text{So, } d &= \frac{1}{\cos \omega_c} - \frac{\sin \omega_c}{\cos \omega_c} \quad \text{or, } d = \frac{1}{\cos \omega_c} + \frac{\sin \omega_c}{\cos \omega_c} \\ &= \frac{1 - \sin \omega_c}{\cos \omega_c} & & = \frac{1 + \sin \omega_c}{\cos \omega_c}\end{aligned}$$

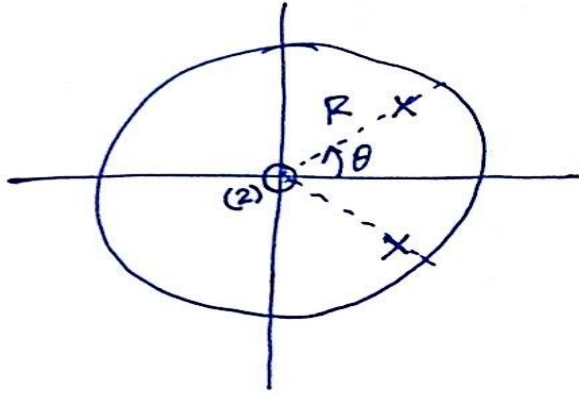
For stability,  $|d| < 1$

Hence,  $d = \frac{1 - \sin \omega_c}{\cos \omega_c}$

# Magnitude response

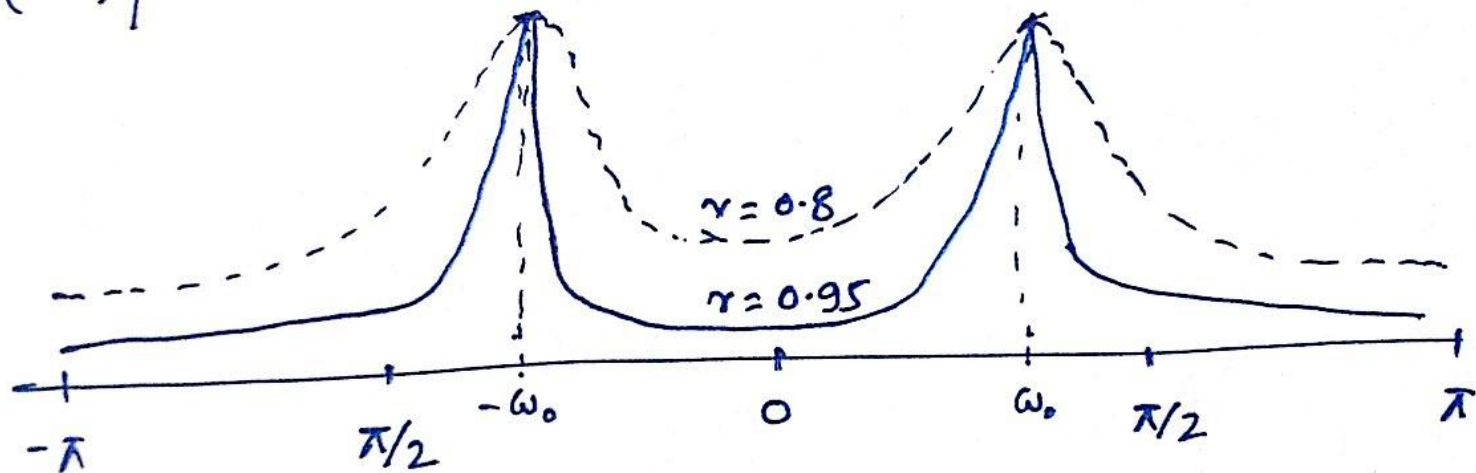


# Resonators (Resons)



$$H(z) = K \cdot \frac{1}{(1 - R e^{j\theta} z^{-1})(1 - R e^{-j\theta} z^{-1})}$$
$$= K \cdot \frac{1}{1 - (2R \cos \theta) z^{-1} + R^2 z^{-2}}$$

$|H(e^{j\omega})|$



Design Steps :

(a) Choose the bandwidth  $B$  and the resonant frequency  $\omega_0$ .

(b) Calculate the pole radius  $R$  from the bandwidth  $B$ .

$$R = 1 - B/2$$

(c) Calculate the cosine of the pole angle  $\theta$ .

$$\cos \theta = \frac{2R}{1+R^2} \cdot \cos \omega_0$$

$$\text{if } R \approx 1, \quad \cos \theta \approx \cos \omega_0 \Rightarrow \theta \approx \omega_0$$

(d) Calculate the gain factor  $K$ ,

$$K = (1 - R^2) \sin \theta \quad \text{so that, } \left. |H(e^{j\omega})| \right|_{\omega=\omega_0} = 1$$

(e) The system function of the filter is

$$H(z) = K \times \frac{1}{(1 - Re^{j\theta} \cdot z^{-1})(1 - Re^{-j\theta} \cdot z^{-1})}$$

$$\begin{aligned}
 |H(e^{j\omega})|^2 &= \frac{H(e^{j\omega}) \cdot H(e^{-j\omega})}{K^2} \\
 &= \frac{1}{[2R \cos \omega - (R^2+1) \cos \theta]^2 + (1-R^2)^2 \sin^2 \theta}
 \end{aligned}$$

Maximum value of  $|H(e^{j\omega})|$  is reached when the first term in the denominator vanishes, i.e. at  $\omega = \omega_0$ , where

$$2R \cos \omega_0 - (R^2+1) \cos \theta = 0$$

$$\Rightarrow \cos \omega_0 = \left( \frac{R^2+1}{2R} \right) \cos \theta$$

$$\Rightarrow \boxed{\cos \theta = \left( \frac{2R}{1+R^2} \right) \cos \omega_0}$$

$$|H(e^{j\omega})|_{\max}^2 = \frac{K^2}{(1-R^2)^2 \sin^2 \theta}$$

For normalization,

$$\boxed{K = (1-R^2) \sin \theta}$$

Bandpass filter :

$$\gamma = 1 - \left(\frac{BW}{F_s}\right) \times \pi$$

$$\Delta\omega = 2(1-\gamma) \quad , \quad \Delta\omega \propto (1-\gamma)$$

$$\Rightarrow \frac{BW}{2F_s} \neq$$

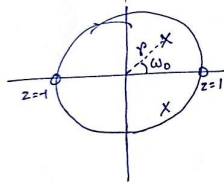
$$\Rightarrow 2\pi \left(\frac{BW}{F_s}\right) = 2(1-\gamma)$$

$$\Rightarrow \boxed{\gamma \approx 1 - \left(\frac{BW}{F_s}\right) \times \pi}$$

magnitude  
of the poles

$$\rightarrow \omega_0 = 2\pi \left(\frac{f_0}{F_s}\right) \quad , \quad f_0 \text{ is the center frequency.}$$

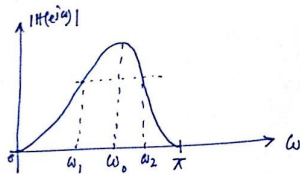
angle  
of the poles



Given :

- i) Center freq<sup>n</sup>  $f_0$  Hz
- ii) 3-dB BW in Hz

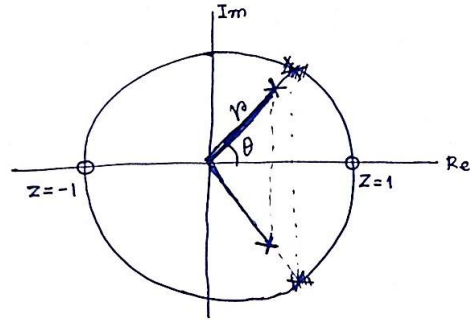
$$H(z) = K \cdot \frac{(z+1)(z-1)}{(z - \gamma e^{j\omega_0})(z - \gamma e^{-j\omega_0})} = \frac{K(z^2-1)}{z^2 - 2\gamma \cos\omega_0 \cdot z + \gamma^2}$$



$$\Delta\omega = \omega_2 - \omega_1$$

$$K = \frac{(1-\gamma)\sqrt{1-2\gamma\cos 2\omega_0 + \gamma^2}}{2|\sin\omega_0|}$$

## Bandpass Filter



Pole-zero diagram

System function:

$$\begin{aligned} H(z) &= K \cdot \frac{(1 - z^{-1})(1 + z^{-1})}{(1 - r e^{j\theta} z^{-1})(1 - r e^{-j\theta} z^{-1})} \\ &= K \cdot \frac{(1 - z^{-2})}{1 - 2r \cos\theta \cdot z^{-1} + r^2 z^{-2}} \end{aligned}$$

where,  $K$  is the gain constant

## Normalization

$K$  will be chosen to normalize the maximum magnitude to unity.

The frequency response is given by

$$H(e^{j\omega}) = K \cdot \frac{(1 - e^{-2j\omega})}{1 - 2r \cos\theta \cdot e^{-j\omega} + r^2 e^{-2j\omega}}$$

$$H(e^{-j\omega}) = K \cdot \frac{(1 - e^{2j\omega})}{1 - 2r \cos\theta \cdot e^{j\omega} + r^2 e^{2j\omega}}$$

$$\begin{aligned} \therefore |H(e^{j\omega})|^2 &= H(e^{j\omega}) \cdot H(e^{-j\omega}) \\ &= \frac{4K^2}{\left[ \frac{(1+r^2)\cos\omega - 2r\cos\theta}{\sin\omega} \right]^2 + (1-r^2)^2} \end{aligned}$$

Maximum value of  $|H(e^{j\omega})|$  is reached when the first term in the denominator vanishes, i.e. at  $\omega = \omega_0$ , where

$$\cos\omega_0 = \left( \frac{2r\cos\theta}{1+r^2} \right) = \beta \quad (\text{let})$$

$$\text{So, } |H(e^{j\omega})|_{\max}^2 = \frac{4K^2}{(1-r^2)^2}$$

$$\Rightarrow |H(e^{j\omega})|_{\max} = \frac{2K}{(1-r^2)} = 1 \quad (\text{normalized value})$$

$$\Rightarrow K = (1-r^2)/2$$

$$\frac{\text{Cutoff frequencies}}{\text{Putting, } K = \frac{1-r^2}{2}}$$

$$|H(e^{j\omega})|^2 = \frac{1}{1 + \left[ \frac{(1+r^2)\cos\omega - 2r\cos\theta}{(1-r^2)\sin\omega} \right]^2}$$

$$\text{At cutoff frequencies, } |H(e^{j\omega})|^2 = \left(\frac{1}{\sqrt{2}}\right)^2 = \frac{1}{2}$$

$$\text{So, } (1+r^2)\cos\omega - 2r\cos\theta = \pm(1-r^2)\sin\omega$$

$$\text{or, } (1+r^2)\cos\omega_1 - 2r\cos\theta = (1-r^2)\sin\omega_1 \quad \text{---(i)}$$

$$\text{and } (1+r^2)\cos\omega_2 - 2r\cos\theta = -(1-r^2)\sin\omega_2 \quad \text{---(ii)}$$

Subtracting (ii) from (i) gives

$$(1+r^2)(\cos\omega_1 - \cos\omega_2) = (1-r^2)(\sin\omega_1 + \sin\omega_2)$$

$$\Rightarrow (1+r^2) \sin\frac{\omega_2+\omega_1}{2} \sin\frac{\omega_2-\omega_1}{2} = (1-r^2) \sin\frac{\omega_2+\omega_1}{2} \cos\frac{\omega_2-\omega_1}{2}$$

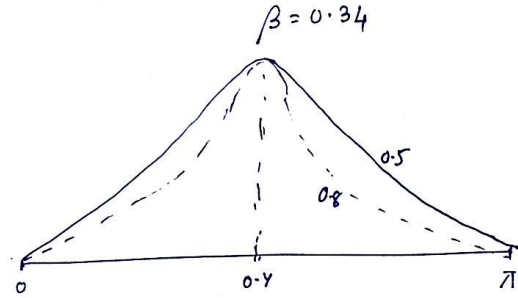
$$\Rightarrow \tan\left(\frac{\omega_2-\omega_1}{2}\right) = \frac{1-r^2}{1+r^2}$$

$$\Rightarrow \cos(\omega_2-\omega_1) = \frac{(1+r^2)^2 - (1-r^2)^2}{(1+r^2)^2 + (1-r^2)^2}$$

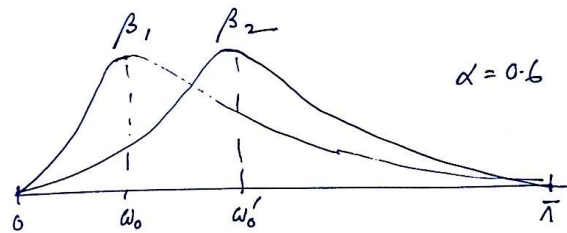
$$\Rightarrow \cos\theta = \frac{2r^2}{1+r^4} = \frac{2\alpha}{1+\alpha^2} \quad \begin{array}{l} \text{Let } \alpha = \frac{r}{d} \\ \text{Let } r = \alpha \end{array}$$

$$\Rightarrow K = \left(\frac{1-\alpha}{2}\right)$$

$$\text{So, } H(z) = \left(\frac{1-\alpha}{2}\right) \cdot \frac{1 - z^{-2}}{1 - \beta(1+\alpha)z^{-1} + \alpha z^{-2}}$$

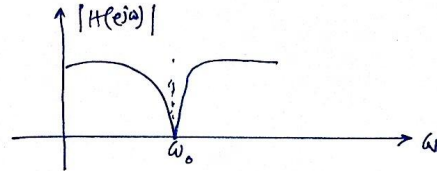
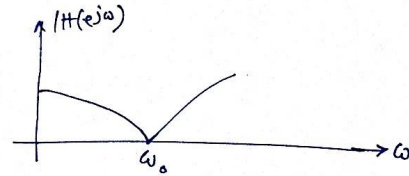
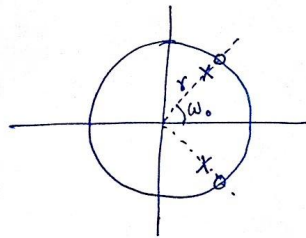


Fixed  $\beta \Rightarrow$  fixed centre freq.  $\omega_0$   
 $\alpha$  is varied  $\Rightarrow$   $B$  is varied  $\alpha \uparrow \rightarrow B \downarrow$



$\beta$  is varied  $\Rightarrow$  centre freq. is varied  
 $\alpha$  is fixed  $\Rightarrow$   $B$  is fixed.

# Bandstop (Notch) Filter



$$H(z) = K \cdot \frac{(z - e^{j\omega_0})(z - e^{-j\omega_0})}{(z - \gamma e^{j\omega_0})(z - \gamma e^{-j\omega_0})} = \frac{K(z^2 - 2\cos\omega_0 z + 1)}{(z^2 - 2\gamma \cos\omega_0 z + \gamma^2)}$$

$$K = \frac{(1 - 2\gamma \cos\omega_0 + \gamma^2)}{2 - 2\cos\omega_0}, \quad \text{Normalization } H(z)|_{z=1} = 1$$

$$\gamma \approx 1 - (BW/F_s) \times \pi, \quad 0.9 \leq \gamma \leq 1$$

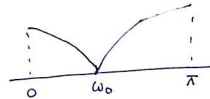
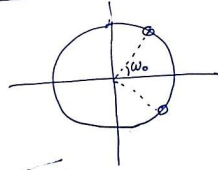
$$\omega_0 = 2\pi (F_0/F_s)$$

Center freq<sup>n</sup>:  $F_0$

3-dB bandwidth  $BW$

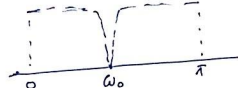
# Bandstop Filter

(IIR Notch)



3 dB BW is very large

$$1 - 2 \cos \omega_0 \cdot z^{-1} + z^{-2}$$



We want to exchange the response near  $\omega_0$ . So we introduce two more poles at the same freqn.

$$H(z) = K \cdot \frac{(1 - 2\beta z^{-1} + z^{-2})}{1 - \beta(1+\alpha)z^{-1} + \alpha z^{-2}}$$

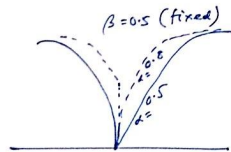
$|\alpha| < 1$  } stability.  
 $|\beta| < 1$  }

where,  $\beta = \cos \omega_0$ ,  $\omega_0$  is the notch freqn.

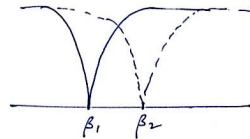
Max. value at  $\omega = 0, \pi$ ,  $\frac{2K}{1+\alpha} = 1 \Rightarrow K = \left(\frac{1+\alpha}{2}\right)$ .

$$H(z) = \left(\frac{1+\alpha}{2}\right) \cdot \frac{1 - 2\beta z^{-1} + z^{-2}}{1 - \beta(1+\alpha)z^{-1} + \alpha z^{-2}}$$

$$B = \cos^{-1}\left(\frac{2\alpha}{1+\alpha^2}\right)$$



$\alpha$  changes the bandwidth



$\alpha$  is fixed  $\Rightarrow B$  is fixed.

## All-pass Filter

An all-pass filter is defined as a system that has a constant magnitude response for all frequencies, that is,

$$|H(e^{j\omega})| = 1, \quad 0 \leq \omega \leq \pi$$

- The simplest example of an all-pass filter is a pure delay (system) of  $k$  samples. This is a trivial all-pass system that has a linear phase characteristic.

$$\boxed{y(n) = x(n-k)}$$

$$\Rightarrow Y(z) = z^{-k} X(z)$$

$$\Rightarrow \boxed{H(z) = \frac{Y(z)}{X(z)} = z^{-k}}$$

$$\Rightarrow H(e^{j\omega}) = e^{-j\omega k}$$

$$|H(e^{j\omega})| = 1, \quad \angle H(e^{j\omega}) = -\omega k$$

• A more interesting all-pass filter is described by the system function

$$H(z) = \frac{a_N + a_{N-1}z^{-1} + \dots + a_1z^{-N+1} + z^{-N}}{1 + a_1z^{-1} + a_2z^{-2} + \dots + a_Nz^{-N}}$$

where all the filter coefficients  $\{a_k\}$  are real.

$$H(z) = z^{-N} \cdot \frac{A(z^{-1})}{A(z)}$$

where  $A(z) = 1 + \sum_{k=0}^N a_k \cdot z^{-k}$  ,  ~~$a_0 = 1$~~

Since,  $|H(e^{j\omega})|^2 = H(z)H(z^{-1})|_{z=e^{j\omega}} = 1$

the system is an all-pass system.

$$A(z) = 1 + \sum_{k=1}^N a_k \cdot z^{-k}$$

$$A(z^{-1}) = 1 + \sum_{k=1}^N a_k \cdot z^k$$

$$\begin{aligned} z^{-N} A(z^{-1}) &= z^{-N} + \sum_{k=1}^N a_k \cdot z^k \cdot z^{-N} \\ &= z^{-N} + \sum_{k=1}^N a_k \cdot z^{-N+k} \end{aligned}$$

= / v -

$$H(z) = \frac{a_N + a_{N-1}z^{-1} + \dots + a_1z^{-N+1} + z^{-N}}{1 + a_1z^{-1} + \dots + a_Nz^{-N}}$$

$$= \frac{z^{-N} + \sum_{k=1}^N a_k \cdot z^{-N+k}}{1 + \sum_{k=1}^N a_k \cdot z^{-k}} = z^{-N} \cdot \frac{A(z^{-1})}{A(z)}$$

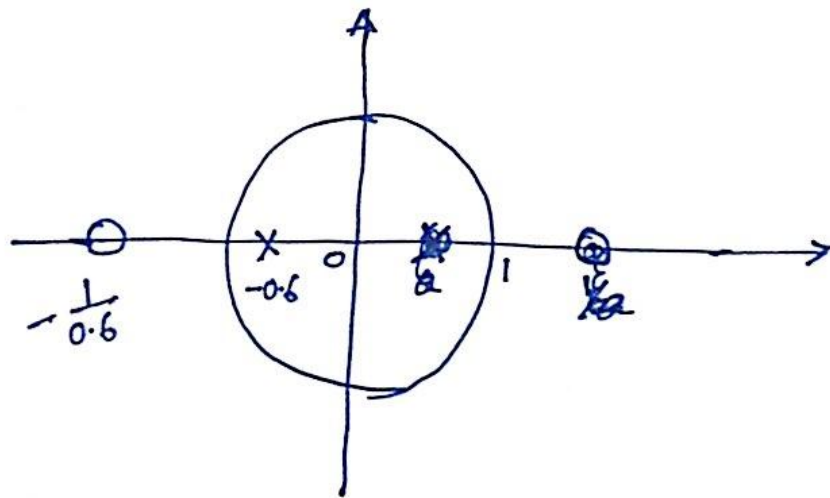
where,  $A(z) = 1 + \sum_{k=1}^N a_k \cdot z^{-k}$

- Furthermore, if  $z_0$  is a pole of  $H(z)$ , then  $1/z_0$  is a zero of  $H(z)$  (i.e. poles and zeros are reciprocals of one another).

$$\begin{aligned}
 |H(e^{j\omega})|^2 &= H(e^{j\omega}) \cdot H^*(e^{j\omega}) = H(e^{j\omega}) H(e^{-j\omega}) = H(z) H(z^{-1}) \Big|_{z=e^{j\omega}} \\
 &= e^{-j\omega N} \cdot \frac{A(e^{-j\omega})}{A(e^{j\omega})} \cdot e^{j\omega N} \cdot \frac{A(e^{j\omega})}{A(e^{-j\omega})} = 1
 \end{aligned}$$

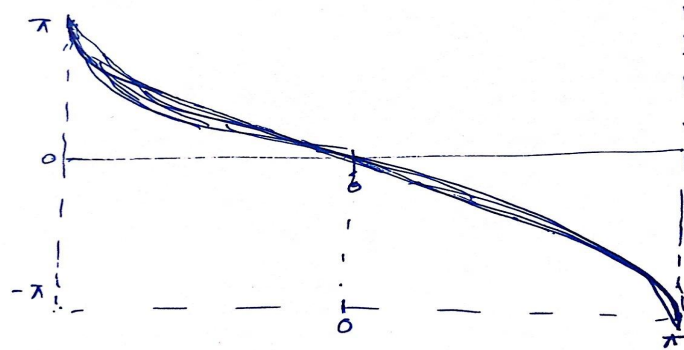
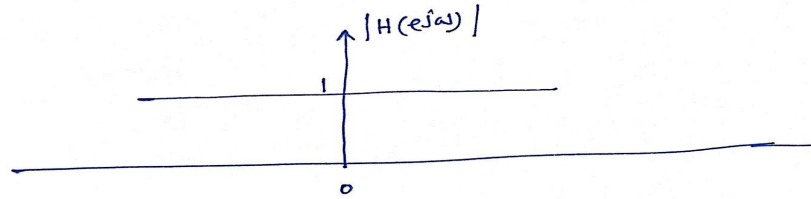
- All pass filters find applications as phase equalizers.  
When placed in cascade with a system that has an undesired phase response, a phase equalizer is designed to compensate for the poor phase characteristics of the system and therefore to produce an overall linear phase response.

- A first-order  
• (Single-pole single-zero) all-pass filter

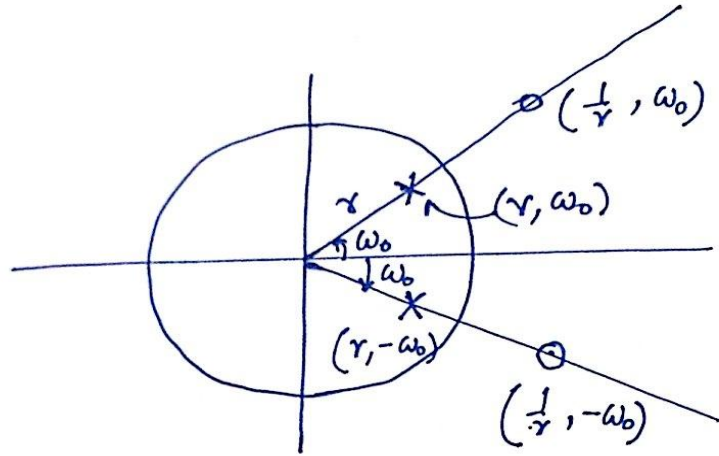


$$H(z) = \frac{0.6 + z^{-1}}{1 + 0.6 z^{-1}} = \frac{0.6}{-}$$

# Magnitude and phase response



- A second order  
 • (A two-pole, two-zero) all-pass filter:



$$H(z) = \frac{r^2 - 2r \cos \omega_0 z^{-1} + z^{-2}}{1 - 2r \cos \omega_0 z^{-1} + r^2 z^{-2}}$$

# Magnitude and phase response

$$\gamma = 0.9, \quad \omega_0 = \pi/4$$

